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A Semi-Empirical Analysis of Strong-Motion Peaks in Terms of Seismic Source, Propagation Path and Local Site Conditions

by

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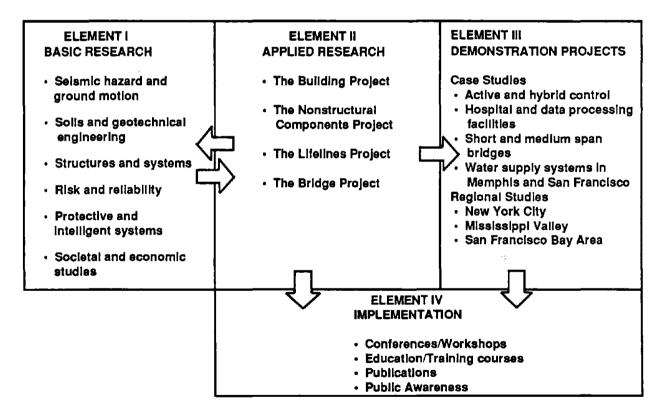
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PREFACE

The National Center for Earthquake Engineering Research (NCEER) was established to expand and disseminate knowledge about earthquakes, improve earthquake-resistant design, and implement seismic hazard mitigation procedures to minimize loss of lives and property. The emphasis is on structures in the eastern and central United States and lifelines throughout the country that are found in zones of low, moderate, and high seismicity.

NCEER's research and implementation plan in years six through ten (1991-1996) comprises four interlocked elements, as shown in the figure below. Element I, Basic Research, is carried out to support projects in the Applied Research area. Element II, Applied Research, is the major focus of work for years six through ten. Element III, Demonstration Projects, have been planned to support Applied Research projects, and will be either case studies or regional studies. Element IV, Implementation, will result from activity in the four Applied Research projects, and from Demonstration Projects.



Tasks in Element I, Basic Research, include research in seismic hazard and ground motion; soils and geotechnical engineering; structures and systems; risk and reliability; protective and intelligent systems; and societal and economic impact.

The soils and geotechnical engineering program constitutes one of the important areas of research in Element I, Basic Research. Major tasks are described as follows:

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- 1. Perform site response studies for code development.
- 2. Develop a better understanding of large lateral and vertical permanent ground deformations associated with liquefaction, and develop corresponding simplified engineering methods.
- 3. Continue U.S. Japan cooperative research in liquefaction, large ground deformation, and effects on buried pipelines.
- 4. Perform soil-structure interaction studies on soil-pile-structure interaction and bridge foundations and abutments, with the main focus on large deformations and the effect of ground failure on structures.
- 5. Study small earth dams and embankments.

The purpose of this report is to derive a semi-empirical expression for scaling strong-motion peaks in terms of seismic source, propagation path and local site conditions. Peak acceleration, peak velocity and peak displacement are derived by using strong-motion data obtained in Japan. In the derivation, earthquake magnitude (JMA) and hypocentral distance are selected as independent variables and the dummy variables are introduced to identify the amplification factor due to individual local site conditions. The resulting semi-empirical expressions for the peak acceleration, velocity and displacement are then compared with strong-motion data observed during three earthquakes in the U.S. and Mexico. In addition, two methods for predicting the amplification factor at a site are proposed. A simplified method for estimating maximum soil strain is also presented.

ABSTRACT

The purpose of this report is to derive a new type of semi-empirical expression for scaling strongmotion peaks in terms of seismic source, propagation path and local site conditions. Peak acceleration, peak velocity and peak displacement are analyzed in a similar fashion because they are interrelated. However emphasis is placed on the peak velocity which is a key ground motion parameter for lifeline earthquake engineering studies. With the help of seismic source theories, the semi-empirical model is derived using strong motions obtained in Japan. In the derivation, statistical considerations are used in the selection of the model itself and the model parameters. Earthquake magnitude M and hypocentral distance r are selected as independent variables and the dummy variables are introduced to identify the amplification factor due to individual local site conditions. The resulting semi-empirical expressions for the peak acceleration, velocity and displacement are then compared with strong-motion data observed during three earthquakes in the U.S. and Mexico. This comparison suggests that the proposed semi-empirical model is superior to existing models for strong ground motion peaks. The amplification factors for acceleration, velocity and displacement peaks obtained empirically by the model are found to be period-dependent and related to local soil conditions. In addition, two methods for predicting the amplification factor at a new site are proposed. Finally, a simplified method for estimating maximum soil strain is presented with the aid of the proposed semi-empirical expression for the peak velocity.

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SECTION 1 INTRODUCTION

In the assessment of earthquake hazard potential and seismic design of engineering structures, it is fundamental from both technological and economical points of view to have realistic estimates of future strong ground motions. Strong motions are generally complicated functions of time. However, in order to simplify design, they are often characterized by parameters such as peak values (acceleration, velocity and displacement), duration, period characteristics, spectral content, energy related parameters, etc. Although spectral content may give more accurate information about damage potential for various structures, the peak values are often employed as representative design parameters mainly because of their simplicity. However, controversy still remains concerning whether peak acceleration, peak velocity or peak displacement is more important to determine earthquake damage. In particular, it has increasingly become known that peak acceleration, which has been most widely used, is not necessarily adequate to assess the seismic performance of various types of structures[1]. In the field of lifeline earthquake engineering, for example, it is well recognized that peak particle velocity is directly related to ground strain which often controls the behavior of buried systems such as pipelines[2]. In addition, peak displacement may be more significant for the sloshing of tanks whose behavior is closely associated with longperiod motions. Thus various peak values of motions are crucial for different systems. Hence a unified assessment of peak acceleration, peak velocity and peak displacement is desirable and reasonable in light of the fact that the peak values are interrelated.

Strong earthquake motions are influenced by three main factors: seismic source, propagation path of waves and local site conditions. Therefore peak ground motion parameters should also be estimated in terms of the three factors. Recent developments in seismic source modeling has enhanced the possibility of theoretical estimates of the parameters, especially, in regions where recorded strong ground motions are limited[3]. However estimates of high frequency peak values are still not reliable because of the complexity of high-frequency motions[4]. In the past, empirical analysis of observed strong ground motion records has been the most common technique. Such analyses have been conducted by a number of researchers worldwide, presenting different expressions for peak values of motions. An extensive review of empirical prediction of strong ground motions has been recently given by Joyner and Boore[5], being preceded by another comprehensive review of Campbell[6] which focussed on strong-motion attenuation relations from a statistical standpoint. Some problems peculiar to empirical prediction of strong motions are pointed out in these reviews along with methods for overcoming such problems. The greatest obstacle for empirical analysis is the limited availability of observed strong motion data. This obstacle is not easily overcome because new strong motion records accumulate at a slow pace. In order to overcome the difficulties of purely empirical prediction methods, it is necessary to develop a semi-empirical technique which incorporates information from theoretical seismic source models.

The main objective of this report is to present a new type of semi-empirical expression for peak particle velocity in terms of seismic source, propagation path of waves and local site conditions. Although the peak particle velocity, which is needed for lifeline earthquake engineering studies, is the primary target of this paper, semi-empirical relations for peak acceleration and peak displacement are also presented.

As stated above, strong-motion records accumulated to date are limited not only in number but also in type. For example, in the United States near field records from moderate-size earthquakes are relatively available but there are few strong-motion records obtained during large magnitude earthquakes. Conversely in Japan there are fewer records in near field even though there is a comparative abundance of records in the far field for large earthquakes. This motivates a systematic empirical analysis of strong-motion records collected from several countries in an attempt to compensate for the lack of data. Such analyses have been carried out by several workers[7, 8]. Although the method gives a way to extensively apply the resulting empirical expression, it simultaneously creates ineffective separation for the effects of seismic source characteristics, propagation path and local soil conditions because these factors are considered to be remarkably site-specific. Herein we use strong-motion records obtained in Japan with emphasis on the dependence on the three factors, in particular, on local site conditions. We attempt to compensate for the lack of data in the near field with the aid of information from theoretical seismic source models. The resulting semi-empirical expression based solely on Japanese data is then compared with near field data observed in the U.S. and Mexico to confirm its validity.

As described in the reviews by Joyner and Boore[5] and by Campbell[6], many workers have investigated the influence of local site conditions on peak values of strong motions. Almost all of these investigations use a rough classification scheme such as soft soil, intermediate soil, hard soil and rock without detailed soil profiles specific to individual sites. However a number of actual earthquake damage experiences have taught us that the degree of earthquake damage vary markedly from site to site even within the "soft soil" area. This indicates the importance of individual differences in soil properties at each site. In this study we device an empirical technique to obtain site-specific amplification of peak acceleration, velocity and displacement based on the soil profile at each site.

The proposed semi-empirical technique also provides us with an estimate of peak values of strong motions on "seismic bed rock", which is bed rock for seismic response analysis of surface soils, as well as the site-specific amplification. Since the characteristics of the seismic bed rock are given explicitly, we can apply the results to estimates of several seismic parameters such as soil strain and liquafaction potential of sandy soils. In this report, as an example of the application, we present a simplified method for estimating soil strain, which is significant in soil dynamics and lifeline earthquake engineering, on the basis of the semi-empirical technique.

SECTION 2 MODEL FOR SEMI-EMPIRICAL ANALYSIS

2.1 Parameter Selection for the Model

According to statistical terminology, an empirical expression presents dependent variable as function of independent variables. In our case, peak acceleration, velocity and displacement respectively are the dependent variables. Regarding the independent variables, it is important to select them considering the physics of problem and their convenience in practical use. The dependent variables in our analysis are physically related to seismic source characteristics, propagation path of waves and local site conditions. Consequently we select the independent variables which represent each of these factors. With the aid of recently developed seismic source models, we could select various independent variables representing the seismic source characteristics and propagation path. However practical considerations confine us to select earthquake magnitude and hypocentral distance because they are the only source- and pathparameters available for most of our earthquake data. Hence for the convenience and simplicity of the model, herein we selected earthquake magnitude and hypocentral distance as the independent variables representing the effects of the seismic source and propagation path. We recognize that there are several ways to measure source-to-site distance. One such measure is the closest distance to fault rupture zone. However that distance is not necessarily available for small earthquakes. Herein we simply use hypocentral distance as a representative of source-to-site distance and derive attenuation in terms of that distance and a fault area parameter.

The technique used herein to characterize local site effects is somewhat unique. We define independent variables to represent local effects at each site as opposed to the rough classification schemes used in the past empirical analyses. That is, we introduce independent variables reflecting the effects specific to individual site conditions rather than grouping sites into a rough classification scheme. Kamiyama and Yanagisawa[9] has shown that the concept of dummy variables was effective for individualizing local site effects in their statistical analysis of response spectra. This concept is also used herein. A dummy variable is given a value of 1 when a phenomenon occurs and 0 when it does not occur[10]. Suppose now that strong motions were observed at a total of N observation sites during various earthquakes. Then we introduce a dummy variable S_i in order to express the phenomenon of obtaining strong motions at the i-th site during an earthquake so that $S_i=1$ when a record was obtained at the i-th site and $S_i=0$ when a record was not obtained. Such dummy variables are available for all the observation sites and by using these variables we can

quantify the local effects at individual observation sites. It should be emphasized herein that these dummy variables are treated in the same manner as the other independent variables, namely earthquake magnitude \mathbf{M} and hypocentral distance \mathbf{r} , in the formulation of the empirical model.

In summary, we start our semi-empirical analysis by assuming the following relationship between the dependent and independent variables.

$$V = f(M,r,S_1,S_2,---,S_j,---S_N)$$
(2.1)

where v is peak acceleration, velocity or displacement, M is the earthquake magnitude, r is the hypocentral distance, S, are the dummy variables related to local site effects, and N is the total number of observation sites.

2.2 Statistical Consideration for Earthquake Magnitude M and Hypocentral Distance r

The parameter selection stated in the preceding section is not unusual except for the introduction of the dummy variables but herein we attempt a unique modelling for these parameters using theoretical seismic source results. It is important to give statistical consideration to the parameters \mathbf{M} and \mathbf{r} because they are generally correlated and such correlation has generally been ignored in past studies. Many studies in the past similarly have selected \mathbf{M} and \mathbf{r} as their independent variables and performed a regression analysis on the data. The resulting relationship from such an analysis typically has the form

$$\log_{10} v = aM + b\log_{10} r + c \tag{2.2}$$

where a,b and c are regression coefficients.

Eq.(2.2) is a multiple regression model based on the assumption that the two independent variables \mathbf{M} and $\log \mathbf{r}$ are statistically independent of each other, namely, the correlation coefficient between them is zero. However the earthquake data in the past empirical analyses of strong motions show rather strong correlation between earthquake magnitude \mathbf{M} and hypocentral distance \mathbf{r} . For example strong motions for a small magnitude earthquake typically are observed only in a near distance field: i.e. when \mathbf{r} is small. Needless to say, an empirical analysis which disregards such a correlation gives less reliable results. Since the above correlation is often unavoidable, one

needs alternative techniques for overcoming such inherent difficulty as long as purely empirical analysis is pursued. Joyner and Boore[11] used the so-called two-stage regression procedure partly for this purpose while Fukushima and Tanaka[8] explained a controversial point about Eq.(2.2) with their own method. An explanation of the problem peculiar to Eq.(2.2) is as follows.

After variance analysis, the regression coefficients \mathbf{a} and \mathbf{b} of Eq.(2.2) can be shown to be

$$a = \frac{\sigma_{logU}}{2\sigma_{M}} \left(\frac{R_{M,logU} + R_{logr,logU}}{1 + R_{M,logr}} + \frac{R_{M,logU} - R_{logr,logU}}{1 - R_{M,logr}} \right)$$
(2.3)

$$b = \frac{\sigma_{logv}}{2\sigma_{logr}} \left(\frac{R_{M,logv} + R_{logr,logv}}{1 + R_{M,logr}} - \frac{R_{M,logv} - R_{logr,logv}}{1 - R_{M,logr}} \right)$$
(2.4)

where σ_{logv} , σ_{M} and σ_{logr} are the standard deviation for log v, M, and log r respectively and $\Pi_{M,logv}$, $\Pi_{logr,logv}$ and $\Pi_{M,logr}$ are the correlation coefficients between M and log v, etc. If M and log r are uncorrelated, that is, $\Pi_{M,logr} = 0$ which would be expected of independent variables, then the regression coefficients a and b become respectively

$$\mathbf{a} = \frac{\sigma_{\log U}}{\sigma_{M}} \mathbf{R}_{M,\log v}$$
(2.5)

$$b = \frac{\sigma_{\log U}}{\sigma_{\log r}} R_{\log r, \log U}$$
(2.6)

In Eqs. (2.5) and (2.6) the coefficients **a** and **b** are determined only by the correlation between the dependent variable and independent variables and the correlation between the independent variables taken as zero. On the other hand, if **M** and **r** are correlated, the values of **a** and **b** are affected by the degrees of the correlation. In particular the value of **b** is more strongly affected than the value of **a**. Fig.2-1 is a three dimensional scattergram of peak particle velocity in cm/sec, hypocentral distance in kilometer and earthquake magnitude for the strong ground motion data analyzed herein. Note that the correlation coefficient $\mathsf{R}_{M,\log r}$ is a positive value close to 1. Hence from Eq.(2.4) the regression coefficient **b** is strongly influenced by the correlation coefficient between these "independent" variables, while the regression coefficient **a** is less strongly influenced. The above discussion suggests that one needs to pay special attention to the attenuation coefficient **b**. Note

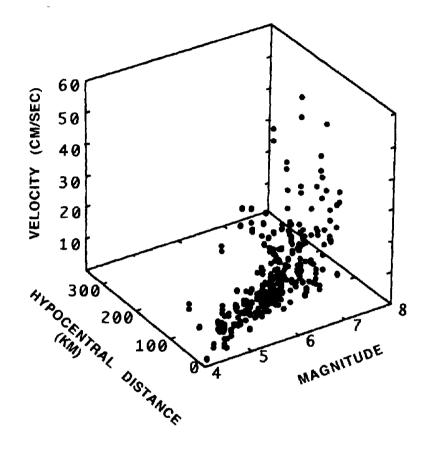


Fig.2-1 Scattergram of Peak Horizontal Velocity in cm/sec, Hypocentral Distance in kilometer and Magnitude for Japanese Earthquakes

for instance that Trifunac[12] employed a standard distance attenuation factor after Richter[13] while Joyner and Boore[11] relied on a geometrical attenuation coefficient derived from wave propagation theory. Herein we use an alternative consideration to avoid the difficulties inherent in the straightforward application of Eq.(2.2).

