# PRELIMINARY EXPERIMENTAL STUDY OF SEISMIC UPLIFT OF A STEEL FRAME 

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Report to National Science Foundation,
American Iron and Steel Institute



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EARTHQUAKE SIMULATION TESTS OF A THREE STORY STEEL FRAME WITH COLUMNS ALLOWED TO UPLIFT
by
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## ABSTRACT

This study represents the preliminary portion of a research program into the effects of allowing column uplift in steel building frames responding to severe seismic loading. Included in this report are experimental and analtyical results for a 3-story steel frame both with and without column uplift allowed. Uplift response results are presented for tests using 2 sets of impact elements with stiffnesses differing by approximately an order of magnitude.

Allowing column uplift is shown for this frame to significantly reduce both the seismic loading and ductility demand, when compared to the fixed base response for a similar input motion. An analytical technique employing bilinear elastic foundation support elements, with no tensile capacity or stiffness in the upward direction, is shown to accurately predict the uplift response of this frame, even in the presence of large rigid body rotations. An analytical technique using concentrated bilinear plastic hinges is shown to accurately predict the nonlinear fixed base response, for moderately nonlinear response.

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## 1. INTRODUCTION

### 1.1 The Overturning Effect in Seismic Response

The overturning moment at the base of a structure resulting from the lateral inertial forces which occur during a major earthquake can easily exceed the overturning resistance provided by the dead weight of the system alone. Assuming that no supplementary anchorage is provided, this condition implies a transient separation of portions of the structure from its foundation, resulting in a highly nonlinear response.

The usual linear dynamic or equivalent static analysis techniques are not capable of treating this type of nonlinear behavior. The stiffness changes associated with separation or impacting of structure and foundation are very drastic and instantaneous in nature, requiring a more sophisticated nonlinear analysis.

The traditional building code solution to this problem has been to avoid it by specifying lateral loading conditions low enough so that overturning complications are not encountered in most designs. The lower design loading conditions have been reasonably justified by requiring adequate detailing for local ductile behavior in overload situations.

No rational provision has been incorporated, however, to consider an overturning overload. Building codes generally require full overturning resisting capacity for whatever overturning moment is computed, even if this requires supplementary anchorage.

Primarily as a result of the structural failures during the 1971 San Fernando earthquake there has been a trend toward more conservative seismic design loading conditions, particularly for hospitals and other essential facilities. This trend now is leading to the necessity for a rational consideration of the overturning effect; to require full
overturning constraint for a strong earthquake would seem to be both uneconomical and unnecessary. A rational consideration of overturning response to severe ground shaking, however, requires a full understanding of that response, including the nonlinear uplift phenomenon.

Analytical studies by Beck and Skinner (1) and by Meek (4) indicate the potential economies of allowing transient uplift of structures in response to strong ground shaking. Indications are that the uplift phenomenon provides a type of structural fuse, limiting the applied overturning forces to those which first produce uplift. This limiting effect can thus lead to reduced internal forces and/or ductility demand on the system, making possible a more rational and more economical design for a realistic seismic loading condition.

Before a general incorporation of uplift capability as a design feature is undertaken, however, the basic uplift response mechanism must be thoroughly investigated, including experimental verification of analytical studies. Once verified, adequate analytical consideration should then lead to a more effective design application, with greater confidence in the intended performance.

### 1.2 Scope and Objectives of this Study

The primary objective of this study was to investigate the seismically induced overturning effect in a simple structural system, both with and without indicated supplementary anchorage provided. The investigation was to be both experimental and analytical in nature, with the experimental data providing a basis for evaluating currently available nonlinear analytical techniques. It was felt that a simple, well-understood superstructure system would facilitate the study of the basic uplift phenomenon, the response feature of greatest interest in this study.

In scope the study has included the conduct of a series of shaking table tests of an experimental structure in the U.C. Berkeley Earthquake Simulator Laboratory. These test results, both with and without uplift allowed, were then compared directly to response predictions by a nonlinear dynamic analysis program, utilizing the experimentally measured excitation as input. The degree of correlation between analytical and experimental results for the same excitation then provided the means of evaluating the analyses.

## 2. EXPERIMENTAL PROGRAM

### 2.1 The Test Facility

The U.C. Berkeley Earthquake Simulator, shown in Fig. 2.1.1, is described fully by Rea and Penzien (6). Briefly, the facility consists of a $20^{\prime} \times 20^{\prime}$ post-tensioned concrete slab shaking table with its associated control and data acquisition equipment. The shaking table can move independently in the vertical and one horizontal direction. The command displacement signals for the two degrees of freedom are supplied and test data are recorded through a Nova mini-computer system. Up to 128 channels of data can be sampled discretely, usually at a rate around 50 samples/sec/channel. The data, converted immediately to digital form, are transferred to magnetic tape for detailed reduction on the Berkeley CDC 6400 computer system.

The range of possible input signals to the shaking table is completely general within the limiting ranges of displacement, velocity and acceleration shown in Fig. 2.1.2. In addition to these limits, the maximum design payload is about $100^{\mathrm{k}}$ and the design overturning moment capacity is about 1700 kip-ft.

### 2.2 The Test Model

As mentioned in the introduction, it was decided to utilize a relatively simple superstructure system for the initial investigation of the uplift phenomenon. An existing three-story, single-bay steel moment frame, described fully by clough and Tang (2), was available for this purpose. This frame had been utilized in the initial experimental and analytical test program conducted on the then newly constructed shaking table, reported by Tang (7).

The existing structure had been fabricated from rolled A36 wide flange sections; the columns were $W 5 \mathrm{x} 16$ and the girders were $W 6 \mathrm{x} 12$. Concrete
weights totaling $24^{k}$ were distributed equally on the 3 floors; each floor had sufficient in-plane bracing to provide a rigid diaphram behavior. The bay width was $12^{\prime}-0^{\prime \prime}$; the floor heights were $6^{\prime}-8^{\prime \prime}, 5^{\prime}-4^{\prime \prime}$, and $5^{\prime}-4^{\prime \prime}$.

It was decided for reasons of economy to adapt this existing structure to the uplift test program. As it was considered desirable to achieve a relatively high amplitude of uplift response, the column bases were pinned to allow rigid body rotation immediately upon separation of the column base and foundation. Braces to the lst floor were introduced to restore stiffness lost through this modification; these also provided a local critical section for study at each column midheight, as shown in Fig. 2.2.1.

The uplift mechanism designed to accommodate the anticipated high amplitude uplift response is shown in Fig. 2.2.2. The vertical roller bearings provided a "shear key" for each column, essential to prevent the structure from "walking" off the foundation, yet with only negligible resistance to uplift motion.

Neoprene impact pads of two different stiffnesses were provided beneath the column bases during uplift testing. For phase I testing, relatively soft pads with an effective stiffness of approximately $44 \mathrm{ki} / \mathrm{in}$ were employed. For phase II testing, pads of approximately an order of magnitude greater stiffness were fabricated. As mentioned previously. provision was made to restrain the uplift motion for comparative purposes. This was accomplished by removing the impact pads and bolting the pin mechanism securely to the foundation. The pinned nature of the column base was thus retained while the relative vertical motion was prevented.

### 2.3. Instrumentation

For the phase I uplift tests a total of 124 data channels were monitored, 36 of which were devoted to various table functions. For phase II uplift tests an additional 4 channels were monitored. These
additional channels were devoted to extra strain readings near the critical section of a first floor column. The instrumentation served to define the table and individual horizontal story accelerations and displacements, the member force distributions, the local member inelastic deformations and the column base relative vertical displacements during each test. Complete channel listings and descriptions are given for all tests in Appendix A.

Data sign conventions are shown in Figs. 2.3.1 and 2.3.2. All data channels were sampled at a rate of approximately 50 points per second during these tests.

Transducer types utilized for these tests consisted of accelerometers, linear potentiometers, linear DC displacement transducers, strain gages and on-off contact switches between the column bases and their respective impact elements. Descriptions of these transducers are given briefly in the following paragraphs.

The accelerometer type used was the Kistler model 305 T non-pendulous, force balance servo accelerometer, with a Kistler model 515T servo amplifier attached. The amplifiers were set to give a data range of $\pm 5 \mathrm{~g}^{\prime} \mathrm{s}$.

Two different models of linear potentiometers were used in testing. To measure the absolute horizontal story displacements, Houston Scientific Inc. model 1800-30A potentiometers were used. This model has a travel range of $\pm 15$ in. Houston Scientific model 1800-15A potentiometers were used to measure the relative column base vertical displacements. This model has a travel range of $\pm 7.5$ in.

Sanborn model 7DCDT-500 displacement transducers with a stroke of $\pm .5$ in. were used in opposing pairs to measure local member average curvatures. For this purpose the transducers were mounted in aluminum frames setat distances of 4 and 6 in. from corresponding target frames.

Typical setups of these devices are shown in Fig. 2.3.3.
Two types of resistance strain gages were utilized in the tests. For strains in elastic regions, foil gages were utilized to derive resultant force quantities. These were manufactured by Micro-Measurements, model EA-06-250BG-120, options $L$ and W. For strains in the plastic regions, post yield gages of types Yt-10 and YL-20 by Tokyo Sokki Kenkyujo Co. were utilized to estimate ductility demands. The latter gages employ a nickel-copper alloy wire, reportedly accurate to strains of $20 \%$.

In addition to the above mentioned instruments, mechanical strain gages manufactured by Prewitt Associates were colocated with standard resistance strain gages at several critical sections. These "scratch strain gages" are self-driven and produce a trace on a polished brass target, which is interpreted with a l00x microscope. One of these gages is shown in Fig. 2.3.4.

### 2.4 Input Signals

As previously mentioned, the family of possible input signals to the shaking table is practically limitless, making necessary a decision as to appropriate signals. For this test series, it was decided to use signals derived from actual strong-motion accelerograms. The two basic signals chosen were the 1940 El Centro N-S and the 1971 Pacoima Dam S74W records. Each signal was run at a wide range of intensities, and the El Centro record was used both with and without the corresponding vertical component of motion. Because the table is displacement controlled, the table motion acclerograms are not exact duplicates of the field-recorded accelerograms, but they do represent well the intensity and frequency content of typical ground motions. The acceleration time histories in the horizontal direction, along with the displacement records and response spectra of all the different test intensitites and motions discussed in this report, are
presented in Figs. 2.4.2 through 2.4.11. The El Centro earthquake motions are designated EC and the Pacoima earthquake inputs are labeled PAC. The number following these designations is the "span" setting for the test: a control system setting indicating the "intensity" of the test, and linearly proportional to the table displacement. Roman numerals $I$ and II identify the two different stiffnesses of rubber impact cushions used in test phases I and II. Where no Roman numeral is shown, the structure was fully constrained against uplift.

The response spectra for each test were obtained using a program developed by Nigam and Jennings (5). The spectral ordinates were computed at the following period intervals:
.10 sec . to .30 sec . @ intervals of .025 sec .
.30 sec . to 1.0 sec . @ intervals of .050 sec .
1.0 sec . to 3.0 sec . @ intervals of .250 sec .
3.0 sec . to 5.0 sec . @ intervals of .500 sec .

The response ordinates were computed using the accelerations as digitized during each test.

Because this test series was not intended as a model test of any prototype structure, no time scaling of the input was performed. Use of normal time scale would tend to exaggerate the amplitude of the uplift response, presuming a larger prototype. Therefore, it was felt that very useful data for analytical comparison could be obtained in this manner.

### 2.5 Experimental Results

A total of 52 dynamic tests was conducted on the test model, and the data were stored permanently on 9 track magnetic tape. A complete list of these tests in the sequence conducted is given in Appendix B. From this total of 52 tests, however, only 11 representative cases were selected for detailed data reduction. Table 2.5 .1 shows in summary a number of the more interesting features of these 11 tests. From this table, it is
apparent that a wide range of excitations and response levels is represented in the data to be discussed in this report.

Global response parameters only were examined for 6 of the selected tests; however, both global and certain local response parameters were examined for the 5 tests exhibiting the greatest extent of nonlinear behavior. The results of each individual test are presented in the following sequence:

1. Table motions.
2. Global response.
3. Local response (if applicable).

The general method of data presentation is in the form of time-history plots of the pertinent parameters. Moment-curvature plots demonstrating nonlinear hysteretic behavior are presented where they are deemed most illustrative.

## 2.5a EC 200I

This test, with the input signal scaled to produce a maximum acceleration about $1 / 3$ that of the actual E1 Centro signal, produced a response entirely within what can be considered the linear behavior range. No vertical component of excitation was applied.

Only global response quantities were examined in detail, for this case. Fig. 2.5a.l shows the table motion and response spectra. Fig. 2.5 a .2 shows the floor accelerations along with the table acceleration. The response is seen to be dominated by the first mode, although zonsiderable $2 n d$ mode response is evident in the lst floor acceleration. The vibration periods of the three modes while the structure was supported on the soft pads for phase I were experimentally observed to be . $463, .130$ and .067 seconds respectively, as determined by a Fast Fourier Transform analysis of the 3 rd floor acceleration during free vibration. The
displacements shown in Fig. 2.5a.3 again point out the predominant lst mode contribution, and the story forces shown in Fig. 2.5a.4 verify the overturning moment did not exceed the limiting value of 180 kip-ft required to initiate uplift.
2.5 b EC 100 II

In this test the input signal was scaled to produce a maximum acceleration about $2 / 3$ that of the actual El Centro record. The table motions, shown in Fig. 2.5b.l thus are all nearly twice the amplitudes of Fig. 2.5a.l. The floor accelerations, shown in Fig. $2.5 b .2$ again show a lst mode predominance, with the 2nd mode still visible, particularly in the lst floor acceleration. With the stiffer rubber pads for this phase II test, the observed modal periods were .379, . 133 and .068 seconds, determined in the same manner as previously described. It is interesting to note, that only the first mode period was reduced by the stiffer support system.

Fig. 2.5b. 3 shows the relative story displacements and Eig. 2.5b. 4 shows the momentary column base separations that occurred during this test. Fig. 2.5b.5 verifies that the base overturning moment did reach the uplift limit of $180 \mathrm{kip}-\mathrm{ft}$. The momentary base separations observed in this test, however, had very little effect on the response; it was still essentially a linear behavior. 2.5 C EC 200

This test very nearly duplicated the excitation of EC 200 I . This test, however, was conducted with the column base fixtures attached securely to the foundation, preventing any relative vertical motion. This resulted in a lowering of the modal periods to observed values of .339, . 130 and .068 seconds respectively.

The response observed during this test was also well within what can be considered the linear range. Any nonlinearity in the base constrained case, of course, would have to be due to material yielding and not to any uplift response.

Fig. 2.5c.1 shows the table motions, nearly identical to Fig. 2.5a.1. Fig. 2.5c. 2 shows the floor accelerations. The differing base conditions did not alter greatly the mode shapes, thus the 2 nd mode still shows up most significantly in the first floor. The relative floor displacements, shown in Fig. 2.5c. 3 were again predominantly lst mode, as were the story forces shown in Fig. 2.5c.4. These story forces did not differ greatly in amplitude from the phase I test, even though the relative displacements of Fig. 2.5c.3 were considerably lower in amplitude than those observed in phase I. The reason for this was the rigid body rotation possible in the case where the column bases were not restrained vertically, but were supported on the relatively soft, neoprene pads.

## 2.5 d EC 1000 I

For this test the input was scaled so as to produce a maximum acceleration more than twice that of the actual El Centro record; this excitation produced a significant nonlinear uplift response.

Fig. 2.5d.1 illustrates the greater intensity of the excitation for this test and Fig. 2.5 d .2 displays the nonlinear nature of the response as evidenced by the changing response period. In particular the intervals of response between 3 and 6 seconds and around 11 seconds of the time history were obviously of a complex nonlinear nature. These were, in fact, the intervals in which the uplifting phenomenon was observed to occur. Higher order flexural response may be seen to be superposed on the rigid body rotations that are associated with the column uplift for this structure. Again the elastic 2nd mode contribution is evident in the lst floor acceleration.

Fig. 2.5d.3 shows the large displacements possible with a rigid body response mode. Fig. 2.5d.4 shows the relative column base separations, indicative of the large rotations which occurred. In Fig. 2.5d.5 the performance of the uplift phenomenon as a structural "fuse" is exhibited; the overturning moment only momentarily exceeded the limit corresponding to initiation of uplift response.

Fig. 2.5 d .6 shows the character of the local response quantities in the lst floor columns. Because the recorded force quantities represent only dynamic forces, the column axial forces in tension were clipped off at a level representing the magnitude of the dead weight or static compression.

Fig. 2.5d.7 shows some additional local response quantities, namely the lst floor column moments and average curvatures. These curvatures were measured over a $6^{\prime \prime}$ gage length near the column midheights, the most critical section of these columns due to the brace connection at that point. The hysteresis plot of these quantities, shown in Fig. 2.5d.8, demonstrates that the member distortions were still generally within what can be called a linear range, despite the high intensity of the excitation. This again is demonstrative of the fuse effect of the uplift phenomenon.

## $2.5 \mathrm{e} \mathrm{EC} 1000 / 850 \mathrm{I}$

This test had essentially the same horizontal excitation as the EC 1000 I test, with the addition of the appropriately scaled vertical component of table motion. Comparison of Fig. 2.5e.1 with Fig. 2.5d.1 indicates the close resemblance of the two horizontal table motions. The acceleration response shown in Fig. 2.5 e .2 similarly is nearly a duplicate of Fig. 2.5d.2.

Fig. 2.5 e .3 shows that the relative story displacements were only slightly greater than in the previous test, indicating a slightly larger amplitude of rigid body rotation. This same observation can be made for the vertical displacements of Fig. $2.5 e .4$, and the overturning moment plots of Fig. 2.5 e .5 are again nearly duplicates of Fig. 2.5d.5.

These observations demonstrate that the vertical component of excitation had little effect on the response. This effect, or lack thereof, was consistently noted with regard to any vertical excitations introduced throughout the test program.
2.5 f EC 300 II

The input signal for this test was again scaled to produce a maximum acceleration more than twice that of the actual El Centro record. As shown in Fig. 2.5 f.l the table motion was very similar to the previous El Centro tests. Actually a few variances are apparent in the response spectra; these were probably due largely to the time interval of several months which elapsed between phase I and phase II testing. The analog integrator used to generate the system command signals demonstrated some inconsistency over the relatively long time period involved. The signals did not vary significantly, however, and it is believed that valid comparisons still can be made.

As seen from Fig. 2.5f.2, the response observed during this test was very similar to that seen in the previous tests. There were essentially the same number of uplift "cycles" at around the same relative times. The response during uplift perhaps showed slightly more impact effect with the stiffer foundation pads, and the response outside the uplifting intervals seemed to be more dominated by the fundamental mode.

The relative displacements, shown in Fig. 2.5f.3, were again very similar to those seen in previous tests, as were the column base vertical displacements of Fig. 2.5f.4. As shown in this figure also, the stiffer foundation pads allowed very little relative vertical motion outside the uplifting intervals. The story forces of Fig. 2.5f.5 differed little from previous observations, as did the local member forces of Fig. 2.5f.6. The column axial forces again were clipped at the level of static compression. The column moments and average curvatures, shown in Figs. 2.5f.7 and 2.5f.8, were again within the linear range despite the high intensity of the input.

By comparison of these test results with those of EC 1000 I, it may be seen that the stiffness of the rubber support pads had little effect on the response behavior even when rather large uplift displacements were induced.
2.5 g EC $300 / 675 \mathrm{II}$

This test was identical to EC 300 II except for the addition of the appropriately scaled vertical component of input. As shown in Fig. 2.5g.1, the horizontal table motions had no significant differences from the previous test. Fig. 2.5 g .2 , showing response accelerations, indicates very little difference in the response, when compared to the preceding test result shown in Fig. 2.5f.2. The same similarity of response was evident in the displacements shown in Figs. 2.5 g .3 and 2.5 g .4 when compared to Figs. 2.5f.3 and 2.5f.4. As might be expected, the story forces shown in Fig. 2.5g. 5 were also very similar in nature to those shown in Fig. 2.5 f. 5

From these observations it is apparent that the vertical excitation had little effect in either phase I or phase II testing. Although not shown, tests also were run including vertical excitation for the base
constrained case, with a similar lack of any observable effect. It should be noted here, however, that the gravity load stresses in this model were very low. Hence this evidence should not be construed to indicate that vertical excitation should never be a design consideration in prototype structures.
2.5 h EC 1000

This test, for which the input was again scaled to produce a maximum acceleration more than twice that of the original El Centro record, was the first instance in which some material yielding was observed. The input motions, shown in Fig. $2.5 h .1$, were very similar to the preceding high intensity El Centro tests, shown in Figs. 2.5d.1, 2.5e.1, 2.5f.1 and 2.5g.1.

However, the response accelerations, shown in Fig. 2.5h.2, demonstrated a marked difference from the previous tests where column uplift was allowed. The floor accelerations did not show the obvious nonlinearity associated with uplift in the previous tests; local material yielding produces more gradual global stiffness changes which are not so immediately apparent in the response.

The relative floor displacements, shown in Fig. 2.5h.3, were considerably less than in the uplifting case due to the elimination of rigid body motion. It should be noted, however, that even though the relative displacements are less, the accelerations and consequent forces are considerably greater than those of the uplift tests. This increase can be attributed to the lack of a fuse effect associated with the uplift mechanism. The differing response is shown clearly by comparing the story forces of Fig. 2.5h. 4 with those of Fig. 2.5d.5.

Local member forces, shown in Fig. 2.5h.5, were also correspondingly higher than those observed in the uplift tests. As can be seen in the north column average curvature plot, shown in Fig. 2.5 h.6, some nonlinearity was present, evidenced by the permanent set remaining at this location following the test. This yield phenomenon also is evident in the hysteresis plots of Fig. 2.5h.7. The south colum did not display a significant set due to the differing sense of the static load.

Fig. 2.5h. 8 shows strain data comparisons for the co-located mechanical and resistance strain gages. The correlation seems very good, considering the uncertainties inherent in the optical digitization of the mechanical gage data.

## $2.5 i$ PAC 400 I

This test used the input signal shown in Fig. 2.5i.1, which was based upon the Pacoima Dam record. This motion had a relatively short duration but was very intense and produced some interesting results.