Although there are several ways of obtaining the attenuation coefficient **b**, we base our attenuation relation on the coefficient which was statistically derived in terms of earthquake magnitude and source-to-site distance using past earthquake data in and around Japan. We need the distance attenuation applied only to the far-field from the seismic source area as will be explained later. From these requirements we adopt the statistical attenuation coefficient of distance obtained by the Japan Meteorological Agency (JMA) which systematically determines the magnitude of earthquakes occurring in and around Japan. The agency has empirically derived the following expression for earthquake magnitude which uses maximum velocity in the vertical direction [14]:

$$M = \log_{10}A_{z} + 1.64\log_{10}\Delta + 0.22$$
 (2.7)

where Az is the maximum velocity in the vertical direction and Δ is the epicentral distance.

Eq.(2.7) was obtained statistically from the earthquake data which satisfy the conditions of the farfield. Accordingly, we employ the value of 1.64 as the distance attenuation coefficient for our semi-empirical model which targets horizontal motions in terms of hypocentral distance, assuming that there is little difference between vertical and horizontal motions and between epicentral and hypocentral distances. That is, the basic expression of our semi-empirical model is given by

$$\log_{10} v = aM - 1.64 \log_{10} r + c + f(S_1, S_2, - - -, S_N)$$
(2.8)

2.3 Theoretical Seismic Source Considerations

The hypocentral distance used in Eq.(2.8) is not necessarily the best choice to quantify source-tosite distance but it was selected purely because of its simplicity in practical use. In its current form Eq.(2.8) implicitly assumes the earthquake source to be a point. Actually, however, the earthquake source is not a point but consists of a fault with some extended area. Herein we make use of seismic source theory to resolve the problem.

According to recent studies of earthquake faults, earthquakes generally occur in a form of multipleshocks which are triggered by rupture of sub-faults associated with the so-called barriers or asperities [15]. In other words, actual earthquakes can be viewed as the result of multiple pointsources, scattered randomly over the entire fault plane. Since such multiple shocks may occur incoherently over the fault plane, one can assume that the peaks of strong motions on or near the fault area are independent of their locations. That is, peak ground motion on and near the fault would be relatively constant. Beyond the immediate fault area, peak motion decreases with distance due to geometric spreading and inelastic phenomena. The model assumed herein for the variation of peak ground motion with hypocentral distance is sketched in Fig.2-2. Hence the remaining problem is the determination of the constant level c and transition distance $\mathbf{r_t}$ in Fig.2-2.

Papageorgiou and Aki[16] discussed theoretically the peak values of strong motions in a fault area based on the specific barrier model. They suggested that the average cohesive force distributed on the cohesive zone of their specific barrier model and average slip **D** are determinant parameters for the peaks, and the peak acceleration $\mathbf{a_{max}}$ and peak velocity $\mathbf{v_{max}}$ in a fault area are approximately given by the following expressions from Ida[17].

$$a_{\max} \approx \frac{\sigma_c}{\mu} U_{\Gamma} 2 \frac{1}{D}$$
(2.9)

$$\cup_{\max} \approx \frac{\sigma_c}{\mu} \cup_{\Gamma}$$
(2.10)

where σ_c is an average cohesive stress in the cohesive zone,

D is the average slip in the cohesive zone , V_r is the rupture velocity and μ is the rigidity modulus.

Applying the specific barrier model to earthquakes in California, Chin and Aki[18] estimated empirically the values of σ_c and **D** which are associated with earthquake magnitude. The results show that the logarithmic values of both σ_c and **D** are linearly proportional to earthquake magnitude in a similar manner. This means from Eqs.(2.9) and (2.10) that peak acceleration in a fault zone is independent of earthquake magnitude while the peak of velocity is proportional to earthquake magnitude since V_r and μ are known to be independent of earthquake magnitude. Such magnitude saturation of peak acceleration has been discussed by other researchers along with debates over its validity. We employ this assumed characteristics of peak acceleration and peak velocity in a fault zone as an important starting point for our semi-empirical model. On the other hand, the fault extent, namely, the transition distance \mathbf{r}_t in Fig.2-2 is identical for both acceleration and velocity and herein assumed to be an increasing function of the earthquake magnitude. This is based on numerous empirical studies which show that earthquake fault length is an increasing function of earthquake magnitude. That is, our semi-empirical models are based on Fig.2-3(a) and

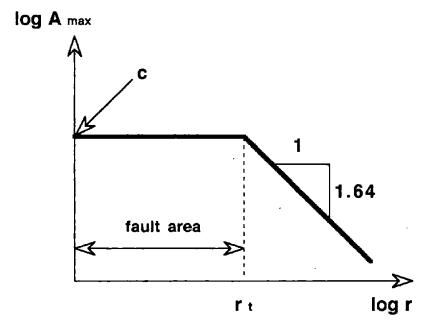


Fig.2-2 Proposed Model for Variation of Ground Motion Peak with Hypocentral Distance for a Fixed Magnitude

Fig.2-3(b) for peak acceleration and peak velocity respectively. Note that peak displacement is assumed to behave in a manner similar to peak velocity.

2.4 Empirical Determination of the Model Parameters

The parameters $\mathbf{c_{a, c_b}}$ and $\mathbf{r_t}$ in Fig.2-3(a) and Fig.2-3(b) are determined empirically in accordance with observed earthquake data. We require that the values of $\mathbf{r_t}$ be common for the acceleration, velocity and displacement models, since they represent earthquake fault size. Fig.2-3(a) and Fig.2-3(b) show clearly that it is easier to first determine $\mathbf{r_t}$ from the acceleration data and then apply the values to the more complicated velocity and displacement models whose peaks in the fault region depend on earthquake magnitude.

Up to this point, the acceleration model is a function of two parameters; \mathbf{r}_t which is a function of earthquake magnitude and \mathbf{c}_a which is a constant. Based upon the results of previous studies, we assume herein that $\log \mathbf{r}_t$ is linearly proportional to earthquake magnitude. A dummy variable concept, described by Kamiyama and Matsukawa[19], is then used to evaluate \mathbf{r}_t and \mathbf{c}_a . We use a trial and error procedure incorporating an arbitrary value \mathbf{r}_e . This yields a regression model:

$$\log_{10} a_{\max} = -1.64R_{0} + b_{1}R_{1} + b_{2}R_{2} + c_{a}$$
(2.11)

where

$$\mathsf{R}_{0} = \left\{ \begin{array}{c} 0 & (r \le r_{c}) \\ \log_{10} r - \log_{10} r_{c} & (r > r_{c}) \end{array} \right.$$
(2.12)

$$\mathsf{H}_{1} = \left\{ \begin{array}{cc} 0 & (r \le r_{c}) \\ 1 & (r > r_{c}) \end{array} \right.$$
(2.13)

$$\mathsf{H}_{2} = \left\{ \begin{array}{c} 0 & (r \le r_{c}) \\ \mathsf{M} & (r > r_{c}) \end{array} \right. \tag{2.14}$$

and b_1 , b_2 and c_a are regression coefficients. The parameter r_t becomes a function of earthquake magnitude M as

$$\Gamma_{t} = \Gamma_{c} \times 10^{\frac{b_{1} + b_{2}M}{1.64}}$$
(2.15)

As shown in Eq.(2.15), the target values \mathbf{r}_t and \mathbf{c}_a determined by the model of Eq.(2.11) are dependent on the selected value for the arbitrary variable \mathbf{r}_c . The final determination of \mathbf{r}_t and \mathbf{c}_a is

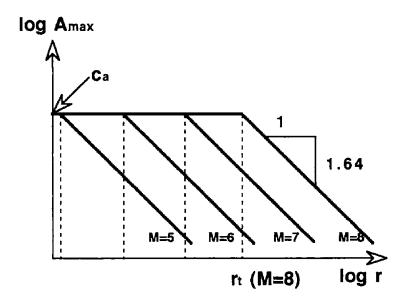


Fig.2-3(a) Proposed Model for Peak Horizontal Ground Acceleration as Function of Hypocentral Distance and Magnitude

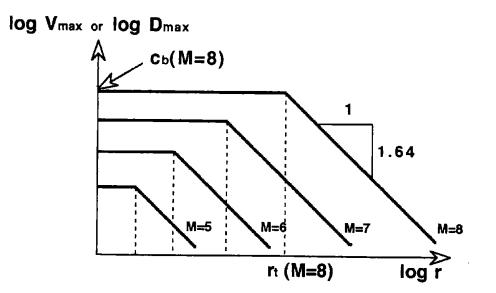


Fig.2-3(b)

Proposed Model for Peak Horizontal Ground Velocity and Displacement as Function Hypocentral Distance and Magnitude

based upon the goodness of fit between predicted and observed of a_{max} for various values of the arbitrary variable r_c , as well as empirical information on earthquake fault size.

The models for peak velocity and displacement in Fig.2-3(b) are constructed by adding another term controlling the magnitude-dependence of the peak in the fault zone and using the regression coefficients $\mathbf{b_1}$ and $\mathbf{b_2}$ in Eq.(2.11) of the acceleration model. Namely, they are given by

$$v_{\text{max}} = \alpha M - 1.64 R_0 + b_1 R_1 + b_2 R_2 + c_v$$
(2.16)

$$d_{max} = \delta M - 1.64R_{0} + b_{1}R_{1} + b_{2}R_{2} + c_{d}$$
(2.17)

where v_{max} is the peak velocity, d_{max} is the peak displacement, M is the earthquake magnitude, and α , δ , c_v and c_d are regression coefficients, and

$$\mathsf{R}_{0} = \left\{ \begin{array}{c} 0 & (r \le r_{c}) \\ \log_{10} r - \log_{10} r_{c} & (r > r_{c}) \end{array} \right.$$
(2.18)

$$\mathsf{H}_{1} = \left\{\begin{array}{cc} 0 & (r \le r_{c}) \\ 1 & (r > r_{c}) \end{array}\right. \tag{2.19}$$

$$H_{2} = \left\{ \begin{array}{c} 0 & (r \le r_{c}) \\ M & (r > r_{c}) \end{array} \right.$$
(2.20)

In Eqs.(2.16) and (2.17), only the coefficients α , δ , c_v and c_d are determined empirically by regression analysis, since the values b_1 and b_2 are determined from the acceleration model.

2.5 Local Site Effects

Eqs.(2.11), (2.16) and (2.17) are semi-empirical models which consists of seismic source characteristics and propagation path. As described in the foregoing section, an additional term is needed to reflect the individual local site effects. In other words, we express the independent variables S_1, S_2, \dots, S_N in Eq.(2.1) as a concrete functional form so that they represent local soil conditions at each observation site.

Referring to response spectra of strong motions, Kamiyama and Yanagisawa[9] discussed in detail such independent variables in connection with the theory of earthquake response of surface soils and concluded that a linear equation of such variables is sufficient to obtain amplification factors compatible with the frequency response function physically caused by local surface soils. The peak values of strong motions which is our target, of course, differ from response spectra in character. Particularly, the linear transmission of frequency response functions which is satisfied in the case of spectra can not be directly applied to the peak values of motions. However, it would be almost impossible to constitute a semi-empirical model which exactly reflects such characteristics peculiar to the peak values of motions because of its complexity. As the first approximation, we herein employ the following model, similar to that for response spectra, in order to empirically obtain the effect of individual local sites:

Peak acceleration,

$$\log_{10} a_{max} = -1.64R_0 + b_1R_1 + b_2R_2 + c_0 + A_1S_1 + A_2S_2 + - - - + A_{N-1}S_{N-1}$$
(2.21)

Peak velocity and displacement,

$$\log_{10} v_{\text{max}} = \alpha M - 1.64R_0 + b_1 R_1 + b_2 R_2 + c_0 + B_1 S_1 + B_2 S_2 + - - - + B_{N-1} S_{N-1}$$
(2.22)

$$\log_{10}d_{max} = \delta M - 1.64R_0 + b_1R_1 + b_2R_2 + c_d + D_1S_1 + D_2S_2 + - - + D_{N-1}S_{N-1}$$
(2.23)

where A_i , B_i and D_i (i=1-N-1) are regression coefficients.

As seen in Eqs.(2.21) to (2.23), the N-1 independent dummy variables S_j are assigned to all observation sites except a reference site. This technique avoids statistical difficulties and obtains local site amplification factors of the peak values with respect to a reference site. When a reference site is selected to satisfy the conditions of the seismic bed rock, the amplification factors thus obtained have physical meaning. An explanation of such amplification factors is described fully in Kamiyama and Yanagisawa[9]. The amplification factors **AMP**_i for the peak acceleration, velocity and displacement at the i-th site against a reference site are given by

$$AMP_{i} = 10^{0}$$
, 10^{0} or 10^{0} (2.24)

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SECTION 3

EARTHQUAKE DATA USED FOR THE SEMI-EMPIRICAL ANALYSIS

In this study we focus our attention on earthquake data obtained in Japan. Strong motion observation in Japan dates back to early 1960's when the so-called SMAC accelerograph was developed. Since then numerous useful records have been obtained. Systematic strong-motion observation networks have been established throughout the country by both the Ministries of Transport and Construction. Since our empirical analysis places an emphasis on local site effects as well as the effects of earthquake source and propagation path, it would be desirable to use earthquake data collected as systematically as possible. In other words, we need earthquake data observed at several specific sites during many earthquakes with various magnitudes for the purpose of efficiently separating seismic source, propagation path and local site condition effects. In addition, we need free field accelerograms to avoid unnecessary effects such as soil-structure interaction. A total of 33 observation sites were selected from the Transport and Construction Ministries networks meeting these requirements. Horizontal accelerograms at these sites obtained during a total of 82 earthquakes constitute the data set for our semi-empirical analysis[20, 21]. The total number of the accelerograms is 357. These accelerograms are listed in Table A-1 along with the observation sites, earthquake magnitude, focal depth, epicentral distance, hypocentral distance and peak ground motion parameters. The observation sites are illustrated together with the epicenters of the earthquakes in Fig.3-1. Many of these accelerograms and observation sites are identical to those used in the statistical analysis of response spectra by Kamiyama and Yanagisawa[9], but 7 observation sites were newly added along with new accelerograms. In these accelerograms, two different horizontal components simultaneously obtained at one site for an earthquake are included as an individual to enrich the data set. The earthquake magnitude listed in Table A-1 is the JMA earthquake magnitude determined by the Japan Meteorological Agency. The agency has been determining the magnitude of earthquakes occurring in and around Japan based on various methods [1,14]. These methods are applied depending on earthquake conditions. For example, the magnitude of earthquakes with the focal depth less than or equal to 60 km is determined using the following formula:

$$M = \frac{1}{2} \log_{10} (A_N^2 + A_E^2) + 1.73 \log_{10} \Delta - 0.83$$
 (3-1)

where M is the magnitude, A_N and A_E are the maximum amplitudes of north and east components in micron respectively, and Δ is the epicentral distance in km. Those ground amplitudes are of seismometers with periods of about 5 seconds and of waves shorter than 5 seconds.