From the floor accelerations shown in Fig. $2.5 i .2$, it can be seen that the response was similar in most respects to that observed in the previous El Centro tests. There were more "cycles" of uplifting response; the rigid body rocking was essentially continuous over the time interval between 3 and 9 seconds of the response. Again a lot of 2 nd mode respanse showed up in the lst floor acceleration.

Although more uplift cycles were observed for this test, Fig. 2.5i.3 shows that the magnitude of rigid body rotation was not as large as that seen in the El Centro tests. Once uplift begins for this structure, the subsequent ground displacement determines the extent of rigid body rotation which takes place. The uplift plots of Fig. $2.5 i .4$ confirm the continuous uplifting response over the previously mentioned time interval. Fig. 2.5i.5 again demonstrates the action of uplift as a structural fuse in limiting the applied loads.

## 2.5 j PAC 700 II

The input for this test was scaled slightly higher than that of the phase I Pacoima test. As mentioned previously, a long term lack of stability observed in the analog integrator used to generate command displacement signals may have led to slight variances between the phase $I$ and phase II signals. The phase II table motions shown in Fig. 2.5j.I are very similar in nature, however, to the phase I input with the possible exception of the lowest frequency range.

The floor acceleration responses of Fig. 2.5j.2 again were similar to the phase I results. The uplift motion, however, lasted a few seconds longer for the phase II test. The relative displacements, shown in Figs. 2.5j.3 and 2.5j.4, indicate that the envelope displacement values were comparable to the phase I test, but occurred later in the response history. The story forces plotted in Fig. 2.5j.5 indicate the same general phenomena mentioned previously.

The local member forces, shown in Figs. 2.5j. 6 and 2.5j.7 bear out the previously described advantage of allowing column uplift. The column axial forces were not observed to be appreciably greater in the phase II tests as compared to the phase I tests. It should be pointed out that the small apparent permanent deformations shown in the average column curvatures of Figure 2.5j. 7 are somewhat misleading. The first floor columns already had been subjected to relatively large inelastic strain during previous "base constrained" tests, and were exhibiting considerable Bauschinger effect. The hysteresis plots of Figs. 2.5j.8 and 2.5j.9 indicate that the local response was very nearly linear.

Fig. 2.5j. 10 shows further strain data comparisons of the mechanical and resistance strain gages. It can be seen that the impact induced transients caused some difficulty in the optical digitization of the
gage trace. The correlation was still relatively good, however.
2.5 k PAC 700

The input signal for this fixed base test was scaled to approximately reproduce the phase II Pacoima Dam test. The table motion shown in Fig. 2.5k.1, indicates that the two excitations were indeed very similar. The low frequency variance in the phase II response spectra from that of the phase I test and of this test may perhaps be attributable to some instrument zero drift.

The floor accelerations, shown in Fig. 2.5k.2, indicate the high intensity of the loads imposed on the structure during this test. These forces were well beyond those required to initiate yielding of critical sections of the structure. The relative floor displacements of Fig. 2.5k.3 show a permanent set, indicative of the nonlinearity of the response. The story forces of Fig. 2.5 k .4 show convincingly the increased loading resulting from anchoring the columns to the foundation; these forces were approximately $1 / 2$ times greater than those of the uplift tests. A similar difference is apparent in the local member forces, shown in Figs. 2.5 k .5 and 2.5 k .6 when compared to those of Figs. 2.5 j .6 and 2.5 j .7 .

As a consequence of increasing the loads acting on the structure, anchoring the columns also can increase considerably the ductility demand on critical sections of the structure. This can be seen quite readily by comparing the plots of Figs. 2.5 k .7 and 2.5 k .8 to those of the corresponding uplift test shown in Figs. 2.5j. 8 and 2.5j.9.

Fig. 2.5 k .9 shows additional comparisons of mechanical and colocated electrical strain gage data. Fig. 2.5 k .10 indicates a potential problem in interpreting the mechanical gage data. Their gage length, in order to produce a readable trace, must by necessity be rather long ( $6^{\prime \prime}$ in this case). By comparing the mechanical gage data to that of resistance gages
of 10 mm gage length distributed along this $6^{\prime \prime}$ distance, one can see the problem which occurs when the mechanical gage spans a region of varying strain gradient. The very high strains in the upper portion of the 6" gage length, associated with the plastic hinge formation at the column midheight, are averaged in with the lower elastic strains below the hinge region. As a consequence of this averaging process, the local strain ductility demand is considerably underestimated by the mechanical gage; one should therefore use some judgment in locating these gages on a structure and in the interpretation of data if obtained in regions of varying strain gradients.

(a) Control Room

(b) Shaking Table

Fig. 2.1.1 Earthquake Simulator


Fig. 2.1.2 Shaking Table Motion Limits


Fig. 2.2.1 Test Model


Fig. 2.2.2 Uplift Mechanism Detail


Fig. 2.3.1 Global Response Sign Convention


Fig. 2.3.2 Local Response Sign Convention

a. Column

b. Girder

Fig. 2.3.3 Average Curvature Measurement


Fig. 2.3.4 Mechanical Strain Gage


Table Displacement


Table Acceleration


EC 200 I
Fig. 2.4.1 Response Spectra; Damping Ratios $=.01, .02$, .03, . 05


Table Displacement


Table Acceleration


EC 1.00 II
Fig. 2.4.2 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


Fig. 2.4.3 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement



EC 1000 I

Fig. 2.4.4 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


EC 1000/850 I

Fig. 2.4.5 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


EC 300 II
Fig. 2.4.6 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


Fig. 2.4.7 Response Spectra; Damping Ratios $=.01, .02$, .03, . 05


Table Displacement


Table Acceleration


Fig. 2.4.8 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


Fig. 2.4.9 Response Spectra; Damping Ratio $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


Fig. 2.4.10 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


Table Displacement


Table Acceleration


PAC 700

Fig. 2.4.11 Response Spectra; Damping Ratios = .01, .02, .03, . 05
Table 2.5.1 Selected Envelope Data Quantities

| No. | Test | Max. Table <br> Acc. (g) | Max. Table Displ. (in) | Max. 3rd Flr. <br> Rel. Displ. (in) | Max. Base <br> Shear (\%W) | Estimated Max. Strain Ductility |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | EC 200 I | . 10 | . 70 | . 85 | 30 | . 25 |
| 2 | EC 100 II | . 22 | 1.25 | 1.1 | 50 | . 4 |
| 3 | EC 200 | . 10 | . 75 | . 50 | 30 | . 25 |
| 4 | EC 1000 I | . 67 | 3.50 | 6.0 | 80 | . 6 |
| 5 | EC 1000/850 I | . 76 | 3.47 | 6.4 | 80 | . 6 |
| 6 | EC 300 II | . 72 | 3.80 | 5.3 | 90 | . 8 |
| 7 | EC 300/675 II | . 84 | 3.65 | 5.3 | 90 | . 8 |
| 8 | EC 1000 | . 74 | 3.67 | 2.4 | 120 | 3. |
| 9 | PAC 400 I | . 88 | 3.45 | 3.3 | 80 | . 8 |
| 10 | PAC 700 II | 1.04 | 3.86 | 3.5 | 90 | . 8 |
| 11 | PAC 700 | 1.11 | 3.84 | 3.3 | 130 | 5. |



Table Displacement


Table Acceleration


Fig. 2.5a.1 Response Spectra, Damping Ratios $=.01, .02, .03, .05$


3rd Floor Acceleration


2nd Floor Acceleration


1st Floor Acceleration


Table Acceleration

Fig. 2.5a. 2 EC 200 I Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement -- 3rd Floor Absolute Displacement

Fig. 2.5a. 3 EC 200 I Displacements


3rd Floor Shear


2nd Floor Shear


Base Shear


Base Overturning Moment

Fig. 2.5a. 4 EC 200 I Story Forces


Table Acceleration


Fig. 2.5b.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


3rd Floor Acceleration


2nd Floor Acceleration

lst Floor Acceleration


Table Acceleration

Fig. 2.5b. 2 EC 100 II Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


Fig. 2.5b. 3 EC 100 II Displacements


Fig. 2.5b. 4 EC 100 II Relative Column Vertical Displacements



2nd Floor Shear


Base Shear


Base Overturning Moment

Fig. 2.5b.5 EC 100 II Story Forces


Table Displacement


Table Acceleration


Fig. 2.5c.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$



1st Floor Acceleration


Fig. 2.5c. 2 EC 200 Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement
-- 3ra Floor Absolute Displacement

Fig. 2.5c. 3 EC 200 Displacements



2nd Floor Shear


Base Shear


Base Overturning Moment

Fig. 2.5c. 4 EC 200 Story Forces


Table Displacement


Table Acceleration


EC 1000 I
Fig. 2.5d.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$



2nd Floor Acceleration

lst Floor Acceleration


Table Acceleration

Fig. 2.5d.2 EC 1000 I Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement -- 3rd Floor Absolute Displacement

Fig. 2.5d.3 EC 1000 I Displacements


North Column West Frame


North Column East Frame


South Column West Frame


South Column East Frame

Fig. 2.5d.4 EC 1000 I Relative Column Vertical Displacements


3rd Floor Shear


2nd Floor Shear


Base Shear


Base Overturning Moment

Fig. 2.5d.5 EC 1000 I Story Forces


North Column Axial Force


South Column Shear


South Column Axial Force

Fig. 2.5d.6 EC 1000 I Member Forces


North Column Moment

North Column Average Curvature (6" gage)

South Column Moment


South Column Average Curavture (6" gage)

Fig. 2.5d.7 EC 1000 I Column Moments and Curvatures


lst Floor Acceleration


Table Acceleration

Fig. 2.5e. 2 EC 1000/850 I Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement
-- 3rd Floor Displacement

Fig. 2.5e. 3 EC 1000/850 I Displacements


3rd Floor Relative Displacement


2nd Floor Relative Displacement


1st Floor Relative Displacement


- Table Displacement
-- 3rd Floor Displacement

Fig. 2.5e.3 EC 1000/850 I Displacements


North Column West Frame


North Column East Frame


South Column west Frame


Fig. 2.5e. 4 EC 1000/850 I Relative Column Vertical Displacements


3rd Floor Shear



Base Shear


Base Overturning Moment

Fig. 2.5e.5 EC 1000/850 I Story Forces


3rd Floor Relative Displacement


2nd Floor Relative Displacement


1st Floor Relative Displacement


Fig. 2.5f.3 EC 300 II Displacements


North Column West Frame


North Column East Frame


South Column West Frame


South Column East Frame
Fig. 2.5f. 4 EC 300 II Relative Vertical Displacements




Base Shear


Base Overturning Moment
Fig. 2.5f.5 EC 300 II Story Forces


North Column Shear


North Column Axial Force


South Column Shear


South Column Axial Force
Fig. 2.5f. 6 EC 300 II Member Forces


North Column Moment


North Column Average Curvature (6" gage)


South Column Moment


South Column Average Curvature (6" gage)