• OBSERVATION SITE

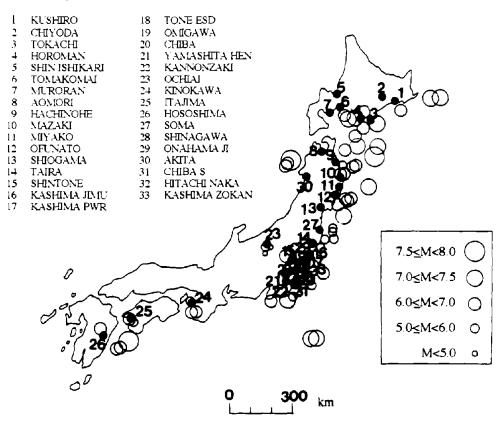


Fig.3-1 Obseravtion Sites and Epicenters

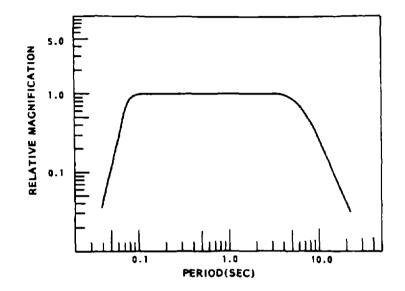
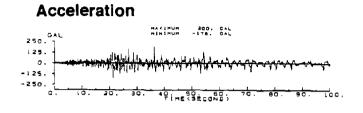
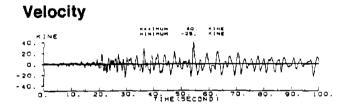


Fig.3-2 Band Pass Filter Used for Corrected Acceleration, Velocity and Displacement Records

The accelerograms in Table A-1 were obtained mostly by the SMAC types of accelerographs. The original accelerograms include several errors resulting from the frequency characteristics of the instrument, digitization processing, etc. We removed the errors by performing a correction according to the frequency characteristics of each instrument as well as by using a band path filter. Based on such correction and filtering, corrected acceleration, velocity and displacement records were numerically obtained together with their peak values which are shown in Table A-1. The frequency characteristics of the band-path filter used herein is shown in Fig. 3-2. This filter, proposed by Iai et al. [22] as a standard filter for accelerograms obtained by the Transport Ministry, has a flat part ranging from about 0.09 sec. to about 4.2 sec. This period band should be emphasized when the peak velocity and displacement are examined. An example of corrected acceleration record and the corresponding velocity and displacement time histories obtained by the processing technique are presented in Fig. 3-3.

Figs. 3-4 and 3-5 describe the range of the independent variables, magnitude and hypocentral distance for the data used in developing the semi-empirical relations. Although the distribution of magnitude is fairly uniform, the hypocentral distance data concentrates in the 50 to 150 kilometer range. Figs. 3-6 through 3-8 are histograms for the dependent variables; peak horizontal acceleration, velocity and displacement. The interrelationship between the independent variables, earthquake magnitude and hypocentral distance is shown in the scattergram in Fig. 3-9. This figure, which presents information similar to that in Fig. 2-1, shows strong positive correlation between the two variables. Hence the data set used herein has some limits from a statistical point of view. These limits provided motivation for the semi-empirical model as stated in the foregoing section.





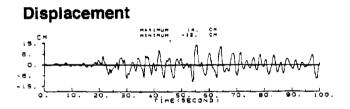


Fig.3-3 Corrected Acceleration Time History, and Corresponding Velocity and Displacement Records for May 16, 1968 Event at Aomori

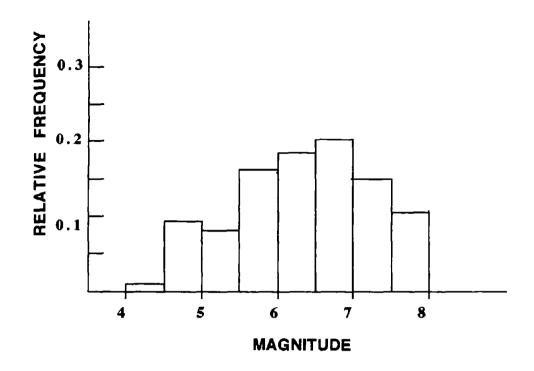


Fig.3-4 Histogram of Earthquake Magnitude Used in the Analysis

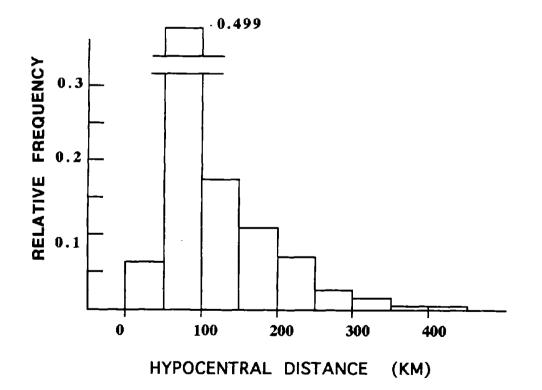


Fig.3-5 Histogram of Hypocentral Distance Used in the Analysis

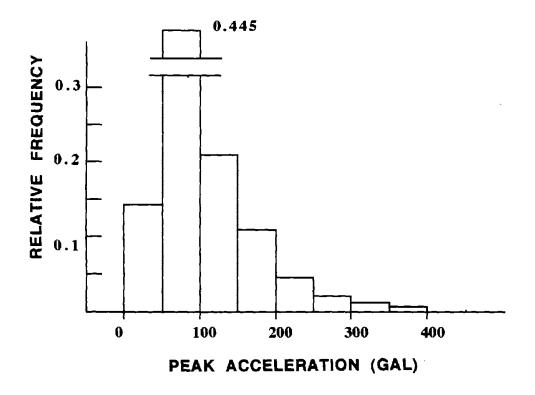
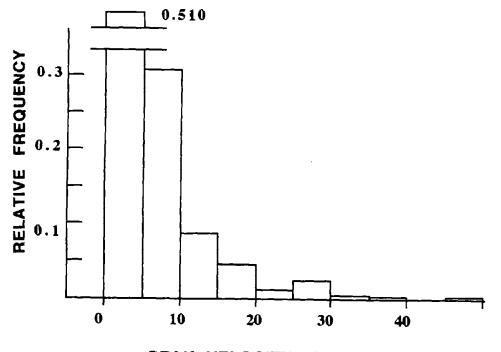


Fig.3-6 Histogram of Peak Horizontal Ground Acceleration Used in the Analysis



PEAK VELOCITY (CM/SEC)

Fig.3-7 Histogram of Peak Horizontal Ground Velocity Used in the Analysis

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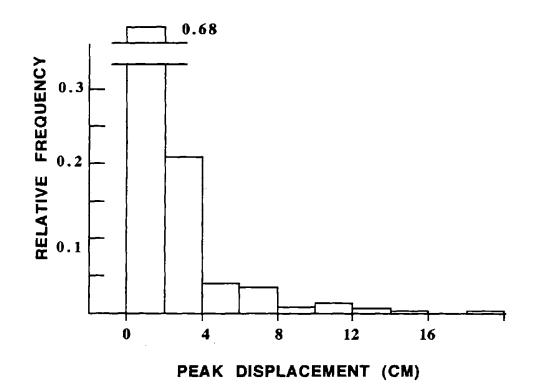


Fig.3-8 Histogram of Peak Horizontal Ground Displacement Used in the Analysis

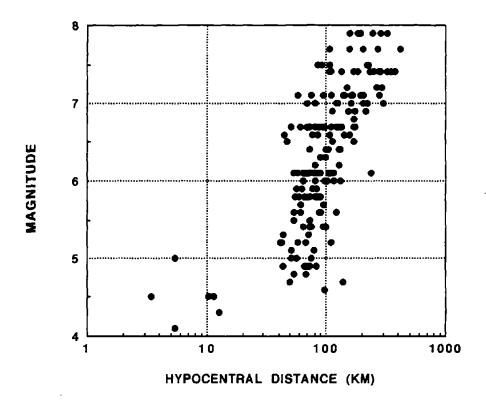


Fig.3-9 Scattergram of Magnitude and Hypocentral Distance in Data

SECTION 4

REGRESSSION ANALYSIS OF THE SEMI-EMPRICAL MODELS

The regression analyses of the semi-empirical models of Eqs.(2.21) through (2.23) were carried out by using the data in Table A-1 with the help of the least-square technique. As mentioned previously, our regression analyses consist of two phases. In the first phase the appropriate values of \mathbf{r}_t are determined using the acceleration model. In the second phase the velocity and displacement models are established using the results for \mathbf{r}_t from the acceleration model. In addition, we need to assign a reference site whose dummy variable S₁ is not given and virtually set to be zero in Eqs.(2.21) through (2.23). Such a reference site, of course, can be picked arbitrarily from any of the observation sites. However our previous studies reveal that it is most desirable to assign a site where there exists outcrop hard enough to satisfy the condition of the seismic bed rock for the other sites. Although the selection of the seismic bed rock might vary according to the dominant frequency content, we initially selected the same reference site for acceleration, velocity and displacement motions on the condition that the definition of the seismic bed rock should be examined based on the resulting amplification factors at each observation site. Herein we choose OFUNATO labelled 12 in Fig. 3-1 as the reference site in accordance with the discussion in Kamiyama and Yanagisawa[9]. The OFUNATO site is situated at a rock outcrop having shear wave velocity in the 1 to 2 km/sec range.

4.1 Regression Analysis for the Acceleration Model

Table 4-I shows the summary of the regression coefficients analyzed for trial values of \mathbf{r}_c in the acceleration model. In Table 4-I, the results of regression coefficients \mathbf{A}_1 , \mathbf{A}_2 ,..., \mathbf{A}_{N-1} are omitted because the main purpose of the table is to determine the most appropriate values for \mathbf{b}_1 and \mathbf{b}_2 based on the variations of \mathbf{r}_t in terms of earthquake magnitude. For this reason, the variations of \mathbf{r}_t estimated by Eq.(2.15) are indicated in Table 4-I in stead of the results of \mathbf{A}_i . Note that the multiple correlation coefficient \mathbf{R} , which means the goodness of fit, is largest for $\mathbf{r}_c < 10$ km. Table 4-I also shows that the variation of \mathbf{r}_t depends on \mathbf{r}_c but it becomes relatively stable for $\mathbf{r}_c < 5.3$ km. As stated in the preceding section, \mathbf{r}_t is closely related to a characteristic length of the earthquake fault. Hence in addition to the goodness of fit and stability of the \mathbf{r}_t parameter, the choice of \mathbf{b}_1 and \mathbf{b}_2 is also based on the consistency of \mathbf{r}_t with empirical estimates of fault length. Although the value of \mathbf{r}_t is somewhat arbitrarily related to fault length, it is reasonable to interpret \mathbf{r}_t as nearly equivalent to the radius of the fault which is assumed herein to be circular. The fault area of earthquake has been investigated by many workers. Typically it is related to earthquake magnitude. For instance, Sato[23] derived the following expression.

		r _c (km)															
<u> </u>		50	40	30	20	10	8.0	6.0	5.8	5.6	5.4	5.3	5.2	5.1	4.8	4.6	4.4
	61	-1.766	-1.760	-1.555	-1.266	-0.767	-0.608	-0.403	-0.379	-0.354	-0.819	-1.164	1.150	-1.137	-1.093	-1.063	-1.031
	b2	0.324	0.333	0.333	0.333	0 332	0 332	0.332	0.332	0.332	0.345	0.358	0.358	0.358	0.358	0.358	0.358
	c _a	2.126	2.228	2.228	2.228	2.228	2.228	2.283	2.228	2.228	2.637	2.910	2.910	2.910	2.910	2.910	2.910
	R	0 845	0.854	0.862	0.876	0.896	0.900	0.905	0.906	0.906	0.894	0.890	0.890	0.890	0.891	0.891	0.891
	S	0.228	0.227	0.227	0.227	0.228	0.228	0.228	0.228	0.228	0.243	0.247	0.247	0.247	0.247	0.247	0.247
r _t (km)	M=5	41.3	35.1	35.1	35.1	35.1	35.1	35.1	35.1	35.1	19.3	12.8	12.8	12.8	12.8	12.8	12.8
	M=6	65.1	56 .0	56.0	56 .0	56.0	<i>5</i> 6.0	<i>5</i> 6.0	56 .0	56.0	31.3	21.2	21.2	21.2	21.2	21.2	21.2
	М=7	102.6	89.4	89.4	89.4	89.3	89.3	89.3	89.3	89.3	50.8	35.0	34.9	34.9	35.0	35.0	35.0
	M=8	161.7	142.8	142.8	142.8	142.5	142.5	142.5	142.5	142.5	82.5	57.9	57.8	57.8	57.9	57.9	57.9
	İ											*					}

 $b_1,\,b_2$ and $c_a{=}regression$ coefficients $\;$, $M{=}$ earthquake magnitude R=multiple correlation coefficient S= standard deviation

$$\Gamma_{t} = \Gamma_{0} \times 10^{\frac{b_{1} + b_{2}M}{1.64}}$$

$$S = 10^{M-4.07}$$
 (4.1)

where S is the area of the fault in square kilometers.

Table 4-II shows the variation of fault radius obtained from Eq.(4.1) assuming a circular fault. A comparison between Table 4-I and Table 4-II indicates that values of \mathbf{r}_c less than or equal to 5.3 km yield the best match between \mathbf{r}_t and empirical estimates of the fault radius by others, even though there is some difference between them. The difference may be due to the possibility that \mathbf{r}_t is related to a characteristic length of a rectangular fault rather than the radius of circular fault. Accordingly, we choose $\mathbf{b_1} = -1.164$, $\mathbf{b_2} = 0.358$ and $\mathbf{c_a} = 2.91$, which were obtained by setting $\mathbf{r}_c = 5.3$ km, for the acceleration model of Eq.(2.21). The regression coefficients $\mathbf{A_1}$, $\mathbf{A_2}$, ---, $\mathbf{A_{N-1}}$ in Eq.(2.21), which were obtained based on $\mathbf{r_c} = 5.3$, are shown in Table 4-III. In Table 4-III, $\mathbf{A_i}$ (i=1~N-1) are given for each observation site except the reference site. Hence the eventual semi-empirical expression for the peak horizontal ground acceleration is

$$a_{mex}(i,M,r) = 10^{2.910} 10^{4} (r \le 10^{0.014+0.218M})$$
 (4.2)

$$a_{max}(i,M,r) = 10 \xrightarrow{2.933 + 0.358 \text{ M} - 1.64 \log_{10} r} \times 10^{6} (r > 10^{0.014 + 0.218 \text{ M}})$$
(4.3)

where A_i are given in Table 4-III on the condition that $A_i = 0$ for the reference site.