Fig. 2.5£.7 EC 300 II Column Moments and Curvatures



Table Displacement


Table Acceleration


Fig. 2.5g.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


lst Floor Acceleration


Table Acceleartion

Fig. 2.5g. 2 EC 300/675 II Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


Fig. 2.5g. 3 EC $300 / 675$ II Displacements


North Column East Frame


South Column West Frame


South Column East Frame

Fig. 2.5g. 4 EC $300 / 675$ II Relative Column Vertical Displacements

##  <br> 3rd Floor Shear



2nd Floor Shear


Base Shear


Base Overturning Moment

Fig. 2.5g.5 EC 300/675 II Story Forces


Table Displacement


Table Acceleration


EC 1000
Fig. 2.5h.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$




Fig. 2.5h. 2 EC 1000 Accelerations


2nd Floor Relative Displacement



Table Displacement
-- 3rd Floor Absolute Displacement
Fig. 2.5h. 3 EC 1000 Displacements




Base Shear


Base Overturning Moment
Fig. 2.5h. 4 EC 1000 Story Forces


North Column Shear


North Column Axial Force


South Column Shear


South Column Axial Force
Fig. 2.5h. 5 EC 1000 Member Forces


North Column Moment


North Column Average Curvature (6" gage)


South Column Moment


South Column Average Curvature (6" gage)

Fig. 2.5h. 6 EC 1000 Column Moments and Curvatures




Fig. 2.5h.7 EC 1000 North Column Moment vs Average Curvature


3rd Floor Acceleration


2nd Floor Acceleration


1st Floor Acceleration


Table Acceleration

Fig. 2.5i. 2 PAC 400 I Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement
-- 3rd Floor Absolute Displacement

Fig. 2.5i.3 PAC 400 I Displacements


North Column West Frame


North Column East Frame


South Column West Frame


South Column East Frame

Fig. 2.5i.4 PAC 400 I Relative Column Vertical Displacements



Base Shear


Base Overturning Moment

Fig. 2.5i.5 PAC 400 I Story Forces


3rd Floor Shear



Base Shear


Base Overturning Moment

Fig. 2.5i. 5 PAC 400 I Story Forces


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


Fig. 2.5j. 3 PAC 700 II Displacements


North Column West Frame


North Column East Frame


South Column West Frame


South Column East Frame

Fig. 2.5j.4 PAC 700 II Relative Column Vertical Displacements


North Column East Frame


South Column west Frame


South Column East Frame

Fig. 2.5j.4 PAC 700 II Relative Column Vertical Displacements




Base Shear


Base Overturning Moment

Fig. 2.5j.5 PAC 700 II Story Forces


North Column Shear


North Column Axial Force


South Column Shear


South Column Axial Force

Fig. 2.5j. 6 PAC 700 II Member Forces



Table Acceleration


Fig. 2.5k.1 Response Spectra; Damping Ratios $=.01, .02, .03, .05$


3rd Floor Acceleration


2nd Floor Acceleration

lst Floor Acceleration


Table Acceleration

Fig. 2.5k.2 PAC 700 Accelerations


3rd Floor Acceleration


2nd Floor Acceleration


Ist Floor Acceleration


Table Acceleration

Fig. 2.5k. 2 PAC 700 Accelerations


3rd Floor Relative Displacement


2nd Floor Relative Displacement

lst Floor Relative Displacement


- Table Displacement
-- 3rd Floor Absolute Displacement

Fig. 2.5k. 3 PAC 700 Displacements


3rd Floor Shear



Base Shear


Base Overturning Moment

Fig. 2.5k. 4 PAC 700 Story Forces



North Column Axial Force


South Column Shear


South Column Axial Force

Fig. 2.5k.5 PAC 700 Member Forces



South Column Moment


South Column Average Curvature (6" gage)

Fig. 2.5k. 6 PAC 700 Column Moments and Curvatures


$11.25-15.00 \mathrm{sec}$
Moment vs Flexural Strain







Fig. 2.5k.9 PAC 700 Mechanical Strain Gage Comparisons



Strain at Center of $6^{\prime \prime}$ Gage Length


Strain at Bottom of 6" Gage Length

- Electrical
$\triangle$ Mechanical
Fig. 2.5k.10 PAC 700 Column NB Mechanical Strain Gage Comparisons


## 3. ANALYTICAL CORRELATION OF TEST DATA

As was mentioned in the introduction, a primary impetus for this initial experimental program was to provide a basis for the evaluation of currently available nonlinear analytical techniques in predicting uplift behavior. In addition to this initial study of the uplift phenomenon, the data obtained in the nonlinear fixed-base tests were also to be used to evaluate nonlinear frame analysis procedures employing concentrated plastic hinges at the member ends. To carry out these evaluations, selected test accelerograms were used as the input records for the nonlinear analysis of the appropriate mathematical models. The analytical responses obtained were then compared directly with the corresponding experimental data.

The computer program utilized for the analytical work was DRAIN-2D, described fully by Kanaan and Powell (3). DRAIN-2D is a general twodimensional structure program for nonlinear earthquake response analysis. It is applicable to cases having identical seismic excitation of all support points. The full set of incremental equations of motion are numerically integrated using the assumption of constant average nodal accelerations within each integration time step. Unbalanced loads resulting from stiffness changes are corrected in the following time step, necessitating fairly small time steps to avoid large "overshoots" at instants of significant stiffness change. Damping capabilities presently available in the program include arbitrary combinations of mass proportional, original stiffness proportional, and tangent stiffness proportional viscous damping.

### 3.1 Uplift Response

The basic uplifting mathematical model is shown in Fig. 3.1.1. The uplift phenomenon was approximated by specifying the vertical foundation support elements to be bilinear elastic, with zero tensile force capacity and with zero stiffness in the upward direction. All structural members in the frame, except these support elements, were assumed to behave in a linear manner. Static loads were applied prior to all dynamic analyses so their influence was considered in the nonlinear support response.

Table interaction in the pitching mode was not considered directly in the uplift analysis, but could be accommodated partially by adjusting the structure support spring stiffnesses. This omission quite possibly could account for the greater difficulty encountered in achieving good correlation of data for the phase II tests, where the stiffer set of impact pads were employed. More will be said of this later.

The improvement of data correlation was accomplished by adjustment of the damping assumed for the basic mathematical model already described. This adjustment process was performed solely on the basis of physical insight into the model's behavior. The more systematic approaches of system identification have not yet been applied to the seismic response of systems with this degree of complexity.

The uplift tests for which analyses were performed were the EC 1000 I test and the EC 300 II test. It was felt that these tests were representative of phase I and phase II nonlinear tests. Integration time steps of .01 and .005 seconds were used for the phase I and phase II tests, respectively. The smaller time step for phase II analysis was utilized to avert potential analytical complications due to the more severe impact conditions in that case.

As was indicated by the experimental results, the stiffness of the impact pads beneath the column bases had a very pronounced effect on the fundamental frequency of vibration of the structure. This analytical relationship, assuming a rigid support beneath the impact pads, is shown in Fig. 3.1.2.

In Fig. 3.1.3 are shown the analytical mode shapes and frequencies of the mathematical models used for phase I and phase II calculations. From these mode shapes, it is apparent why a great deal of 2 nd mode response was evident in the lst floor accelerations, as was mentioned previously in Chapter 2. The very slight influence of the pad stiffness on the mode shapes is interesting to note, in view of its rather significant effect on the first mode frequency.

## 3.1a Phase I Computations

As was mentioned previously, the EC 1000 I test was selected as an appropriate signal for the phase I nonlinear analysis. An effective impact pad stiffness of $40 \mathrm{kip} / \mathrm{in}$ in the mathematical model matched very closely the observed fundamental frequency, although this is nearly 10\% below the actual value. A damping estimate of $2 \%$ critical for the observed first mode frequency was selected as a reasonable preliminary estimate, based on observed decay curves for the structure.

The mass proportional, original stiffness proportional and tangent stiffness proportional viscous damping coefficients employed in the computer analysis are designated $\alpha, \beta_{0}$, and $\beta$, respectively. Since a rigid body motion was possible for this structure, and it would not be expected to exhibit much damping in this type of response, mass proportional damping, which increases with decreasing frequency, was not deemed a reasonable type of damping to employ. For the first analysis, therefore, it was decided to try original stiffness porportional viscous damping,
with $\beta_{0}$ equal to .00293 , corresponding to about $2 \%$ critical first mode damping. The results of this analysis are shown in Fig. 3.la.l; the response quantities plotted are the top floor displacement relative to the table and the relative vertical displacements of the two column bases. As can be seen in the time history plots, the rigid body motion evidently was damped too heavily in this analysis.

Based on the results of this first analysis it was decided to reduce the effective damping of the rigid body motion. For this reason, the type of damping was changed to tangent stiffness proportional, with $\beta$ equal to the same value of .00293 . Because the effective tangent stiffness of the rigid body motion is zero, this mechanism should have produced less damping in the uplifting portion of the response. The results of this second analysis are shown in Fig. $3.1 a .2$ and, indeed, the results are considerably improved.

From the results of this second analysis, however, it seemed that there still was too much damping in the system. Therefore, for the third analysis $\beta$ was reduced from .00293 to . 002196 , corresponding to a reduction in the first mode critical damping ratio to about $1 / 2 \%$. The results of this analysis are shown in Fig. 3.la.3. Here the correlation between analysis and experiment is much improved, and was in fact deemed satisfactory from an engineering viewpoint. The shear and axial forces developed in the two lst floor columns during this analysis are shown in Fig. 3.la.4.

## 3.1b Phase II Computations

The phase II correlation was more complicated than the phase I case due largely, it was felt, to two separate problems. The stiffer impact pads, as fabricated did not exhibit a consistent behavior from one pad to another, nor for each individual pad throughout the test sequence. Most of this problem was associated with bond deterioration between the neoprene
material and the steel plates used to attach the pads to the structure's foundation. Secondly, the stiffer impact pads resulted in a more obvious pitching mode interaction problem between the structure and the shaking table. This problem was treated by reducing the effective stiffness of the spring support elements in the basic mathematical uplift model to about 50 per cent of the actual value, so that the observed fixst mode frequency was reasonably well matched; this is not a completely satisfactory solution but it eventually gave acceptable results.

As was mentioned previously, the EC 300 II test was selected as the basis of analytical correlation for phase II tests. It seemed reasonable that the same type of damping, i.e. tangent stiffness proportional viscous damping, should be used for this analysis as was used successfully in the phase $I$ computations. As a first attempt, the same damping coefficient, .002196, was used. The results of this analysis, which had an effective first mode damping coefficient of 1.8\%, are shown in Fig. 3.1b.1. They indicate that the damping was too high, so the damping ratio was reduced to about $11 / 2 \%$ for the next analysis by lowering $\beta$ to . 001758. The results of this analysis are shown in Fig. 3.1b.2; there is some improvement in the correlation, but it was not yet deemed acceptable.

As the correlation seemed to be improving, it was decided to continue lowering the damping in the system. Fig. $3.1 b .3$ shows the results of an analysis with $\beta$ equal to .001621 , corxesponding to an effective first mode damping ratio of $1.4 \%$. Fig. 3.1b. 4 shows the results of an analysis with $\beta$ equal to . 0015, corresponding to a first mode damping ratio of 1.26\%. This analysis appeared to have reduced the damping too far. Fig. 3.1b.5 shows the results of the final analysis, performed with $\beta$ equal to . 00153, corresponding to an effective first mode damping ratio of 1.3\%. It was felt that this was about the best results obtainable without
modeling the table interaction, and due to the other complications mentioned earlier, it was decided to assume these results were within reasonable engineering accuracy. The local force comparisons shown in Fig. 3.lb. 6 again depict the first floor column shears and axial forces.

### 3.2 Fixed-Base Response

The basic "fixed-base" mathematical model is shown in Fig. 3.2.1. As can be seen, the shaking table pitching mode was considered in this model. The spring elements supporting the table were taken to be linear in both tension and compression, within the force limits expected in the analysis. The table itself was assumed to rotate as a rigid body. One additional modification from the mathematical model used in the uplift analyses was the addition of a second beam-column element, parallel to the lower half of each first floor column. Since both beam-column elements used in the analysis were bilinear in nature, this parallel configuration allowed a more general trilinear or quadrilinear moment-curvature relationship.

The model parameters which were available for adjustment were the moment-curvature relationship for the first floor columns, the support spring stiffness for the shaking table and the viscous damping coefficients. In preliminary studies, it was found that a table support spring stiffness of $400 \mathrm{kip} /$ in matched well the lst mode frequency of vibration. The frequencies and mode shapes of the resulting mathematical model are shown in Fig. 3.2.2.

From experimental observation, it was concluded that a trilinear moment-curvature relationship would adequately model the first floor column members. The moment values used for the "corners", $M_{1}$ and $M_{2}$ in Figure 3.2.3, were taken initially to roughly fit the experimental curve
of Figure 2.5k.8, for the hysteresis cycle of greatest amplitude. It was also decided rather arbitrarily to begin analysis using only original stiffness proportional viscous damping.

For the first attempt at analytical correlation, the EC 1000 test signal was used as the input. A value of .0014 was chosen as the initial value of $\beta_{o}$, and values of 100 kip -in and 350 kip -in were used as $M_{1}$ and $M_{2}$, respectively. The results of this analysis for the 3 rd floor relative displacement are shown in Figure 3.2.4.

From the first analysis it appeared there was too much damping present in the system, so the value of $\beta$ was lowered to .00125 ; this lowered the lst mode damping ratio from $1.3 \%$ to approximately $1.2 \%$. The results of this analysis are shown in Figure 3.2.5.

It still appeared that too much damping was present in the system, so analyses were carried out with values of $\beta_{o}$ of .00108 and .0008 . These results are shown in Figs. 3.2 .6 and 3.2 .7 , respectively. There was no significant improvement in the correlation between analytical and experimental results. Even though the first mode damping ratio was down to $.75 \%$ for the last analysis, apparently too much damping still was present.

At this point, it was decided that the excessive energy dissipation noted above might be due to the hysteretic characteristics of the momentcurvature relationship of the lst floor columns rather than to the damping coefficient. Another analysis was carried out with the value of $M_{1}$ increased to $200 \mathrm{kip}-\mathrm{in}$ and $\beta_{o}$ again set to .00108 . This value of $\beta_{o}$ produces a first mode damping ratio of $1 \%$. The results of this analysis are shown in Figure 3.2.9; the three plots depict the 3rd floor relative displacement, the north column shear and the north column axial force, respectively. The correlation appears excellent, and no futher analyses
were carried out for this input signal.
It was decided, however, to attempt another analysis using the PAC 700 input signal, during which the greatest amplitude plastic hinge rotation was observed. For this analysis, values of 100 kip -in and 300 kip -in were used for $M_{1}$ and $M_{2}$, respectively. A value of . 00196 was specified for $\beta_{0}$. The results of this analysis are shown in Figure 3.2.9; the quantities plotted were the same as for Figure 3.2.8.

From the results of this last analysis, one deficiency of the analytical model is pointed out; the lack of any form of stiffness degradation mechanism. The large amplitude response was matched relatively well, but there was again too much hysteretic energy dissipation for the lower amplitude portion of the response. The moment-curvature relationship used in the analysis matched well the large amplitude response, where considerable Bauschinger effect was observed, but did not match well the low amplitude response. This fact can be seen by examination of the hysteretic behavior shown in Figure 2.5 k .7 and Figure 2.5 k .8 .


Fig. 3.l.1 Uplift Analytical Model


Fig. 3.1.2 Calculated lst Mode Period vs Impact Pad Stiffness.


Fig. 3.1.3 Frequencies Calculated and Mode Shapes


North Column Relative Vertical Displacement


South Column Relative Vertical Displacement

Fig. 3.Ia.1 EC 1000 I Analytical Comparisons, $\beta_{0}=.00293$



North Column Relative Vertical Displacement


South Column Relative Vertical Displacement

Fig. 3.la. 2 EC 1000 I Analytical Comparisons, $\beta=.00293$


Fig. 3.la.3 EC 1000 I Analytical Comparisons, $\beta=.002196$



Axial Force North Column



Axial Force South Column
Fig. 3.la. 4 EC 1000 I Analytical Comparisons, $\beta=.002196$


3rd Floor Relative Displacement



South Column Relative Vertical Displacement

Fig. 3.1b.1 EC 300 II Analytical Comparisons, $\beta=.002196$


Fig. 3.2.8 EC 1000 Analtyical Comparisons, $B_{0}=.00108, M_{1}=200, M_{2}=350$


3rd Floor Relative Displacement


Shear North Column


Fig. 3.2.9 PAC 700 Analytical Comparisons, $\beta_{0}=.00196, M_{1}=100, M_{2}=300$

## 4. SUMMARY AND CONCLUSTONS

In this test program the uplifting response of a three story singlebay steel frame under simulated earthquake excitation was investigated, both experimentally and analytically. In addition, this uplift response was compared with the response to similar excitations during which the column bases were securely anchored to the foundation to prevent uplift.

It was demonstrated that the uplift phenomenon resulted in a definite reduction in the structural force response quantities, as compared to the cases for which uplift was prevented. The action of the uplift response mechanism as a structural "fuse" was clearly evident. For this frame, the internal forces were reduced by about one-third through allowing uplift, and local strain ductility demands on the structure were reduced from values of about 5 to less than unity. It was noted, however, that the rigid body motions possible for this single-bay frame with pinned column bases led to considerably larger relative story displacements when uplift was allowed.

It was also demonstrated that the uplift response for this frame was very accurately represented by means of an analytical procedure utilizing bilinear elastic support elements having zero tensile stiffness and force capacity in the upward direction. Good agreement with experimental results was achieved even when the column base separations approached four inches in amplitude, for this approximately one-half scale frame. The analtyical procedure predicted accurately the large rigid body rotations when a tangent stiffness proportional viscous damping matrix was employed.

Good agreement between experimental and analytical results also was achieved for the inelastic response tests with no uplift allowed. It was observed, however, that some problems occurred during the largest plastic hinge rotations due to the Bauschinger effect, which was not well simulated in the analytical model.

The results of this test program validate the hypothesis stated in the introduction that allowing column uplift in building frames can lead to more rational and economical designs. At least for the type of frame tested, analytical procedures are currently available to accurately predict the uplift behavior which is developed during very severe earthquake excitation.

As a consequence of the promising results reported in this preliminary study, it was decided to extend the research program to include a superstructure system more representative of a realistic prototype. The results of that combined experimental and analytical investigation are presented in a subsequent EERC report entitled "Earthquake Simulation Tests of a Nine-Story Steel Frame with Columns Allowed to Uplift."

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Appendix A

Data Channel Listings

Table A-1 Phase I Data Channel Schedule

| CHANNEL | CHANNEL MNEMONIC | CHANNEL DESCRIPTION |
| :---: | :---: | :---: |
| 0 | Cmd H Acc | Command horizontal accl. signal |
| 1 | Cmd V Acc | Command vertical accl. signal |
| 2 | Cmd H Disp | Command horizontal displ. signal |
| 3 | Cmd V Disp | Command vertical displ. signal |
| 4 | Av H T Displ | Average horizontal table displ. |
| 5 | Av V T Displ | Average vertical table displ. |
| 6 | Av H T Acc | Average horitontal table accl. |
| 7 | Av V T Acc | Average vertical table accl. |
| 8 | Pitch | Angular accl. in pitching mode |
| 9 | Roll | Angular accl. in rolling mode |
| 10 | Twist | Angular accl. in twisting mode |
| 11 | Force Hl | Force in horizontal actuator |
| 12 | Force H2 | Force in horizontal actuator |
| 13 | Force H3 | Force in horizontal actuator |
| 14 | Acc H1 | Individual table accelerometer (hor) |
| 15 | Acc H2 | Individual table accelerometer (hor) |
| 16 | Acc V1 | Individual table accelerometer (vert) |
| 17 | Acc V2 | Individual table accelerometer (vert) |
| 18 | Acc V3 | Individual table accelerometer (vert) |
| 19 | Acc V4 | Individual table accelerometer (vert) |
| 20 | Force V1 | Force in vertical actuator |
| 21 | Force V2 | Force in vertical actuator |
| 22 | Force V3 | Force in vertical actuator |
| 23 | Force V4 | Force in vertical actuator |
| 24 | Displ V1 | Individual table vertical displ. |
| 25 | Displ V2 | Individual table vertical displ. |
| 26 | Displ V3 | Individual table vertical displ. |
| 27 | Displ V4 | Individual table vertical displ. |
| 28 | Displ H1 | Individual table horizontal displ. |
| 29 | Displ H2 | Individual table horizontal displ. |
| 30 | Displ H3 | Individual table horizontal displ. |
| 31 | blank |  |
| 32 | PS Force-1 | Force in passive stabilizer |
| 33 | PS Force-2 | Force in passive stabilizer |
| 34 | PS Force-3 | Force in passive stabilizer |
| 35 | PS Force-4 | Force in passive stabilizer |
| 36 | Flr Acc 1 | lst floor acceleration |
| 37 | Flr Acc 2 | 2nd floor acceleration |
| 38 | Flr Acc 3 | 3rd floor acceleration |
| 39 | blank |  |
| 40 | Flr Disp 1 | lst floor absolute displacement |
| 41 | Flr Disp 2 | 2nd floor absolute displacement |
| 42 | FIr Disp 3 | 3rd floor absolute displacement |
| 43 | Uplift NA | Vertical displacement of column base NA |
| 44 | Uplift NBO | Vertical displ. of outside column base NB |
| 45 | Uplift NBI | Vertical displ. of inside column base NB |

Uplift SA
Uplift SB
Contact Na
Contact NB
Contact SA
Contact SB
Clstr-NAO-1
Clstr-NAI-1
Clstr-SAO-1
CLstr-SAI-1
Clrot-NAO-1
Clrot-NAI-1
Clrot-SAO-1
Clrot-SAI-1
C1flx-NAM-1
Clflx-SAM-1
Clflx-NBM-1
Clflx-SBM-;
Clstr-NBO-1
Clstr-NBI-1
Clstr-SBO-1
Clstr-SBI-1
Clrot-NBO-1
Clrot-NBI-1
Clrot-SBO-1
Clrot-SBI-1
Clflx-NAB-1
Clf1x-NAT-1
Slflx-SAB-1
Clflx-SAT-1
Bmflx-NO-1
Bmflx-NI-1
Bmflx-SI-1
Bmflx-SO-1
Clrot-NBO-2
Clrot-NBI-2
clrot-SBO-2
Clrot-SBI-2
Clflx-NBT-2
Clflx-NBB-2
Clflx-SBT-2
C1f1x-SBB-2
Clflx-NAY-2
Clflx-NBY-2
Clf1x-SAY-2
Clflx-SBY-2
Clflx-NAT-2
Clflx-NAB-2
Clflx-SAT-2
C1flx-SAB-2
Clrot-NAO-2
Clrot-NAI-2
Clrot-SAO-2
Clrot-SAI-2