4.2 Regression Analysis for the Velocity and Displacement Models

The regression coefficients of the velocity and displacement models of Eqs.(2.22) and (2.23) are presented in Table 4-IV, based on $b_1 = -1.164$ and $b_2 = 0.358$ from the acceleration model. Hence the semi-empirical expressions for the peak horizontal ground velocity and displacement are

$$v_{\text{mex}}(i,M,r) = 10^{0.535 + 0.153 \text{ M}} \times 10^{-8} (r \le 10^{0.014 + 0.218 \text{ M}})$$
 (4.4)

$$v_{mex}(i, M, r) = 10^{0.558 + 0.511 M - 1.64 \log_{10} r} \times 10^{0.014 + 0.218 M})$$
 (4.5)

$$d_{mex}(i,M,r) = 10^{-0.522 + 0.236 M} \times 10^{0} \qquad (r \le 10^{0.014 + 0.218M}) \tag{4.6}$$

Table 4-II Fault Radius Based on the Sato[23] Relation for Fault Area

MAGNITUDE M	RADIUS (KM)		
5	1.65		
6	5.21		
7	16.46		
8	52.05		

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NO	SITE NAME	Δ.
<u> </u>		Aj
1	KUSHIRO	0.196
2	CHIYODA	0.127
3	TOKACHI	0.110
4	HOROMAN	-0.202
5	SHIN ISHIKARI	0.396
6	TOMAKOMAI	0.129
7	MURORAN	0.271
8	AOMORI	0.090
9	HACHINOHE	-0.098
10	MAZAKI	-0.092
11	MIYAKO	0.194
12	OFUNATO	
_13	SHIOGAMA	0.193
14	TAIRA	0.046
15	SHINTONE	-0.092
16	KASHIMA JIMU	-0.002
17	KASHIMA PWR	-0.047
18	TONE ESD	-0.139
19	OMIGAWA	-0.104
20	CHIBA	0.021
21	YAMASHITA HEN	-0.123
22	KANNONZAKI	0.129
23	OCHIAI C	-0.768
24	KINOKAWA	-0.771
25	ITAJIMA	0.349
26	HOSOSHIMA	-0.113
27	SOMA	0.239
28	SHINAGAWA	0.032
29	ONAHAMA JI	0.076
30	AKITA	-0.037
31	CHIBA S	-0.032
32	HITACHI NAKA	0.135
33	KASHIMA ZOKAN	0.016

Table 4-III Site Amplification Coefficients for Acceleration Model

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Table 4-IVRegression Coefficients, Site Amplification Coefficients, Multiple
Coefficient and Standard Deviation for Velocity and Displacement
models

REGRES	SSION COEFFICIENTS	MAX. VEL	MAX. DIS
	α, δ	0.153	0.236
	b1	-1.164	-1.164
	b2	0.358	0.358
	c _v , c _d	0.535	-0.522
	B _i ,D _i		
1	TKUSHIRO	0.431	0.345
2	CHIYODA	0.296	0.294
3	TOKACHI	0.127	0.151
4	HOROMAN	-0.295	-0.302
5	SHIN ISHIKARI	0.748	0.662
6	TOMAKOMAI	0.255	0.241
7	MURORAN	0.313	0.213
8	AOMORI	0.488	0.494
9	HACHINOHE	0.131	0.176
10	MAZAKI	0.039	0.409
11	MIYAKO	0.033	-0.034
12	OFUNATO		
13	SHIOGAMA	0.465	0.161
14	TAIRA	0.310	0.282
15	SHINTONE	0.298	0.204
16	KASHIMA JIMU	0.364	0.239
17	KASHIMA PWR	0.294	0.089
18	TONE ESD	0.346	0.568
19	OMIGAWA	0.357	0.587
20	CHIBA	0.314	0.432
21	YAMASHITA HEN	0.116	0.051
22	KANNONZAKI	0.179	0.067
23	OCHIAI C	-0.534	-0.641
24	KINOKAWA	-0.568	-0.650
25	ПАЛМА	0.356	0.207
26	HOSOSHIMA	0.051	-0.118
27	SOMA	0.110	-0.088
28	SHINAGAWA	0.358	0.136
29	ONAHAMA JI	0.112	0.099
30	AKITA	0.227	0.248
31	CHIBA S	0.342	0.176
32	HITACHI NAKA	0.053	-0.496
33	KASHIMA ZOKAN	0.133	0.050
	CORRELATION COEFFICI.	0.770	0.848
STAND	ARD DEVIATION	0.264	0.272

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$$d_{max}(i,M,r) = 10 \qquad (r > 10^{0.014 + 0.218 M}) \qquad (4.7)$$

where B_i and D_i are given in Table 4-4 on the condition that $B_i = 0$ or $D_i = 0$ for the reference site.

Finally, adequacy of the semi-empirical model was checked statistically by inspection of the residuals plots. The residual, which is simply the ratio of the observed to predicted velocities from Eqs.(4.4) and (4.5), were plotted as functions of each independent variable. The residual plots for peak velocity are illustrated in Figs. 4-1 through 4-3. The fact that no particular trend was observed in the residual plots implies that the proposed semi-empirical model is adequate from a statistical point of view.

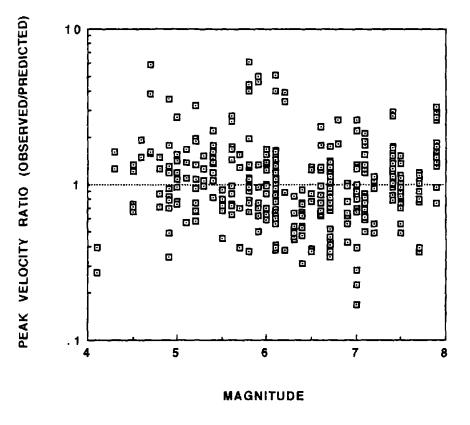


Fig.4-1 Residual Plots of Peak Velocity versus Magnitude

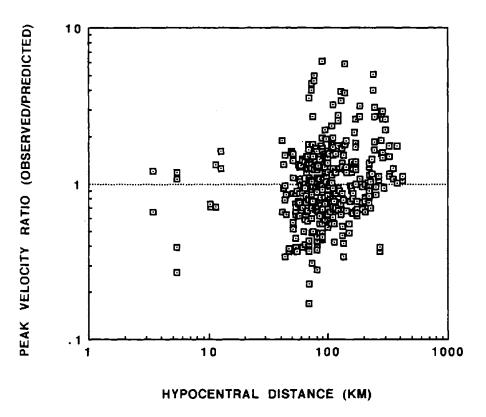


Fig.4-2 Residual Plots of Peak Velocity versus Hypocentral Distance

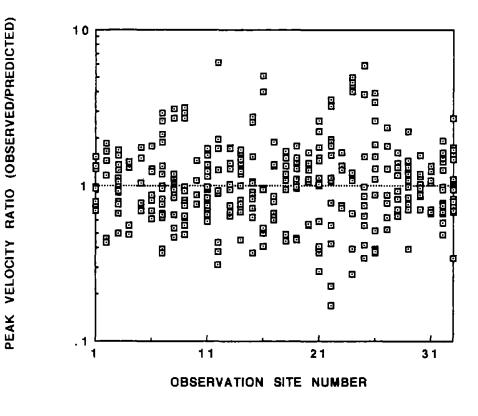


Fig.4-3 Residual Plots of Peak Velocity versus Observation Site Number

SECTION 5 AMPLIFICATION DUE TO LOCAL SITE CONDITIONS

The proposed semi-empirical model provides local soil amplification factors for the peak values at each site. In this section, the amplification factors are discussed in terms of the soil conditions at the sites as well as the frequency content of the motions.

5.1 Amplification Factors for the Peak Acceleration, Velocity and Displacement

As implied in Eq.(4.2) to Eq.(4.7), the amplification factor at each site is given by 10^{6} , 10^{8} or $10^{0^{-1}}$ with respect to the reference site which was selected as a candidate to satisfy the condition of the seismic bed rock. Table 5-I lists the amplification factors obtained for the peak acceleration, velocity and displacement at each site along with their mean values and standard deviations. In Table 5-I, the amplification factor at the reference site (OFUNATO) is set to be one by definition. We can see from Table 5-I that the amplification factors vary markedly from site to site probably reflecting the difference in the soil conditions. In addition, the variations of the amplification factors differ depending on the type of motion characteristics: acceleration, velocity and displacement. This significant variation in amplification factors indicates the importance of taking individual site conditions into consideration, as contrasted with the rough classification schemes of soil conditions employed in the past studies. The averages and standard deviations in Table 5-I also reveal that the peak acceleration is less dependent on local site conditions than the peak velocity and displacement. Correlations between the amplification factors for the peak acceleration, velocity and displacement are shown in Figs.5-1 to 5-3. Note that, as shown in Figs.5-1 and 5-2, the amplification factor for peak acceleration is not well correlated with the amplification factors for peak velocity and peak displacement, while Fig.5-3 shows that the amplification factor for peak velocity is fairly well correlated with that for peak displacement. This suggests that there is a difference in the mechanism and frequency content between acceleration motion and the other motions such as velocity and displacement when they are amplified through surface soils.

It is noted in Table 5-I that the two observation sites, OCHIAI C and KINOKAWA give very small amplification factors for the peak acceleration, peak velocity and peak displacement. These amplification factors are considerably smaller than that for the reference site(OFUNATO). The recording conditions of strong motions at these two sites are the most likely reason. Note that almost all the strong-motion records observed at the two sites are lacking in a part of the main-

		AMPLIFICATION FACTORS				
NO	SITE NAME	ACC	VEL	DIS		
1	KUSHIRO	1.57	2.70	2.21		
2	CHIYODA	1.30	1.98	1.97		
3	TOKACHI	1.29	1.34	1.42		
4	HOROMAN	0.63	0.51	0.50		
5	SHIN ISHIKARI	2.49	5.59	4.67		
6	TOMAKOMAI	1.35	1.80	1.74		
7	MURORAN	1.86	2.05	1.63		
8	AOMORI	1.23	3.08	3.12		
9	HACHINOHE	0.80	1.35	1.50		
10	MAZAKI	0.81	1.09	2.56		
11	MIYAKO	1.56	1.08	0.92		
12	OFUNATO	1.00	1.00	1.00		
13	SHIOGAMA	1.56	2.91	1.45		
14	TAIRA	1.11	2.04	1.91		
15	SHINTONE	0.81	1.99	1.60		
16	КАЅНІМА ЛМИ	1.00	2.31	1.73		
17	KASHIMA PWR	0.89	1.97	1.23		
18	TONE ESD	0.73	2.27	3.70		
19	OMIGAWA	0.79	2.27	3.86		
20	CHIBA	1.05	2.06	2.70		
21	YAMASHITA HEN	0.76	1.45	1.12		
22	KANNONZAKI	1.35	1.51	1.17		
23	OCHIAI C	0.17	0.29	0.23		
24	KINOKAWA	0.17	0.28	0.22		
25	ІТАЛМА	2.23	2.27	1.61		
26	HOSOSHIMA	0.74	1.12	0.76		
27	SOMA	1.73	1.29	0.82		
28	SHINAGAWA	1.08	2.28	1.37		
29	ONAHAMA JI	1.19	1.31	1.26		
30	AKITA	0.92	1.68	1.77		
31	CHIBA S	0.93	2.20	1.50		
32	HITACHI NAKA	1.36	1.13	0.32		
33	KASHIMA ZOKAN	1.03	1.36	1.12		
	AVERAGE	1.136	1.805	1.657		
	SD	0.497	0.965	1.027		

Table 5-I Amplification Factors for Peak Acceleration, Peak Velocity and PeakDisplacement

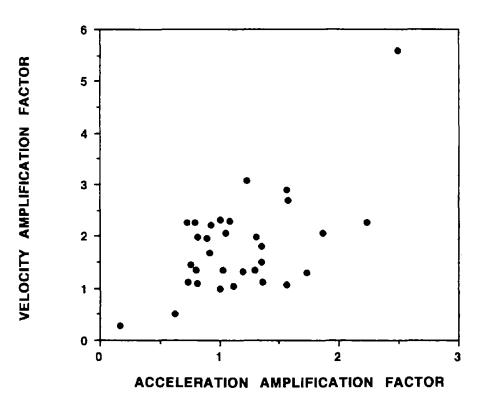


Fig.5-1 Scattergram of Velocity and Acceleration Amplification Factors (Correlation Coefficient =0.635)

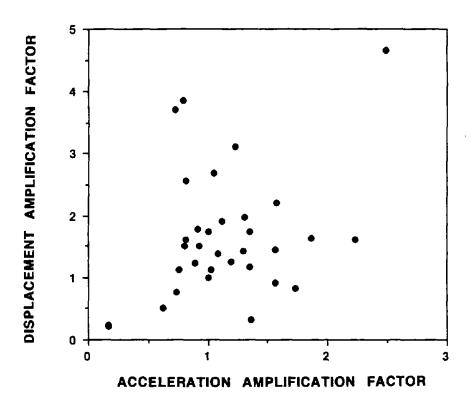


Fig.5-2 Scattergram of Displacement and Acceleration Amplification Factors (Correlation Coefficient=0.329)

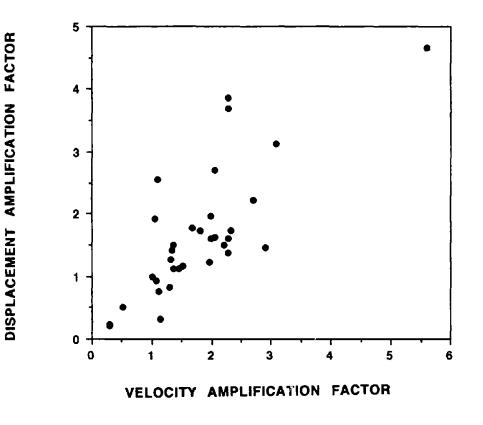


Fig.5-3 Scattergram of Displacement and Velocity Amplification Factors (Correlation Coefficient=0.767)

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motions as well as first-motions, resulting from miss triggering of the recording instruments. Incompleteness of the recordings is considered to affect the peak values of acceleration, velocity and displacement at both sites because they were obtained through band-pass filtering as well as the instrument correction. Hence the two sites of OCHIAI C and KINOKAWA are exempted from the discussion of amplification in terms of frequency and local soils which will be described in a later section.

The same reference site was selected for all three motions; acceleration, velocity and displacement. At the same time, OFUNATO was assigned to the reference site as a candidate satisfying the condition of the seismic bed rock for the other sites. However, the difference in the variations of amplification factors for the three motions indicates that the reference site should be selected differently depending on the motion characteristics. In fact, the absolute values of the amplification factors in Table 5-I differ for the peak acceleration, velocity and displacement. Note that, for example, the average amplification factor for the peak acceleration is only slightly larger than 1.0 which is the amplification factor for the reference site, whereas the average amplification factors for the peak velocity and displacement are roughly 1.8 and 1.7 respectively. Since local soil conditions generally amplify the motions incident to the seismic bed rock, the amplification factor is expected to be greater than 1.0 when the reference site is properly selected to satisfy the condition of the seismic bed rock. In the cases of the peak velocity and displacement in Table 5-I, the amplification factors at each site are almost always greater than 1.0, implying a relatively proper selection as seismic bed rock site. The amplification factors for the peak acceleration, on the other hand, show many values less than 1.0. This means that the reference site is improperly selected to satisfy the condition of seismic bed rock for the peak acceleration.

A possible way for obtaining more proper amplification factors is to redo the regression analysis for the peak acceleration by selecting another reference site. However this requires iteration because the selection of the reference site is not the only parameter controlling the amplification factors. Considering that we have obtained meaningful amplification factors as relative values even though they are controversial in the absolute values, we herein renovate the amplification factors in Table 5-I so as to meet the proper condition of amplification. That is, the amplification factors in Table 5-I are multiplied by a value to correspond to the definition of amplification factor with respect to the seismic bed rock. Though the inverse of the least amplification factor in each motion peak in Table 5-I can be a candidate for the multiplier, such simple multiplication gives little reasonable amplification factor because the least amplification factor involves more statistical errors. Herein we make an alternative attempt by renovating the amplification factors in Table 5-I so that the average value minus the one standard error is 1.0. For example, 1/(1.136-0.497) is multiplied to the amplification factors in the case of the peak acceleration. This is an attempt to make the amplification factors approach proper values with respect to the seismic bed rock while avoiding the statistical errors. The amplification factors for the peak velocity and peak displacement were also renovated in a similar manner. The final amplification factors for each motion peak are listed in Table 5-II. Note in Table 5-II that the definition of the seismic bed rock differs for peak acceleration, velocity and displacement as a result of the renovations. For example, HOROMAN, OFUNATO and HOROMAN correspond to the seismic bed rock site for the peak acceleration, velocity and displacement respectively because their renovated amplification factors are nearly equal to 1.0. A geological survey shows a rock outcrop at the HOROMAN site as well as OFUNATO. Table 5-II shows that the absolute values for the renovated amplification factors are always greater than 1.0 except at a few sites including OCHIAI C and KINOKAWA. Table 5-II also indicates that the average values of the renovated amplification factors increase proportionally from acceleration to displacement. This is consistent with a theoretical explanation from amplification phenomena through surface soils. That is, the amplification factor for velocity motion is theoretically expected to be greater than that for acceleration motion because velocity motion is generally affected by deeper soil layers with its dominant amplitude components in longer periods than acceleration motion. Similarly the amplification for displacement motion is greater than that for velocity motion.

As a result of the renovations for the amplification factors, the overall semi-empirical expressions of Eqs.(4.2) to (4.7) are modified so that the motion peaks on the seismic bed rock are diminished to offset the increased amplification factors resulting from the renovations. Denoting the renovated amplification factors at the i-th site in Table 5-II as $AMP_i(a)$, $AMP_i(v)$ and $AMP_i(d)$ for the peak acceleration, peak velocity and peak displacement respectively, we rewrite the final semi-empirical expressions as follows:

(peak acceleration)

$$= 518.9 \times \text{AMP}_{(6)} \qquad (\Gamma \le 10^{0.014 + 0.218M}) \qquad (5.1)$$

$$a_{max}(i,M,r) = 547.6 \times 10^{0.358 \text{ M}-1.64 \log_{10} r} \times \text{AMP}_{i}(a) (r > 10^{0.014+0.218M})$$
 (5.2)

		RENOVATED	AMPLIFICATION			
		FACTORS				
NO	SITE NAME	ACC	VEL	DIS		
1	KUSHIRO	2.46	3.21	3.51		
2	CHIYODA	2.03	2.36	3.13		
3	TOKACHI	2.02	1.60	2.25		
4	HOROMAN	0.99	0.61	0.79		
5	SHIN ISHIKARI	3.90	6.66	7.41		
6	TOMAKOMAI	2.11	2.14	2.76		
7	MURORAN	2.91	2.44	2.59		
8	AOMORI	1.92	3.67	4.95		
9	HACHINOHE	1.25	1.61	2.38		
10	MAZAKI	1.27	1.30	4.06		
11	MIYAKO	2.44	1.29	1.46		
12	OFUNATO	1.56	1.19	1.59		
13	SHIOGAMA	2.44	3.46	2.30		
14	TAIRA	1.74	2.43	3.03		
15	SHINTONE	1.27	2.37	2.54		
16	KASHIMA JIMU	1.56	2.75	2.75		
17	KASHIMA PWR	1.39	2.35	1.95		
18	TONE ESD	1.14	2.70	5.87		
19	OMIGAWA	1.24	2.70	6.13		
20	CHIBA	1.64	2.45	4.29		
21	YAMASHITA HEN	1.19	1.73	1.78		
22	KANNONZAKI	2.11	1.80	1.86		
23	OCHIAI C	0.27	0.35	0.37		
24	KINOKAWA	0.27	0.33	0.35		
25	ПАЛМА	3.49	2.70	2.56		
26	HOSOSHIMA	1.16	1.33	1.21		
27	SOMA_	2.71	1.54	1.30		
28	SHINAGAWA	1.69	2.71	2.17		
29	ОЛАНАМА Л	1.86	1.56	2.00		
30	AKITA	1.44	2.00	2.81		
31	CHIBA S	1.46	2.62	2.38		
32	HITACHI NAKA	2.13	1.35	0.51		
33	KASHIMA ZOKAN	1.61	1.62	1.78		
	- AVERAGE	1.778	2.149	2.630		
	- SD	0.778	1.149	1.630		

Table 5-IIRenovated Amplification Factors for Peak Acceleration, Peak
Velocity and Peak Displacement

(peak velocity)

 $v_{\text{mex}}(i, M, r) = (1.805 - 0.965) \times 10^{0.535 + 0.153 \text{ M}} \times \text{AMP}_{i}(v) \quad (r \le 10^{0.014 + 0.218 \text{ M}})$ $= 2.879 \times 10^{0.153 \text{ M}} \times \text{AMP}_{i}(v) \qquad (r \le 10^{0.014 + 0.218 \text{ M}}) \qquad (5.3)$

$$v_{max}(i,M,r) = 3.036 \times 10^{0.511M - 1.64 \log_{10} r} \times AMP_i(v) (r > 10^{0.014 + 0.218 M}) (5.4)$$

(peak displacement)

$$d_{max}(i,M,r) = (1.657 - 1.027) \times 10^{-0.522 + 0.236 M} \times AMP_{i}(d) \quad (r \le 10^{0.014 + 0.218 M})$$
$$= 0.189 \times 10^{0.236 M} \times AMP_{i}(d) \quad (r \le 10^{0.014 + 0.218 M}) \quad (5.5)$$

$$d_{max}(i,M,r) = 0.200 \times 10^{0.594 M-1.64 \log_{10} r} \times AMP_i(d)$$
 (r> $10^{0.014+0.218M}$) (5.6)

where a_{max} is peak acceleration(cm/sec²), v_{max} is peak velocity(cm/sec), d_{max} is peak displacement(cm), i is the number for identifying the observation site, M is the earthquake magnitude, and r is the hypocentral distance(km).

5.2 Relation Between the Amplification Factors and Frequency Content

The above discussion reveals that local site effects for peak acceleration are different than those for peak velocity and displacement. This suggests that the dominant frequency component in acceleration, velocity and displacement motions plays a significant role in determining the amplification factor for peak values. In relation to the frequency content in strong motions, Kamiyama and Yanagisawa[9] derived amplification factors for response spectra using almost same strong-motion records and observation sites as in the present study. These spectral amplifications were presented in a frequency-dependent form. Hence they allow us to examine the frequency effect on the amplification factors for the peak values. Figs.5-4 to 5-8 show spectral amplification factors obtained by Kamiyama and Yanagisawa[9] at sites used in this study. No simple relation exists between the peak value and the spectral characteristics of ground motions

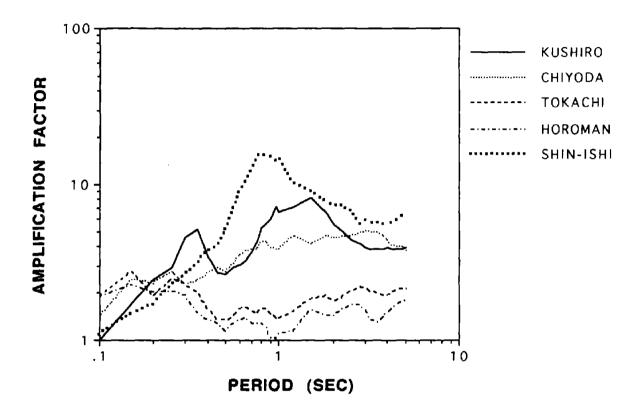


Fig.5-4 Response Spectra Amplification Factors for 5 Sites(Kushiro, Chiyoda, Tokachi, Horoman and Shin Ishikari) in Japan (after Kamiyama and Yanagisawa[9])

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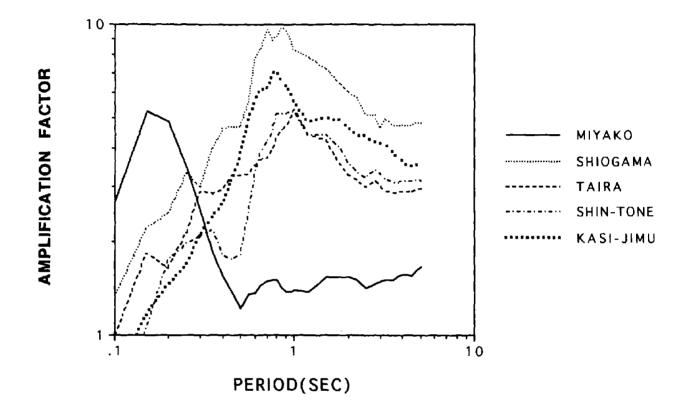


Fig.5-5 Response Spectra Amplification Factors for 5 Sites(Miyako, Shiogama, Taira, Shintone and Kashima Jimu) in Japan (after Kamiyama and Yanagisawa[9])

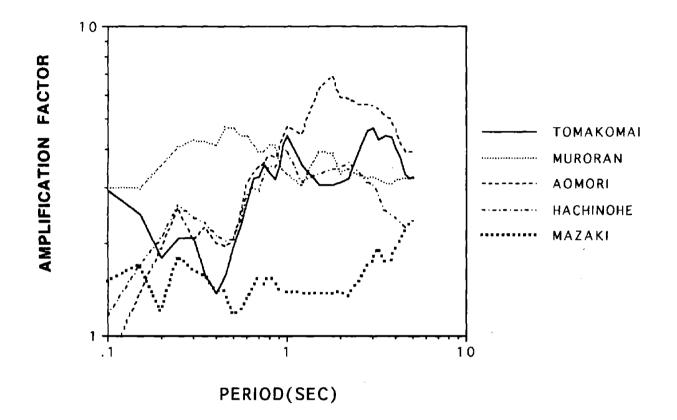


Fig.5-6 Response Spectra Amplification Factors for 5 Sites(Tomakomai, Muroran, Aomori, Hachinohe and Mazaki) in Japan (after Kamiyama and Yanagisawa[9])

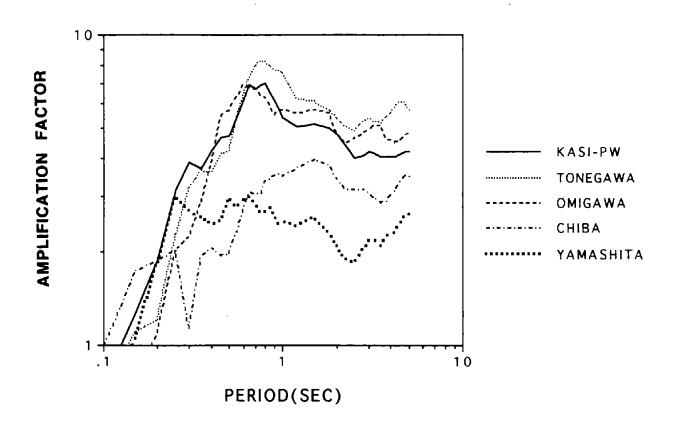


Fig.5-7 Response Spectra Amplification Factors for 5 Sites(Kashima PWR, Tone ESD,Omigawa, Chiba and Yamashita HEN) in Japan (after Kamiyama and Yanagisawa[9])

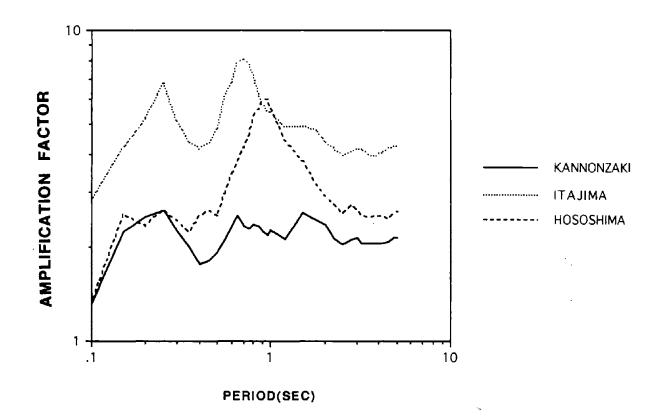


Fig.5-8 Response Spectra Amplification Factors for 3 Sites(Kannonzaki, Itajima and Hososhima) in Japan (after Kamiyama and Yanagisawa[9])

because the peak value results from quite complicated processes. Herein we integrate the amplification spectra in Figs. 5-4 to 5-8 within a period band to investigate how the amplification factors for the peak acceleration, velocity and displacement are associated with their frequency content.

Since short period motions likely control peak acceleration and large period motions likely control peak velocity, band-pass filters were applied to the amplification spectra. The integrated spectral value **SP**_i then becomes

$$SP_{i} = \frac{1}{4.9} \int_{0.1}^{5.0} A_{i}(T) R(T) dT$$
(5.7)

where $A_i(T)$ are the period dependent spectral amplifications shown in Figs. 5-4 to 5-8, R(T) is a high frequency pass filter for peak acceleration and a low frequency pass filter for peak velocity and T is period.