Vertical displ. of column base SA
Vertical displ. of column base $S B$
Contact switch under column NA
Contact switch under column NB
Contact switch under column SA
Contact switch under column SB
Col. NA strain outside face lst floor
Col. NA strain inside face lst floor
Col. SA strain outside face lst floor
Col. SA strain inside face lst floor
Col. NA DCDT outside face lst floor
Col. NA DCDT inside face lst floor
Col. SA DCDT outside face lst floor
Col SA DCDT inside face lst floor
Col. NA flex. strain @ midheight lst floor
Col. SA flex. strain @ midheight lst floor
Col. NB flex. strain @ midheight lst floor
Col. SB flex. strain @ midheight lst floor
Col. NB strain outside face lst floor
Col. NB strain inside face lst floor
Col. SB strain oustide face lst floor
Col. SB strain inside face lst floor
Col. NB DCDT outside face lst floor
Col. NB DCDT inside face lst floor
Col. SB DCDT outside face lst floor
Col. SB DCDT inside face lst floor
Col. NA flex. strain bottom station lst flr.
Col. NA flex strain top station lst flr.
Col. SA flex strain bottom station 1st flr.
Col. SA flex. strain top station lst flr.
Beam flex. strain noxth end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Col. NB DCDT outside face 2nd floor
Col. NB DCDT inside face 2nd floor
Col. SB DCDT outside face 2nd floor
Col. SB DCDT inside face 2nd floor
Col. NB flex. strain top station 2 nd flr.
Col. NB flex. strain bottom station 2nd flr.
Col. SB flex. strain top station 2nd flr.
Col. SB flex. strain bottom station $2 n d$ flr.
Col. NA post-yield strain 2nd floor
Col. NB post-yield strain 2nd floor
Col. SA post-yield strain 2nd floor
Col. SB post-yield strain 2nd floor
Col. NA flex. strain top station 2nd flr.
Col. NA flex. strain bottom station 2nd flr.
Col. SA flex. strain top station $2 n d$ flr.
Col. SA flex. strain bottom station 2nd flr.
Col. NA DCDT outside face 2 nd floor
Col. NA DCDT inside face 2nd floor
Col. SA DCDT outside face 2nd floor
Col. SA DCDT inside face 2nd floor

Bmflx-NAY-2
Bmflx-NBY-2
Bmflx-SAY-2
Bmflx-SMY-2
Bmflx-NO-2
Bmflx-NI-2
Bmflx-SI-2
Bmflx-SO-2
Bmrot-NOT-2
Bmrot-NOB-2
Bmrot-SOT-2
Bmrot-SOB-2
Jtrot-NT
Jtrot-NB
Jtrot-ST
Jtrot-SB
Bmrot-NIT
Bmrot-NIB
Bmrot-SIT
Bmrot-SIB
Clflx-NAT-3

## Clflx-NAB-3

Clflx-SAT-3
Clflx-SAB-3

Beam post-yield strain north end frame A
Beam post-yield strain north end frame B
Beam post-yield strain south end frame A
Beam post-yield strain south end frame B
Beam flex. strain north end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Beam DCDT north outside station top face
Beam DCDT north outside station bottom face
Beam DCDT south outside station top face
Beam DCDT south soutside station bottom face
Joint DCDT north end top side
Joint DCDT north end bottom side
Joint DCDT south end top side
Joint DCDT south end bottom side
Beam DCDT north inside station top face
Beam DCDT north inside station bottom face
Beam DCDT south inside station top face
Beam DCDT south inside station bottom face
Col. NA flex. strain top station 3rd flr.
Col. NA flex. strain bottom station 3rd flr.
Col. SA flex. strain top station 3rd flr.
Col. SA flex. strain bottom station 3rd flr.

Table A-2 Phase II Data Channel Schedule

## CHANNEL

CHANNEL MNEMONIC

Cmd H Acc
Cmd V Acc
Cmd H Disp
Cmd v Disp
Av H T Displ
Av $V$ T Displ
Av H T Acc
AV $V$ T Acc
Pitch
Roll
Twist
Force HI
Force H2
Force H3
Acc Hl
Acc H2
Acc V1
Acc V2
Acc V3
Acc V4
Force VI
Force V2
Force V3
Force V4
Displ V1
Displ V2
Displ V3
Displ V4
Displ Hl
Displ H2
Displ H3
blank
PS Force-1
PS Force-2
PS Force-3
PS Force-4
Flr Acc 1
Flr Acc 2
Fir Acc 3
blank
Flr Disp 1
Flr Disp 2
Flr Disp 3
blank
Uplift NA
Uplift NB

## CHANNEL DESCRIPTION

Command horizontal accl. signal
Command vertical accl. signal Command horizontal displ. signal Command vertical displ. signal Average horizontal table displ. Average vertical table displ. Average horizontal table accl. Average vertical table accl. Angular accl. in pitching mode Angular accl. in rolling mode Angular accl. in twisting mode
Force in horizontal actuator
Force in horizontal actuator
Force in horizontal actuator
Individual table accelerometer (hor)
Individual table accelerometer (hor)
Individual table accelerometer (vert) Individual table accelerometer (vert) Individual table accelerometer (vert) Individual table accelerometer (vert)
Force in vertical actuator
Force in vertical actuator
Force in vertical actuator
Force in vertical actuator
Individual table vertical displ.
Individual table vertical displ. Individual table vertical displ. Individual table vertical displ. Individual table horizontal displ. Individual table horizontal displ. Individual table horizontal displ.

Force in passive stabilizer
Force in passive stabilizer
Force in passive stabilizer
Force in passive stabilizer
lst floor acceleration
2nd floor acceleration
3rd floor acceleration
1st floor absolute displacement
2nd floor absolute displacement
3rd floor absolute displacement
Vertical displacement column base NA Vertical displacement column base NB

Uplift SA
Uplift SB
Clstr-NBO-L Clstr-NBO-M
Clstr-NBO-U
Clstr-NBI-U
Clstr-NAO-1
Clstr-NAI-1
Clstr-SAO-1
Clstr-SAI-1
Clrot-NAO-1
Clrot-NAI-1
Clrot-SAO-1
Clrot-SAI-1
Clflx-NAM-1
Clflx-SAM-1
Clstr-NBI-M
Clflx-SBM-1
Clstr-NBO-1
Clstr-NBI-1
Clstr-SBO-I
Clstr-SBI-1
Clrot-NBO-1
Clrot-NBI-1
Clrot-SBO-1
Clrot-SBI-1
Clf1x-NAB-1
Clflx-NAT-1
C1flx-SAB-1
C1flx-SAT-1
Bmflx-NO-1
Bmflx-NI-1
Bmflx-SI-1
Bmflx-SO-1
Clrot-NBO-2
Clrot-NBI-2
clrot-SBO-2
Clrot-SBI-2
Clflx-NBT-2
Clflx-NBB-2
Clflx-SBT-2
Clflx-SBB-2
Clflx-NAY-2
Clflx-NBY-2
Clflx-SAY-2
Clflx-SBY-2
Clflx-NAT-2
Clflx-NAB-2
Clflx-SAT-2
Clflx-SAB-2
Clrot-NAO-2
Clrot-NAI-2
Clrot-SAO-2
Clrot-SAI-2

Vertical displ. of column base SA
Vertical displ. of column base SB
Col NB midheight strain out face lower station
Col NB midheight strain out face mid station
Col Nb midheight strain out face upper station
Col NB midheight strain in face upper station
Col. NA strain outside face lst floor
Col. NA strain inside face lst floor
Col. SA strain outside face lst floor
Col. SA strain inside face lst floor
Col. NA DCDT outside face lst floor
Col. NA DCDT inside face lst floor
Col. SA DCDT outside face lst floor
Col. SA DCDT inside face lst floor
Col. NA flex. strain @ midheight lst floor
Col. SA flex. strain © midheight lst floor
Col. NB midheight strain in face mid station
Col. SB flex. strain @ midheight lst floor
Col. NB strain outside face lst floor
Col. NB strain inside face lst floor
Col. SB strain outside face lst floor
Col. SB strain inside face lst floor
Col. NB DCDT outside face lst floor
Col. NB DCDT inside face lst floor
Col. SB DCDT outside face lst floor
Col. SB DCDT inside face lst floor
Col. NA flex. strain bottom station lst flr.
Col. NA flex. strain top station lst flr.
Col. SA flex. strain bottom station lst flr.
Col. SA flex. strain top station lst flr.
Beam flex. strain north end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Col. NB DCDT outside face 2nd floor
Col. NB DCDT inside face 2nd floor
Col. SB DCDT outside face 2nd floor
Col. SB DCDT inside face 2nd floor
Col. NB flex. Strain top station 2nd flr.
Col. NB flex. strain bottom station $2 n d$ flr.
Col. SB flex. strain top station 2 nd flr.
Col. SB flex. strain bottom station $2 n d$ flr.
Col. NA post-yield strain 2nd floor
Col. NB post-yield strain 2nd floor
Col. SA post-yield strain 2nd floor
Col. SB post-yield strain 2nd floor
Col. NA flex. strain top station 2nd flr.
Col. NA flex. strain bottom station 2nd flr.
Col. SA flex. strain top station 2nd flr.
Col. SA flex. strain bottom station 2nd flr.
Col. NA DCDT outside face 2nd floor
Col. NA DCDT inside face 2nd floor
Col. SA DCDT outside face 2nd floor
Col. SA DCDT inside face 2nd floor

| 100 | Bmflx-NAY-2 | Beam post-yield strain north end frame A |
| :--- | :--- | :--- |
| 101 | Bmflx-NBY-2 | Beam post-yield strain north end frame B |
| 102 | Bmflx-SAY-2 | Beam post-yield strain south end frame A |
| 103 | Bmflx-SMY-2 | Beam post-yield strain south end frame B |
| 104 | Bmflx-NO-2 | Beam flex. strain north end outside station |
| 105 | Bmflx-NI-2 | Beam flex. strain north end inside station |
| 106 | Bmflx-SI-2 | Beam flex. strain south end inside stacion |
| 107 | Bmflx-SO-2 | Beam flex. strain south end outside station |
| 108 | Bmrot-NOT-2 | Beam DCDT north outside station top face |
| 109 | Bmrot-NOB-2 | Beam DCDT north outside station bottom face |
| 110 | Bmrot-SOT-2 | Beam DCDT south outside station top face |
| 111 | Bmrot-SOB-2 | Beam DCDT south outside station bottom face |
| 112 | Jtrot-NT | Joint DCDT north end top side |
| 113 | Jtrot-NB | Joint DCDT north end bottom side |
| 114 | Jtrot-ST | Joint DCDT south end top side |
| 115 | Itrot-SB | Joint DCDT south end bottom side |
| 116 | Bmrot-NIT | Beam DCDT north inside station top face |
| 117 | Bmrot-NIB | Beam DCDT north inside station bottom face |
| 118 | Bmrot-SIT | Beam DCDT south inside station top face |
| 119 | Bmrot-SIB | Beam DCDT south inside station bottom face |
| 120 | Clflx-NAT-3 | Col. NA flex. strain top station 3rd flr. |
| 121 | Clflx-NAB-3 | Col. NA flex. strain bottom station 3rd flr. |
| 122 | Clflx-SAT-3 | Col. SA flex. strain top station 3rd flr. |
| 123 | Clflx-SAB-3 | Col. SA flex. strain bottom station 3rd flr. |
| 124 | Contact NA | Contact switch under column base NA |
| 125 | Contact NB | Contact switch under column base NB |
| 126 | Contact SA | Contact switch under column base SA |
| 127 | Contact SB | Contact switch under column base SB |