After a number of trials, the high frequency pass filter in Fig.5-9 was chosen for peak acceleration while the low frequency pass filter in Fig.5-10 was chosen for peak velocity. Figs. 5-11 and 5-12 show the correlations between the amplification factors for peak acceleration and peak velocity at some sites in Table 5-II and their corresponding integrated spectral values by Eq.(5.7). The displacement case is omitted herein because of its close correlation with velocity. We can see from Figs.5-9 through 5-12 that the peak acceleration is determined principally by spectral amplifications in periods leass than about 0.3 sec while the peak velocity is determined by periods greater than about 1.0 sec. This means that local soils respond differently to acceleration and velocity motions with a definite period-dependence. It is clear from this result that a site composed of extremely soft soil with high viscosity is expected to show only small peak acceleration in spite of showing a large peak velocity because such a site has spectral amplification with long-period dominance as well as high attenuation in the short period domain. Consider, for example, the SHIN ISHIKATRI site which will be shown later to consist of a deep layer of relatively soft soils. As shown in Fig.5-4, the spectral amplification at this site is large for periods greater than about 1.0 seconds but comparatively small for periods less than 0.3 seconds. As a consequence the amplification factors for the peak velocity and displacement in Table 5-II are about double the peak acceleration amplification factor. Conversely, a site with a thin superficial layer over hard rock tends to exhibit large peak and small peak, respectively, in acceleration and velocity because of the short-period dominance of its spectral amplification. An example is the Miyako site which

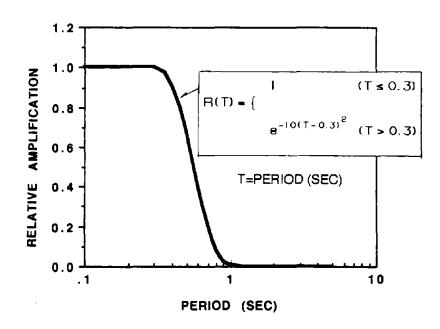


Fig.5-9 High Frequency Pass Filter Applied to Spectra Amplification for Comparison with Peak Acceleration

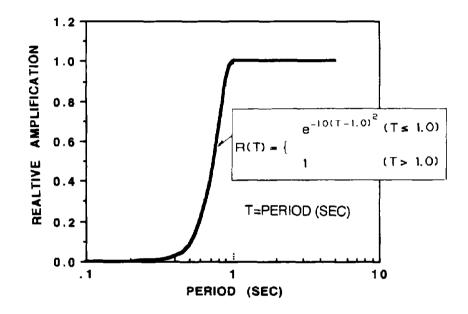


Fig.5-10 Low Frequency Pass Filter Applied to Spectral Amplification for Comparison with Peak Velocity

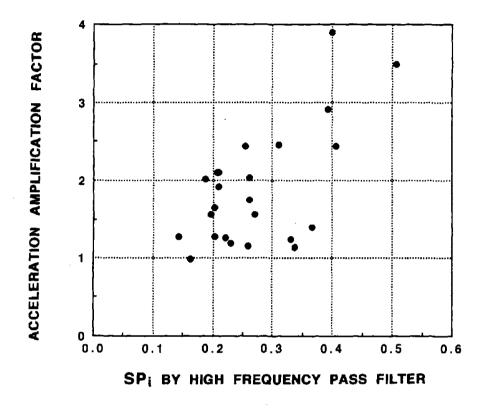


Fig.5-11 Scattergram for Peak Acceleration Amplification Factor and Integrated Spectral Value from Eq.(5.7) Using High Frequency Pass Filter

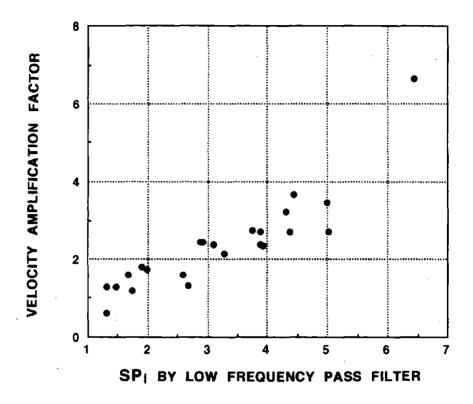


Fig.5-12 Scattergram for Peak Velocity Amplification Factor and Integrated Spectral Value from Eq.(5.7) Using Low Frequency Pass Filter

corresponds to a relatively thin layer over rock. The Miyako site has large spectral amplifications for periods less than 0.3 seconds, as shown in Fig.5-5. The spectral amplification at Miyako is consistent with the small amplification factor for the peak velocity and the relatively large amplification factor for the peak acceleration in Table 5-II.

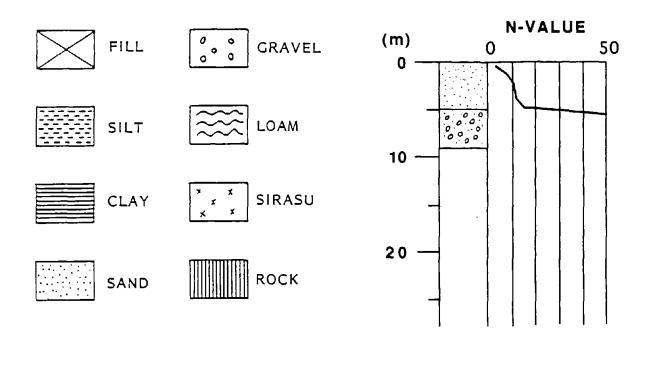
The above examples suggest that peak velocity can be a candidate parameter more responsible for earthquake damage than peak acceleration which has been regarded as the foremost parameter controlling earthquake damage, because damages were overwhelmingly caused at soft soil sites rather than at firm soil sites in the past earthquakes. In addition, since amplification factors for peak motion are related to different frequency ranges, a two parameter characterization of a site may be appropriate. That is, the seismic hazard for a given site may be given in terms of estimates for both peak acceleration and peak velocity. Peak acceleration would control the design of short period structures while peak velocity would control large period structures.

The difference in the period-dependent amplification between peak acceleration and peak velocity also explains the discrepancy of the reference site noted in the preceding section. The OFUNATO site is not appropriate as a reference site for the peak acceleration while it is justified for peak velocity. Although the OFUNATO site was initially selected as the common reference site because of its outcropping of hard slate, there is a possibility that its surface part has been weathered so as to give a high amplification in short periods. Hence it might fail to offer a proper reference site corresponding to the seismic bed rock for the other sites in the case of the peak acceleration.

5.3 Relation Between the Amplification Factors and the Local Soil Conditions

It is obvious from the foregoing discussion that the peak motion amplification factors are closely related to the corresponding local soil conditions. In order to apply our semi-empirical model to an arbitrary site not included in the present empirical analysis, it is necessary to be able to predict the amplification factors at a site from its local soil conditions. Herein we examine the detailed relation between the empirical amplifications and soil conditions, and propose two methods; one qualitative and the other quantitative for estimating an amplification factor at a new site having soil information.

Soil profiles are available for some of the observation sites in Fig. 3-1. Figs. 5-13(a) to 5-13(q) show the soil profiles at these sites which consist of the soil formation and the standard penetration test results meeting the Japanese Industrial Standard, namely, the N-value. These soil profiles

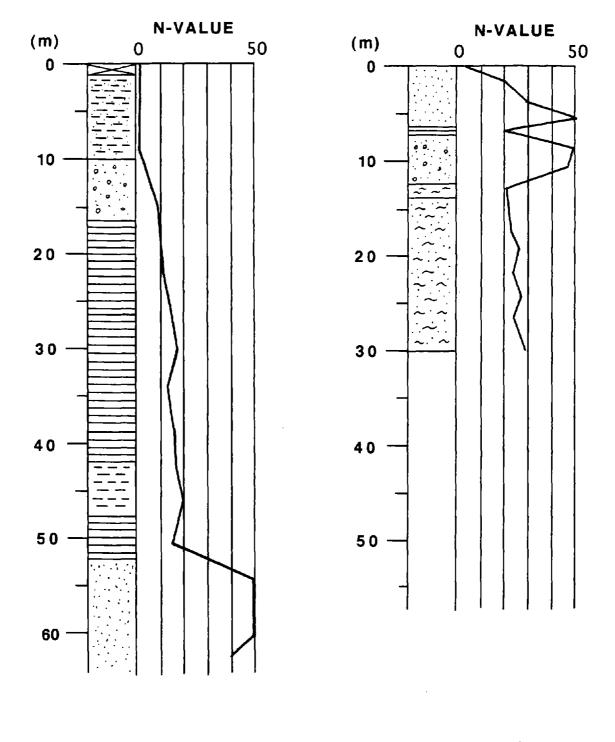


LEGEND

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(a) Tokachi

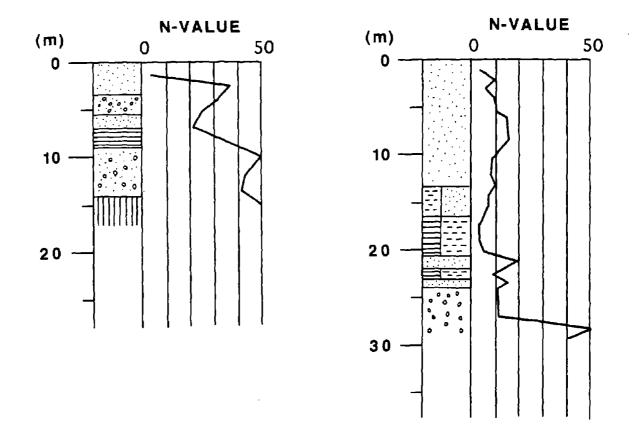




(b) Shin Ishikari

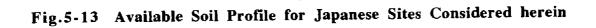
(c) Tomakomai

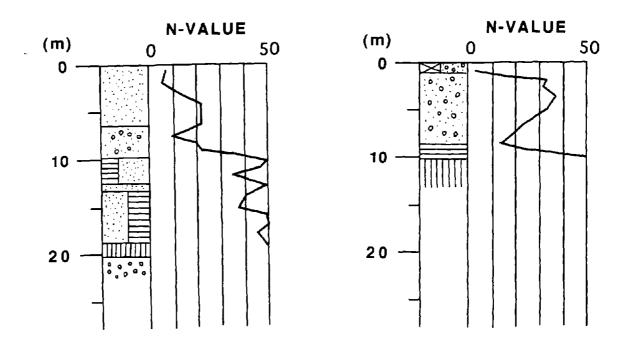




(d) Muroran

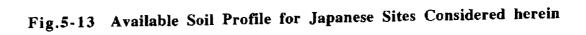
(e) Aomori

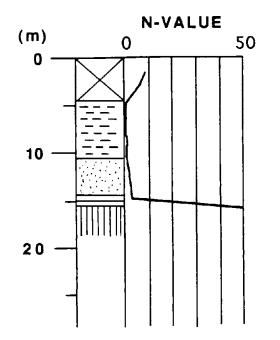


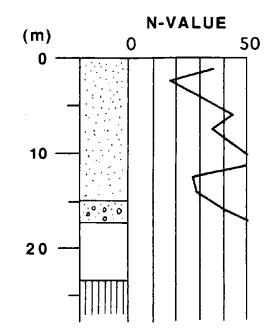


(f) Hachinohe

(g) Miyako



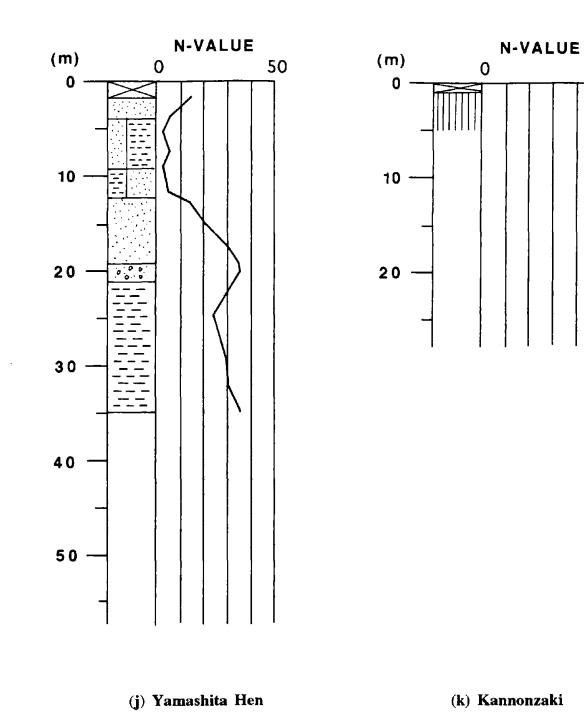




(h) Shiogama

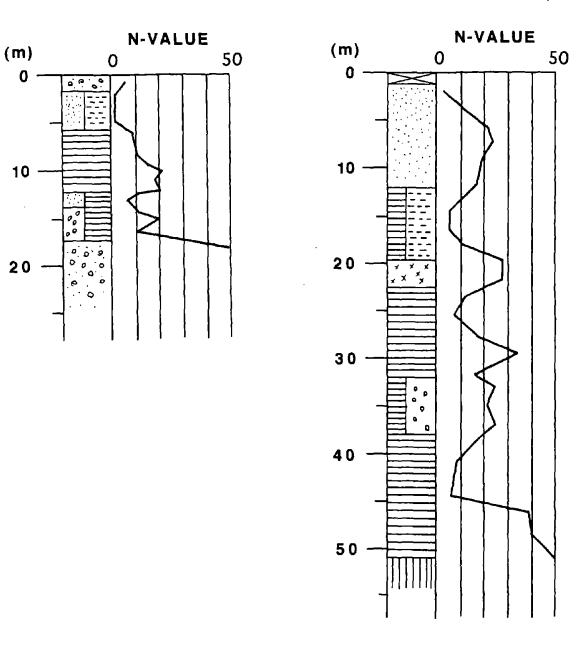
(i) Kashima Jimu

Fig.5-13 Available Soil Profile for Japanese Sites Considered herein



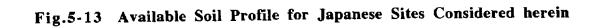
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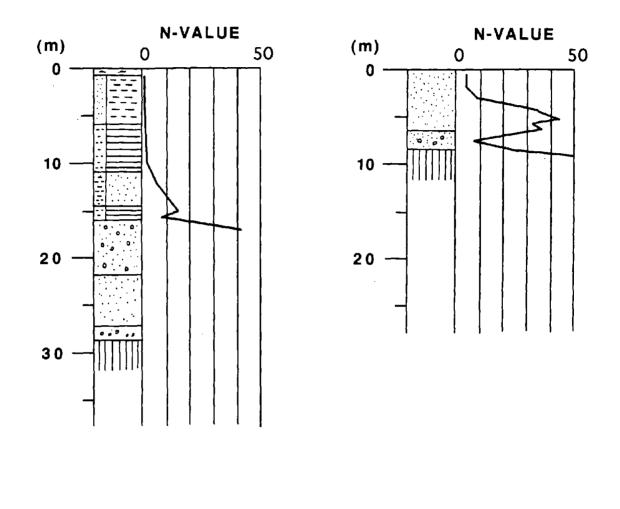
Fig.5-13 Available Soil Profile for Japanese Sites Considered herein

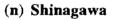




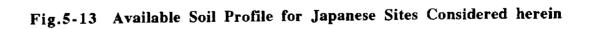
(m) Hososhima

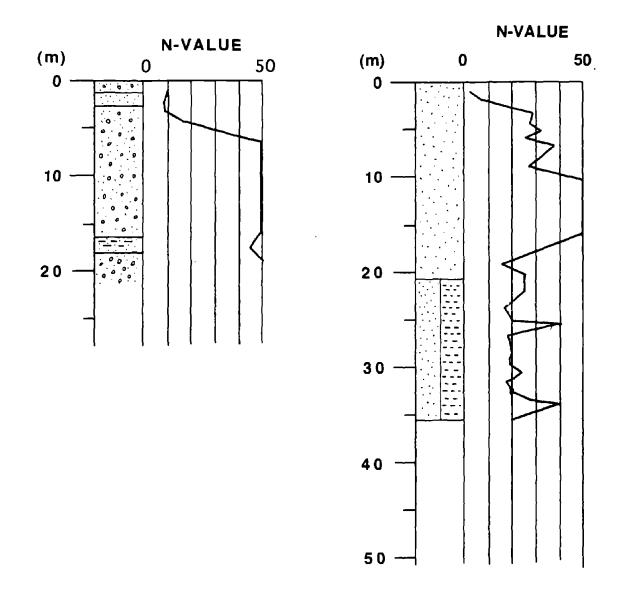














(q) Kashima Zokan



were obtained primarily from the site data compiled by the Port and Harbor Research Institute, Ministry of Transport of Japan[24].

As illustrated in Figs. 5-13(a) to 5-13(q), each observation site has various types of soil formations as well as soil softness. A close look at both Table 5-II and Figs. 5-13(a) to 5-13(q)indicates that the amplification factors vary depending on the formation and the softness of soils. For example, some soft soil sites like SHIN-ISHIKARI, SHIOGAMA, SHINAGAWA etc. represent large amplification factors for peak velocity and displacement while except for SHIN-ISHIKARI they give relatively small amplifications for acceleration. On the other hand, the stiff soil sites such as TOKACHI, MIYAKO etc. show large amplifications in the peak acceleration while they show extremely small amplifications in the peak velocity and displacement. Such a relation between the amplifications and soil profiles suggests a method for estimating the amplification factor at a new site. That is, given a soil profile at a new site, one can approximately predict an amplification factor at the site by looking for a soil profile in Figs. 5-13 (a) to 5-13(q)most similar to the new site profile and selecting its amplification factor. This method is hereafter called the "qualitative method". Since a variety of soil profiles are compiled in Figs. 5-13(a) to 5-13(q), this method may, despite its simplicity, provide an unexpectedly good way for estimating an amplification factor. For example, both SHINAGAWA(Fig.5-13(n) and SHIOGAMA(Fig.5-13(h) have very soft soils(N<10) for moderate depth(up to about 15 m). The acceleration and velocity amplification factors for these sites in Table 5-II are somewhat similar (2.44 and 3.46 respectively for SHIOGAMA and 1.69 and 2.71 respectively for SHINAGAWA). That is, both these sites have moderate acceleration amplification but significant velocity amplification. Contrast this with TOKACHI(Fig.5-13(a)) and AKITA(Fig.5-13(p)) which have a thin layer (depth of about 5 m) of moderately soft soils $(N\sim10)$. Both these sites have low to moderate acceleration amplification factors (2.02 and 1.44 respectively) and somewhat similar velocity amplification factors(1.60 and 2.00 respectively).

The quantitative method for a new site is based upon the concept of the vibration impedance ratio. As described previously, the amplification factors for the peak acceleration, velocity and displacement were obtained with respect to the seismic bed rock at our reference site having S wave velocity of 1 to 2 km/sec range. This strictly means that these amplification factors should be related to soil structures overlaying such seismic bed rock. In general, however, seismic bed rock is laid deep and we have almost no opportunity for finding it in a usual soil profile. In addition, one needs elaborate material information of each layer such as P and S waves velocity, Q values, etc. in order to relate soil conditions to the empirical amplification factors. However such material information is available only at some special sites because of the cost. Hence although vibration

impedance and amplification are directly related to P and S wave velocities, density and Q value(damping), herein we use the N-value variation with depth such as shown in Figs.5-13(a) to 5-13(q) which is the typical information available to a designer and is known to have some relation with the rigidity and density of soils.

Furthermore the quantitative method is restricted to peak velocity amplification factors. This is based on two consideration; first of all Table 5-II indicates that the variation in the peak acceleration amplification factors is relatively small and secondly peak velocity is the parameter of interest for lifeline earthquake engineering studies which is the primary purpose of this study. After a number of trials, the following expression C_{amp} was chosen to represent the impedance characteristics and predominant period of a soil profile.

$$C_{amp} = Max[\frac{\sqrt{N(x_{j+1})}}{\frac{1}{j}\sum_{j=1}^{j}\sqrt{N(x_{j})}}] \times \frac{x_{M}}{\frac{1}{M}\sum_{j=1}^{M}\sqrt{N(x_{j})}}$$
(5.8)

where \mathbf{x}_j is the depth of the j-th N-value, $N(\mathbf{x}_j)$ is the N-value corresponding to the depth of \mathbf{x}_{j} , i is the order number of N-value (i=1~L-1), L is the total number of N-values and M is the the order number maximizing the first term on the right-hand side.

In Eq.(5.8), the first term on the right-hand side is the maximum value of the expression within the parenthesis for i=1 to i=L-1, and M is the value i which maximizes the expression. Eq.(5.8) was derived as a simple approximation based on the concept of the maximum vibrational impedance ratio and the corresponding predominant period. A caluculation of C_{amp} is shown in Appendix B. C_{amp} was estimated for each soil profile in Figs. 5-13(a) to 5-13(q) and is plotted against the corresponding the peak velocity amplification factor AMP_i(v), in Fig.5-14. Though there is some variance, a positive relation is seen between c_{amp} and $AMP_i(v)$. A linear regression expression for $AMP_i(v)$ as a function of c_{amp} is

$$AMP_i(v) = 1.25 + 0.112 C_{amp}$$
 (5.9)

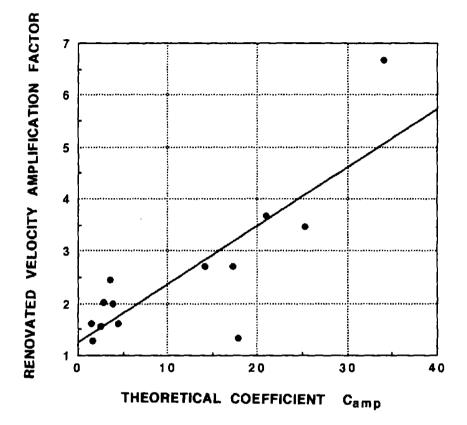


Fig.5-14 Scattergram of Velocity Amplification Factor and Coefficient Camp

Although Eq.(5.8) is simplified and typically would not incorporate information on deep structure down to the seismic bed rock nor Q values, it yields reasonable estimates of the amplification factor for peak velocity. The equation will be applied in a later section.

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SECTION 6 ESTIMATES OF THE PEAK ACCELERATION, VELOCITY AND DISPLACEMENT ON SEISMIC BED ROCK

If the local site amplification factors AMP_i(a), AMP_i(v) and AMP_i(d) are set equal to 1.0, Eqs. (5.1) to (5.6) give the peak values on seismic bed rock for acceleration, velocity and displacement. Such bed rock values depend on earthquake magnitude and hypocentral distance but not on local site conditions. As described in the preceding section, the seismic bed rock corresponds to the rock outcrops at HOROMAN, OFUNATO and HOROMAN for peak acceleration, velocity and displacement respectively. Figs. 6-1 to 6-3 show examples of the attenuation with hypocentral distance for the peak acceleration, velocity and displacement on seismic bed rock. In these figures, the attenuation curves are plotted versus earthquake magnitude. We can see from these figures that the peak acceleration in an epicentral area is limited to about **500 gal** irrespective of earthquake magnitude. Conversely the peak velocity and displacement in the epicentral area depend on earthquake magnitude having maxima of about **50 cm/sec** and **15 cm**, respectively, for an earthquake of magnitude of **8.0**. The validity of the peak values of each motion in Figs. 6-1 to 6-3 is confirmed in a later section by a comparison with actually observed peaks during earthquakes in the U.S. and Mexico. In this section we consider a different type of verification.

As is well known, for harmonic motion we have the following relations for the maximum amplitude of acceleration, velocity and displacement motions.

$$v = \frac{a}{2\pi} T_a \tag{6.1}$$

$$d = \frac{\nabla}{2\pi} T_{\rm o} \tag{6.2}$$

where a is the amplitude of acceleration, v is the amplitude of velocity, d is the amplitude of displacement, T_a is the period of the acceleration motion and T_v is the period of the velocity motion.

With respect to a random wave such as earthquake motions, of course, the simple relations in Eqs.(6.1) and (6.2) are not satisfied. However these equations are approximately correct for earthquake motions if we use the predominant period and maximum amplitude of earthquake motions. Given values for the peak acceleration, velocity and displacement, Eqs.(6.1) and (6.2) enable us to estimate predominant periods for acceleration and velocity motions.

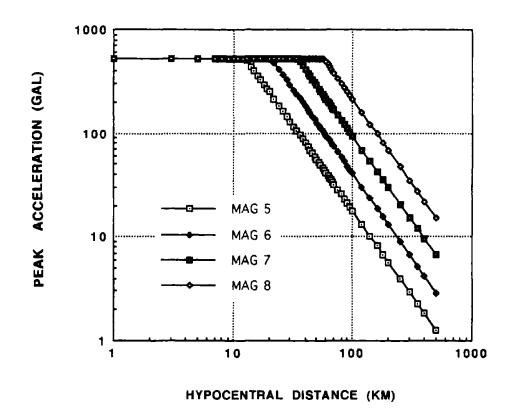


Fig.6-1 Attenuation Relationship for Peak Acceleration on Bed Rock from Proposed Semi-Empirical Model

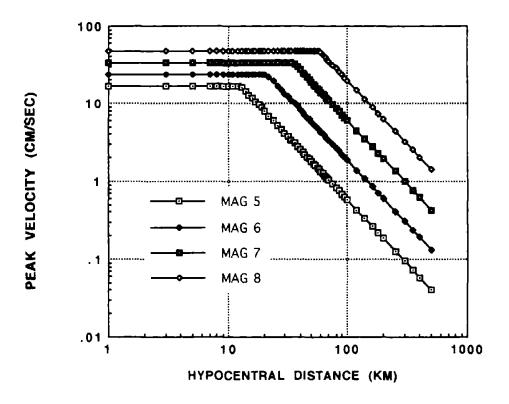


Fig.6-2 Attenuation Relationship for Peak Velocity on Bed Rock from Proposed Semi-Empirical Model

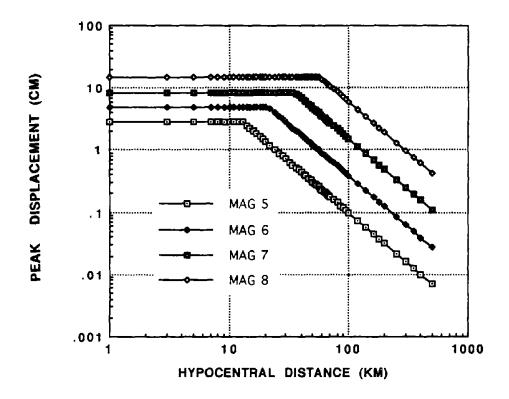


Fig.6-3 Attenuation Relationship for Peak Displacement on Bed Rock from Proposed Semi-Empirical Model

Herein we examined the magnitude-dependence of predominant periods for the acceleration and velocity motions on bed rock. Table 6-I shows the predominant periods of the bed rock acceleration and velocity motions in an epicentral area (the flat area in Figs.6-1 through 6-3) estimated for various earthquake magnitudes using Eqs. (6.1) and (6.2) as well as Figs.6-1 through 6-3. As shown in Table 6-I the predominant periods of the bed rock motions become larger with the increasing earthquake magnitude. The magnitude dependence of predominant period has been noted in other studies. For example Seed et al.[25] graphically presented predominant periods of acceleration motions in an epicentral area resulting from earthquakes in California. The Seed et al. relation is shown in Fig.6-4. A comparison of Table 6-I against the results by Seed et al. indicates that the predominant periods from the model proposed herein are relatively compatible with the Seed et al. results. This provides support for the appropriateness of our semi-empirical model.

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 Table 6-I
 Predominant Periods for Bed Rock Acceleration and Velocity from Proposed Semi-Empirical Model

MAGNITUDE M	PREDOMINANT PERIOD(SEC) (ACCELERATION)	PREDOMINANT PERIOD(SEC) (VELOCITY)
5	0.20	1.07
6	0.29	1.30
7	0.41	1.57
8	0.58	1.90

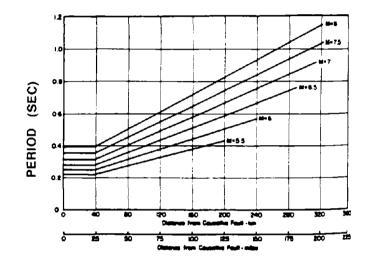


Fig.6-4 Predominant Periods for Acceleration on Rock (after Seed et al.[25])

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SECTION 7

COMPARISON WITH OTHER EMPIRICAL RELATIONSHIPS

As mentioned in the introduction, many researchers have developed empirical relations for peak values of strong motions. Herein we compare our proposed semi-empirical model with empirical results by others. We restrict our comparison to peak velocity at rock sites which correspond to the seismic bed rock in our model and correspond to various rocks in the others. We chose peak velocity because the primary focus of our study is lifeline earthquake engineering for which peak velocity is the ground motion parameter of interest. Rock sites are chosen to simplify the comparison by elimination of local soil effects. Trifunac[12], McGuire[26], Joyner and Boore [27], Campbell [28], Sabetta [29], Ohsaki et al. [30], Watabe and Tohdo [31], and Kawashima et al. [32] have developed empirical relationships for peak velocity at rock sites or nearly rock sites. All these empirical expressions for peak velocity are dependent on earthquake magnitude and source-to-site distance. Figs 7-1 and 7-2 show a comparison of the proposed peak velocity attenuation for an earthquake magnitude of 7.0 with these available relations. The first figure shows a comparison with existing relations mainly from the U.S. while the second is for existing relations from Japan. It should be noted that the distance in Figs.7-1 and 7-2 is either epicentral distance, hypocentral distance, or closest distance to fault rupture, depending on what the individual researches choose as the source-to-site distance. That is, the proposed model uses hypocentral distance; Trifunac[12], McGuire[27], Ohsaki et al.[30], Watabe and Tohdo[31] and Kawashima et al.[32] use epicentral distance; and Joyner and Boore[27], Campbell[28] and Sabetta[29] use closest distance to fault rupture.

It is clear in Fig.7-1 that the proposed semi-empirical model yields peak velocities smaller than most of the U.S. empirical models in the near field, while the converse is true for source-to-site distance greater than about 30 km. On the other hand, Fig.7-2 shows that the proposed model predicts larger values than Kawashima et al.[32] at almost all distances. Considering that the data in the present study overlap in part with the more comprehensive data used by Kawashima et al.[32], the comparison in Fig.7-2 shows that the resulting expressions depend greatly on the initial model choice. In other words, both Figs.7-1 and 7-2 show not only the importance of the data set to be analyzed but also the importance of the analysis model. In any case, the validity for each expression in Fig.7-1 and 7-2 should be eventually judged in reference to a comparison against new observation data not included in their analyses. Such a comparison is performed in the following section.