Table A-3 Data Channel Schedule for EC 200 and EC 1000

| CHANNEL | CHANNEL MNEMONIC | CHANNEL DESCRIPTION |
| :---: | :---: | :---: |
| 0 | Cmd H Acc | Command horizontal accl. signal |
| 1 | Cmd V Acc | Command vertical accl. signal |
| 2 | Cmd H Disp | Command horizontal displ. signal |
| 3 | Cmd V Disp | Command vertical displ. signal |
| 4 | Av H T Displ | Average horizontal table displ. |
| 5 | Av V T Displ | Average vertical table displ. |
| 6 | Av H T Acc | Average horizontal table accl. |
| 7 | Av V T Acc | Average vertical table accl. |
| 8 | Pitch | Angular accl. in putching mode |
| 9 | Roll | Angular accl. in rolling mode |
| 10 | Twist | Angular accl. in twisting mode |
| 11 | Force Hl | Force in horizontal actuator |
| 12 | Force H2 | Force in horizontal actuator |
| 13 | Force H3 | Force in horizontal actuator |
| 14 | Acc Hl | Individual table accelerometer (hor) |
| 15 | Acc H2 | Individual table accelerometer (hor) |
| 16 | Acc Vl | Individual table accelerometer (vert) |
| 17 | Acc V2 | Individual table accelerometer (vert) |
| 18 | Acc V3 | Individual table accelerometer (vert) |
| 19 | Acc V4 | Individual table accelerometer (vert) |
| 20 | Force VI | Force in vertical actuator |
| 21 | Force V2 | Force in vertical actuator |
| 22 | Force V3 | Force in vertical actuator |
| 23 | Force V4 | Force in vertical actuator |
| 24 | Displ V1 | Individual table vertical displ. |
| 25 | Displ V2 | Individual table vertical displ. |
| 26 | Displ V3 | Individual table vertical displ. |
| 27 | Displ V4 | Individual table vertical displ. |
| 28 | Displ Hl | Individual table horizontal displ. |
| 29 | Displ H2 | Individual table horizontal displ. |
| 30 | Displ H3 | Individual table horizontal displ. |
| 31 | blank |  |
| 32 | PS Force-1 | Force in passive stabilizer |
| 33 | PS Force-2 | Force in passive stabilizer |
| 34 | PS Force-3 | Force in passive stabilizer |
| 35 | PS Force-4 | Force in passive stabilizer |
| 36 | Flr Acc 1 | lst floor acceleration |
| 37 | Flx Acc 2 | 2nd floor acceleration |
| 38 | Flr Acc 3 | 3rd floor acceleration |
| 39 | blank |  |
| 40 | Flr Disp 1 | lst floor absolute displacement |
| 41 | Flr Disp 2 | 2nd floor absolute displacement |
| 42 | Flr Disp 3 | 3rd floor absolute displacement |
| 43 | Uplift NA | Vertical displacement of column base NA |
| 44 | Uplift NBO | Vertical displ. of outside column base NB |
| 45 | Uplift NBI | Vertical displ. of inside column base NB |


| 46 | Uplift SA |
| :---: | :---: |
| 47 | Uplift SB |
| 48 | blank |
| 49 | blank |
| 50 | blank |
| 51 | blank |
| 52 | Clstr-NAO-1 |
| 53 | C1str-NAI-1 |
| 54 | Clstr-SAO-1 |
| 55 | C1str-SAI-1 |
| 56 | Clrot-NAO-1 |
| 57 | Clrot-NAI-1 |
| 58 | Clrot-SAO-1 |
| 59 | Clrot-SAI-1 |
| 60 | Clflx-NAM-1 |
| 61 | C1flx-SAM-1 |
| 62 | Clflx-NBM-1 |
| 63 | Clflx-SBM-1 |
| 64 | Clstr-NBO-1 |
| 65 | Clstr-NBI-1 |
| 66 | Clstr-SBO-1 |
| 67 | Clstr-SBI-1 |
| 68 | Clrot-NBO-1 |
| 69 | Clrot-NBI-1 |
| 70 | Clrot-SBO-1 |
| 71 | Clrot-SBI-1 |
| 72 | Clflx-NAB-1 |
| 73 | Clflx-NAT-I |
| 74 | Clflx-SAB-1 |
| 75 | Clflx-SAT-1 |
| 76 | Bmflx-NO-1 |
| 77 | Bmflx-NI-1 |
| 78 | Bmflx-SI-1 |
| 79 | Bmflx-SO-1 |
| 80 | Clrot-NBO-2 |
| 81 | Clrot-NBI-2 |
| 82 | Clrot-SBO-2 |
| 83 | Clrot-SBI-2 |
| 84 | Clflx-NBT-2 |
| 85 | Clflx-NBB-2 |
| 86 | Clflx-SBT-2 |
| 87 | Clflx-SBB-2 |
| 88 | Clflx-NAY-2 |
| 89 | Clflx-NBY-2 |
| 90 | Clflx-SAY-2 |
| 91 | Clflx-SBY-2 |
| 92 | Clflx-NAT-2 |
| 93 | Clflx-NAB-2 |
| 94 | C1flx-SAT-2 |
| 95 | C1flx-SAB-2 |
| 96 | Clrot-NAO-2 |
| 97 | Clrot-NAI-2 |
| 98 | Clrot-SAO-2 |
| 99 | Clrot-SAI-2 |

Vertical displ. of column base SA
Vertical displ. of column base SB

Col. NA strain outside face lst floor
Col. NA strain inside face lst floor
Col. SA strain outside face lst floor
Col. SA strain inside face lst floor
Col. NA DCDT outside face lst floor
Col. NA DCDT inside face lst floor
Col. SA DCDT outside face lst floor
Col. SA DCDT inside face lst floor
Col. NA flex. strain @ midheight lst floor
Col. SA flex. strain @ midheight lst floor
Col. NB flex. strain @ midheight lst floor
Col. SB flex. strain @ midheight lst floor
Col. NB strain outside face lst floor
Col. NB strain inside face lst floor
Col. SB strain outside face lst floor
Col. SB strain inside face lst floor
Col. NB DCDT outside face lst floor
Col. NB DCDT inside face lst floor
Col. SB DCDT outside face lst floor
Col. SB DCDT inside face lst floor
Col. NA flex. strain bottom station lst flr.
Col. NA flex. strain top station lst flr.
Col. SA flex. strain bottom station lst fir. Col. SA flex. strain top station lst flr.
Beam flex. strain north end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Col. NB DCDT outside face 2nd floor
Col. NB DCDT inside face 2nd floor
Col. SB DCDT outside face 2nd floor
Col. SB DCDT inside face 2nd floor
Col. NB flex. strain top station 2nd flr.
Col. NB flex. strain bottom station 2nd flr.
Col. SB flex. strain top station $2 n d$ flr.
Col. SB flex. strain bottom station 2nd flr.
Col. NA post-yield strain 2nd floor
Col. NB post-yield strain 2nd floor
Col. SA post-yield strain 2nd floor
Col. SB post-yield strain 2nd floor
Col. NA flex. strain top station 2nd flr.
Col. NA flex. strain bottom station 2nd flr.
Col. SA flex. strain top station 2nd flr.
Col. SA flex. strain bottom station $2 n d$ flr.
Col. NA DCDT outside face 2nd floor
Col. NA DCDT inside face 2nd floor
Col. SA DCDT outside face 2nd floor
Col. SA DCDT inside face 2nd floor

| 100 | Bmflx-NAY-2 |
| :--- | :--- |
| 101 | Bmflx-NBY-2 |
| 102 | Bmflx-SAY-2 |
| 103 | Bmflx-SMY-2 |
| 104 | Bmflx-NO-2 |
| 105 | Bmflx-NI-2 |
| 106 | Bmflx-SI-2 |
| 107 | Bmflx-SO-2 |
| 108 | Bmrot-NOT-2 |
| 109 | Bmrot-NOB-2 |
| 110 | Bmrot-SOT-2 |
| 111 | Bmrot-SOB-2 |
| 112 | Jtrot-NT |
| 113 | Jtrot-NB |
| 114 | Jtrot-ST |
| 115 | Jtrot-SB |
| 116 | Bmrot-NIT |
| 117 | Bmrot-NIB |
| 118 | Bmrot-SIT |
| 119 | Bmrot-SIB |
| 120 | Clflx-NAT-3 |
| 121 | Clflx-NAB-3 |
| 122 | Clflx-SAT-3 |
| 123 | Clflx-SAB-3 |

Beam post-yield strain north end frame A
Beam post-yield strain north end frame $B$
Beam post-yield strain south end frame $A$
Beam post-yield strain south end frame B
Beam flex. strain north end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Beam DCDT north outside station top face
Beam DCDT north outside station bottom face
Beam DCDT south outside station top face
Beam DCDT south outside station bottom face Joint DCDT north end top side
Joint DCDT north end bottom side
Joint DCDT south end top side
Joint DCDT south end bottom side
Beam DCDT north inside station top face
Beam DCDT north inside station bottom face
Beam DCDT south inside station top face
Beam DCDT south inside station bottom face
Col. NA flex. strain top station $3 r d f l r$.
Col. NA flex. strain bottom station 3rd flr.
Col. SA flex. scrain top station $3 r d$ flr.
Col. SA flex. strain bottom station 3rd flr.

Table A-4 Data Channel Schedule for PAC 700

| CHANNEL | CHANNEL MNEMONIC | CHANNEL DESCRIPTION |
| :---: | :---: | :---: |
| 0 | Cond H Acc | Command horizontal accl. signal |
| 1 | Cmd V Acc | Command vertical accl. signal |
| 2 | Cmd H Disp | Command horizontal displ. signal |
| 3 | Cmd V Disp | Command vertical displ. signal |
| 4 | Av H T Displ | Average horizontal table displ. |
| 5 | Av V T Displ | Average vertical table displ. |
| 6 | Av H T Acc | Average horizontal table accl. |
| 7 | Av V T Acc | Average vertical table accl. |
| 8 | Pitch | Angular accl. in pitching mode |
| 9 | Roll | Angular accl. in rolling mode |
| 10 | Twist | Angular accl. in twisting mode |
| 11 | Force Hl | Force in horizontal actuator |
| 12 | Force H2 | Force in horizontal actuator |
| 13 | Force H3 | Force in horizontal actuator |
| 14 | Acc Hl | Individual table accelerometer (hor) |
| 15 | Acc H2 | Individual table accelerometer (hor) |
| 16 | Acc V1 | Individual table accelerometer (vert) |
| 17 | Acc V2 | Individual table accelerometer (vert) |
| 18 | Acc V3 | Individual table accelerometer (vert) |
| 19 | Acc V4 | Individual table accelerometer (vert) |
| 20 | Force V1 | Force in vertical actuator |
| 21 | Force V2 | Force in vertical actuator |
| 22 | Force V3 | Force in vertical actuator |
| 23 | Force V4 | Force in vertical actuator |
| 24 | Displ V1 | Individual table vertical displ. |
| 25 | Displ V2. | Individual table vertical displ. |
| 26 | Displ V3 | Individual table vertical displ. |
| 27 | Displ V4 | Individual table vertical displ. |
| 28 | Displ H1 | Individual table horizontal displ. |
| 29 | Displ H2 | Individual table horizontal displ. |
| 30 | Displ H3 | Individual table horizontal displ. |
| 31 | blank |  |
| 32 | PS Force-1 | Force in passive stabilizer |
| 33 | PS Force-2 | Force in passive stabilizer |
| 34 | PS Force-3 | Force in passive stabilizer |
| 35 | PS Force-4 | Force in passive stabilizer |
| 36 | Flr Acc 1 | lst floor acceleration |
| 37 | Flr Acc 2 | 2nd floor acceleration |
| 38 | Flr Acc 3 | 3rd floor acceleration |
| 39 | blank |  |
| 40 | Flr Disp 1 | lst floor absolute displacement |
| 41 | Flr Disp 2 | 2nd floor absolute displacement |
| 42 | Flr Disp 3 | 3rd floor absolute displacement |
| 43 | blank |  |
| 44 | Uplift NA | Vertical displacement column base NA |
| 45 | Uplift NB | Vertical displacement column base NB |

Uplift SA
Uplift SB
Clistr-NBO-L
Clstr-NBO-M
Clstr-NBO-U
Clstr-NBI-U
Clstr-NAO-1
Clstr-NAI-1
Clstr-SAO-1
Clstr-SAI-1
Clrot-NAO-1
Clrot-NAI-I
C1rot-SAO-1
Clrot-SAI-1
C1f1x-NAM-1
Clflx-SAM-1
Clstr-NBI-M
Clflx-SBM-1
Clstr-NBO-1
Clstr-NBI-1
Clstr-SBO-1
Clstr-SBI-I
Clrot-NBO-l
Clrot-NBI-I
Clrot-SBO-1
CLrot-SBI-1
Clflx-NAB-1
Clflx-NAT-1
Clflx-SAB-1
C1flx-SAT-1
Bmflx-NO-I
Bmflx-NI-1
Bnflx-SI-1
Bmflx-SO-1
Clrot-NBO-2
Clrot-NBI-2
Clrot-SBO-2
Clrot-SBI-2
Clflx-NBT-2
Clflx-NBB-2
Clflx-SBT-2
Clflx-SBB-2
Clflx-NAY-2
Clflx-NBY-2
Clflx-SAY-2
Clflx-SBY-2
Slflx-NAT-2
Clflx-NAB-2
CLflx-SAT-2
Clflx-SAB-2
Clrot-NAO-2
Clrot-NAI-2
Clrot-NAO-2
Clrot-SAI-2

Vertical displ. of column base SA
Vertical displ. of column base SB
Col. NB midheight strain out face lower station
Col. NB midheight strain out face mid station
Col. NB midheight strain out face upper station
Col. NB midheight strain in face upper station
Col. NA strain outside face lst floor
Col. NA strain inside face lst floor
Col. SA strain outside face lst floor
Col. SA strain inside face lst floor
Col. NA DCDT outside face lst floor
Col. NA DCDT inside face lst floor
Col. SA DCDT outside face lst floor
Col. SA DCDT inside face lst floor
Col. NA flex. strain @ midheight lst floor
Col. SA Flex. strain @ midheight lst floor
Col. NB midheight strain in face mid station
Col. SB flex. strain @ midheight lst floor
Col. NB strain outside face lst floor
Col. NB strain inside face lst floor
Col. SB strain outside face lst floor
Col. SB strain inside face lst floor
Col. NB DCDT outside face lst floor
Col. NB DCDT inside face lst floor
Col. SB DCDT outside face lst floor
Col. SB DCDT inside face lst floor
Col. NA flex. strain bottom station lst flr.
Col. NA flex. strain top stacion lst flr.
Col. SA flex. strain bottom station lst flr.
Col. SA flex. strain top station lst flr.
Beam flex. strain north end outside station
Beam flex. strain north end inside station
Beam flex. strain south end inside station
Beam flex. strain south end outside station
Col. NB DCDT outside face 2nd floor
Col. NB DCDT inside face 2nd floor
Col. SB DCDT outside face 2nd floor
Col. SB DCDT inside face 2nd floor
Col. NB flex. strain top station 2nd flr.
Col. NB flex. strain bottom station 2 nd flr.
Col. SB flex. strain top station 2 nd flr.
Col. SB flex. strain bottom station $2 n d$ flr.
Col. NA post-yield strain 2nd floor
Col. NB post-yeild strain 2nd floor
Col. SA post-yield strain 2nd floor
Col. SB post-yield strain 2nd floor
Col. NA flex. strain top station 2nd flr.
Col. NA flex. strain bottom station 2 nd flr.
Col. SA flex. strain top station $2 n d$ flr.
Col. SA flex. strain bottom station $2 n d$ flr.
Col. NA DCDT outside face 2nd floor
Col. NA DCDT inside face 2nd floor
Col. SA DCDT outside face 2nd floor
Col. SA DCDT inside face 2nd floor

| 100 | Bmflx-NAY-2 | Beam post-yield strain north end frame A |
| :--- | :--- | :--- |
| 101 | Bmflx-NBY-2 | Beam post-yield strain north end frame B |
| 102 | Bmflx-SAY-2 | Beam post-yield strain south end frame A |
| 103 | Bmflx-SMY-2 | Beam post-yield strain south end frame B |
| 104 | Bmflx-NO-2 | Beam flex. strain north end outside station |
| 105 | Bmflx-NI-2 | Beam flex. strain north end inside station |
| 106 | Bmflx-SI-2 | Beam flex. strain south end inside station |
| 107 | Bmflx-SO-2 | Beam flex. strain south end outside station |
| 108 | Bmrot-NOT-2 | Beam DCDT north outside station top face |
| 109 | Bmrot-NOB-2 | Beam DCDT north outside station bottom face |
| 110 | Bmrot-SOT-2 | Beam DCDT south outside station top face |
| 111 | Bmrot-SOB-2 | Beam DCDT south outside station bottom face |
| 112 | Jtrot-NT | Joint DCDT north end top side |
| 113 | Jtrot-NB | Joint DCDT north end bottom side |
| 114 | Jtrot-ST | Joint DCDT south end top side |
| 115 | Jtrot-SB | Jmrot-NIT |
| 116 | Bmrot-NIB | Beam DCDT north inside station top face |
| 117 | Bmrot-SIT | Beam DCDT north inside station bottom face |
| 118 | Bmrot-SIB | Beam DCDT south inside station top face |
| 119 | Clflx-NAT-3 | Beam DCDT south inside station bottom face |
| 120 | Clflx-NAB-3 | Col. NA flex. strain top station 3rd flr. |
| 121 | Clflx-SAT-3 | Col. SA flex. strain bottom station 3rd flr. |
| 122 | Clflx-SAB-3 | Col. SA flex. strain top station 3rd flr. |

## Appendix $B$

List of Dynamic Tests Performed

| SEQUENCE | FILE NAME | SIGNAL | SPANS | COMMENTS |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 200875.2 | EC | 100/000 | Phase I |
| 2 | 200875.3 | EC | 300/000 | " |
| 3 | 220875.2 | EC | 400/000 | " |
| 4 | 220875.2 | EC | 500/000 | " |
| 5 | 220875.6 | EC | 600/000 | " |
| 6 | 220875.8 | EC | 700/000 | " |
| 7 | 220875.10 | EC | 800/000 | " |
| 8 | 220875.12 | EC | 900/000 | " |
| 9 | 250875.2 | EC | 200/000 | EC 200 I in this report |
| 10 | 250875.4 | EC | 1000/000 | EC 1000 I in this report (filmed) |
| 11 | 250875.6 | EC | 200/200 | Phase I |
| 12 | 250875.8 | EC | 200/400 | " |
| 13 | 250875.10 | EC | 200/200 | " (V. Signal gain doubled) |
| 14 | 250875.12 | EC | 500/330 | , |
| 15 | 250875.14 | EC | 600/500 | " |
| 16 | 270875.2 | EC | 700/595 | " |
| 17 | 270875.4 | EC | 800/680 | " |
| 18 | 270875.6 | EC | 900/765 | " |
| 19 | 270875.8 | EC | 1000/850 | EC 1000/850 I in this report |
| 20 | 270875.10 | PAC | 100/000 | Phase I |
| 21 | 270875.12 | PAC | 200/000 | " |
| 22 | 270875.14 | PAC | 300/000 | " |
| 23 | 270875.16 | PAC | 350/000 | " |
| 24 | 270875.18 | PAC | 400/000 | PAC 400 I in this report |
| 25 | 280875.2 | EC | 200/000 | EC 200 in this report (Base Fixed) |
| 26 | 280875.4 | EC | 400/000 | Base Fixed |
| 27 | 280875.6 | EC | 600/000 | " |
| 28 | 280875.8 | EC | 800/000 | " " |
| 29 | 280875.10 | EC | 9001000 | " " |
| 30 | 280875.12 | EC | 1000/000 | EC 1000 in this report |
| 31 | 290875.2 | EC | 400/340 | Base Fixed |
| 32 | 290875.4 | EC | 800/680 | " |
| 33 | 290875.6 | EC | 1000/850 | " |
| 34 | 290875.8 | PAC | 100/000 | " " |
| 35 | 290875.10 | PAC | 200/000 | " " |
| 36 | 290875.12 | PAC | 300/000 | " " |
| 37 | 020975.2 | PAC | 400/000 | " (filmed) |
| 38 | 160175.1 | PAC | 400/000 | " " |
| 39 | 160175.2 | PAC | 600/000 | " " |
| 40 | 160175.3 | PAC | 700/000 | PAC 700 in this report (Base Fixed) |
| 41 | 200176.3 | PAC | 150/000 | Phase II |
| 42 | 200176.4 | PAC | 400/000 | " " |
| 43 | 200176.5 | PAC | 500/000 | " " |
| 44 | 200176.6 | PAC | 600/000 | " " |
| 45 | 200176.7 | PAC | 700/000 | PAC 700 II in this report |
| 46 | 210176.1 | EC | 100/000 | EC 100 II in this report |
| 47 | 210176.2 | EC | 200/000 | Phase II |
| 48 | 210176.3 | EC | 250/000 | " |
| 49 | 210176.4 | EC | 300/000 | EC 300 II in this report |
| 50 | 220176.1 | EC | 100/300 | Phase II |
| 51 | 220176.2 | EC | 200/500 |  |
| 52 | 220176.3 | EC | 300/675 | EC 300/675 in this report |

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