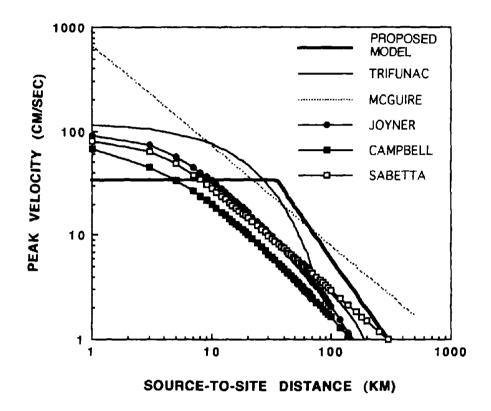


Fig.7-1 Comparison of Proposed Model with Currently Existing Models from the US. and Italy for Magnitude 7.0 Earthquake

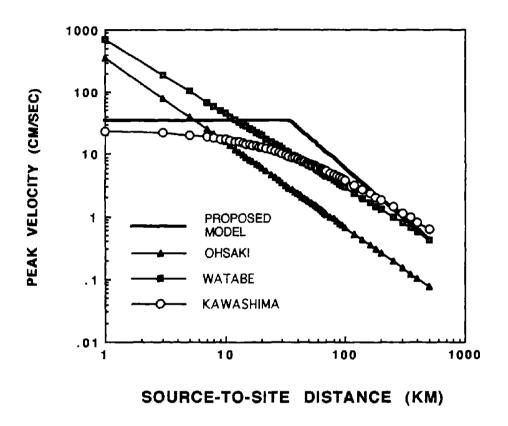


Fig.7-2 Comparison of Proposed Model with Currently Existing Models from Japan for Magnitude 7.0 Earthquake

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SECTION 8

COMPARISON BETWEEN THE PROPOSED MODEL AND OSBERVATIONS DURING EARTHQUAKES IN THE U.S. AND MEXICO

The proposed semi-empirical model was developed using only earthquake data observed in Japan. Information from theoretical seismic source models was used to overcome the lack of near field strong-motion data. It is of primary interest, therefore, to investigate how consistent the proposed model is with observed strong-motion data from other countries that are relatively rich in near field data. In addition to confirming the validity of the proposed model, such an investigation is also essential to judge whether or not strong-motion characteristics vary from country to country. In this section, we investigate the validity of the proposed model by comparing its predicted results with the strong-motion data observed during three earthquakes: the 1989 Loma Prieta earthquake in the U.S., the 1985 Michoacan earthquake in Mexico and the 1971 San Fernando earthquake in the U.S. These earthquakes were chosen because they offer strong-motion records from both the near field and far field. Comparing velocity and displacement motions from different countries is complicated by the fact that different filters are used in determining velocity and displacement from original accelerograms. The filter used for the Japanese records was already illustrated in Fig.3-2. It has a flat part between periods of about 0.09 sec and 4.5 sec. Although somewhat different filters are used by different researchers, it seems that the flat portions of the filters are practically the same regardless of country. Herein we use the reported peak acceleration, velocity and displacement from the original text publishing the relevant earthquake data. That is, the effects if any of using filters different from that in Fig.3-2 are neglected. Also we compare exclusively strong motions on rock sites or nearly rock sites because they are less affected by local site conditions.

8.1 1989 Loma Prieta Earthquake

Many useful strong-motion records were obtained at the stations of the California Strong Motion Instrumentation Program (CSMIP) during the 1989 Loma Prieta earthquake. The estimated earthquake location and magnitude are:

> Epicenter : 37.037 N, 121.883 W Depth : 18 km Magnitude : 7.0 (ML)

The strong-motion data including the geological characteristics of the stations are available in a report from CSMIP[33]. We picked strong-motion data at rock sites from the report and compared

them with the predicted values from the proposed semi-empirical model. Since we consider only rock sites in the comparison, $AMP_i(a)$, $AMP_i(v)$ and $AMP_i(d)$ were set equal to one in Eqs.(5.1) through (5-6). In the comparison, the magnitude scale ML was regarded as identical to the JMA magnitude scale employed in the proposed model.

Figs.8-1 to 8-3 show respectively the comparison between the observed and predicted peak accelerations, peak velocities and peak displacements. In each figure, the error bands of prediction based on the one standard deviation of the regression analysis are plotted in addition to predicted mean values. The standard deviation for the the peak acceleration analysis is shown in Table 4-I($r_c = 5.3 \text{ km}$) and those for the peak velocity and displacement are shown in Table 4-IV. Note that there is a good agreement between the observed and predicted values in Figs.8-1 to 8-3, especially for peak velocity of Fig.8-2. Since the proposed model does not use earthquake fault parameters like rupture directivity but uses only simple parameters such as earthquake magnitude and hypocentral distance, some discrepancy between the observed and predicted values is inevitable. However most of the observed peak velocities are distributed within the error band of the prediction.

8.2 1985 Michoacan Earthquake

The 1985 Michoacan earthquake was a large event that caused severe damage in Mexico City and some damage in the epicentral region. The event provided strong motion records in both the near and far fields. Since earthquake engineering design is often based upon such large events, the prediction of strong motions for this type of event is a goal of our semi-empirical model. The location and magnitude of the earthquake are outlined as follows:

Epicenter: 18.14 N, 102.71 W Depth: 16 km Magnitude: 8.1 (Ms)

Strong-motion records for this event are contained in a UNAM report[34]. Strong motions obtained at rock sites, especially along the coast of Guerrero during the earthquake are compared with predicted values from the proposed model in Figs.8-4 to 8-6. In this comparison, the earthquake magnitude Ms was treated as equivalent to the JMA magnitude. In contrast to the 1989 Loma Prieta earthquake, Figs.8-4 to 8-6 show that the 1985 Michoacan earthquake motions were somewhat smaller than the predicted values in the near field. However relatively good agreement between the observed and predicted values is notable at intermediate to long distances, giving implicit support for the proposed model.

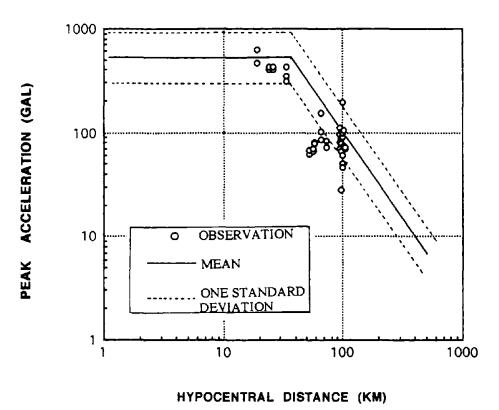


Fig.8-1 Comparison of Peak Acceleration at Rock Sites for the 1989 Lom

Fig.8-1 Comparison of Peak Acceleration at Rock Sites for the 1989 Loma Prieta Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=7.0

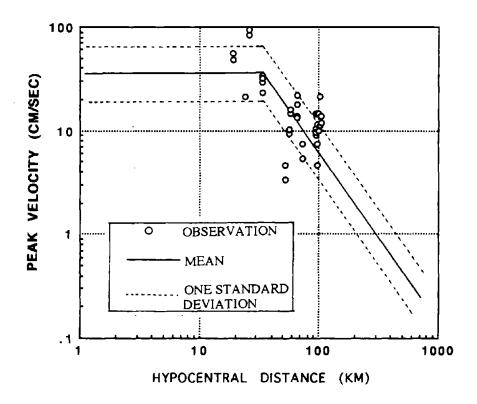


Fig.8-2 Comparison of Peak Velocity at Rock Sites for the 1989 Loma Prieta Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=7.0

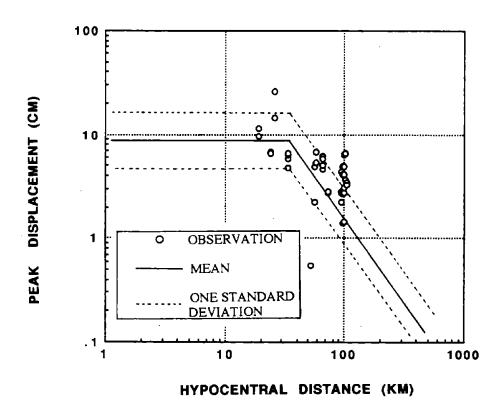


Fig.8-3 Comparison of Peak Displacement at Rock Sites for the 1989 Loma Prieta Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=7.0

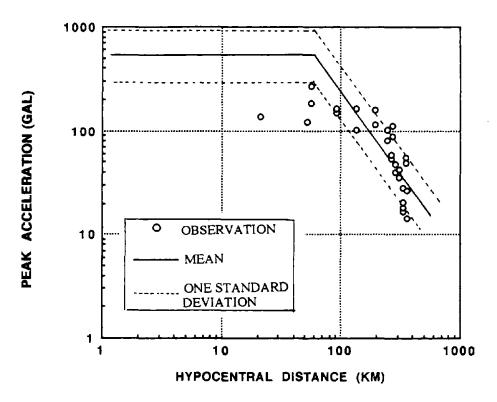


Fig.8-4 Comparison of Peak Acceleration at Rock Sites for the 1985 Michoacan Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=8.1

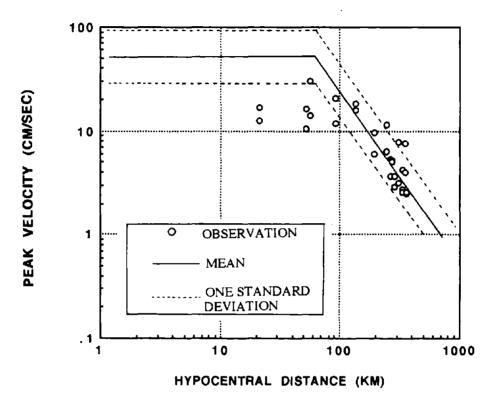


Fig.8-5 Comparison of Peak Velocity at Rock Sites for the 1985 Michoacan Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=8.1

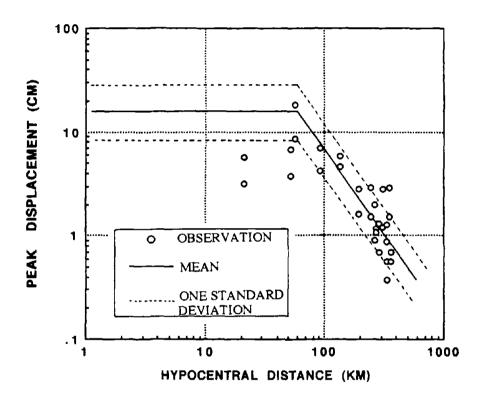


Fig.8-6 Comparison of Peak Displacement at Rock Sites for the 1985 Michoacan Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=8.1

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8.3 1971 San Fernando Earthquake

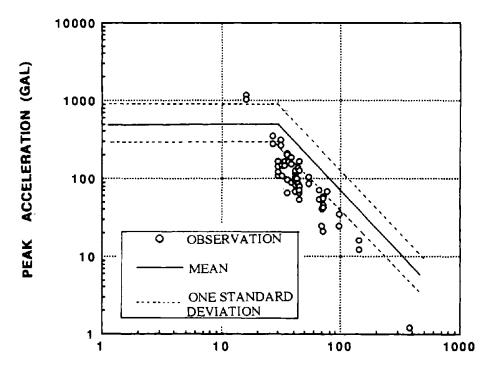
The 1971 San Fernando earthquake was a major source of data for empirical analyses of strong motions by other researchers. This is particularly true for the U.S. empirical expressions discussed in Section 7. Hence a comparison of this earthquake data with the proposed semi-empirical model is meaningful. The strong-motion data and site geological information for this earthquake were taken from a Caltech report[35]. General information for the earthquake is:

Epicenter : 34.40 N, 118.43 W Depth: 13 km Magnitude 6.6 (ML)

Taking the Richter magnitude ML as being identical to the JMA magnitude, the peak motion values for the earthquake were estimated by the proposed model using Eqs.(5-1) to (5-6) with AMP_i =1.0 and compared with the observed peaks at rock sites and nearly rock sites, as shown in Figs. 8-7 to 8-9. It is obvious in Fig.8-7 that the proposed model gives systematically larger acceleration peaks than were observed, whereas a relatively good agreement is found in the cases of velocity and displacement shown in Figs.8-8 and 8-9. It is beyond the scope of this study to explain such differences. However the consistency between the predicted and observed peak velocities lends additional support for our model because we are primarily interested in the prediction of peak velocity.

8.4 Discussion

Among the comparisons shown in Figs.8-1 through 8-9, the observed velocity motions for the three earthquakes match best the predicted values from the proposed semi-empirical model. Except for the observed near field values for the 1985 Michoacan earthquake, the proposed model for peak velocity could serve as a statistical prediction method. This is desirable because the primary goal of this study is to develop an empirical model for estimating peak velocity in connection with the seismic performance of lifelines. In the case of peak acceleration, on the other hand, the observed values for the 1971 San Fernando earthquake are systematically smaller than the predicted values despite relatively good agreement of the predicted values with the observed values for the other earthquakes. However, since the 1971 San Fernando earthquake gives a similar trend in the peak velocity comparison, the systematic difference for the acceleration comparison may be due to the peculiarity of the earthquake. For peak displacement the predicted values for the three earthquakes agree relatively well with the observed values although one may have expected difference due to the different filters used to numerically obtain displacement records. We can see



HYPOCENTRAL DISTANCE (KM)

Fig.8-7 Comparison of Peak Acceleration at Rock Sites for the 1971 San Fernando Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=6.6

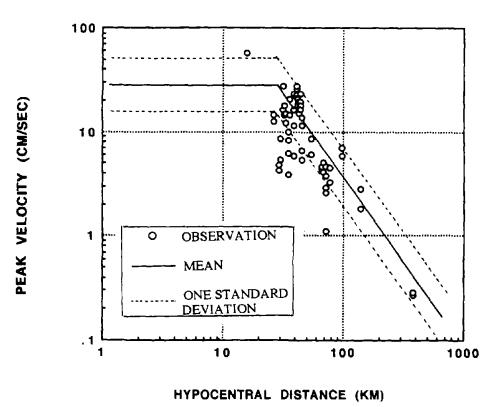


Fig.8-8 Comparison of Peak Velocity at Rock Sites for the 1971 San Fernando Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=6.6

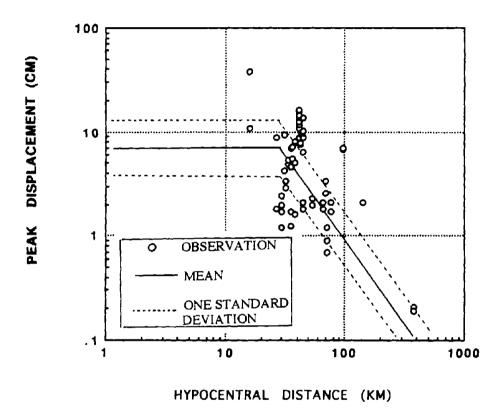
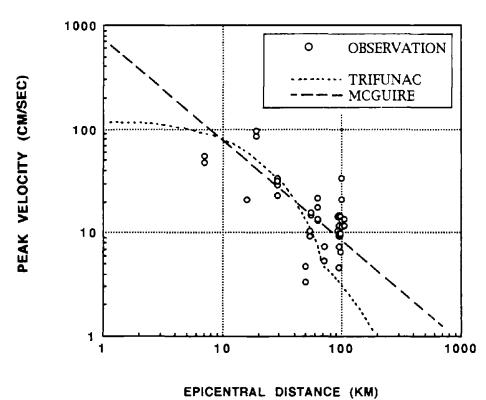


Fig.8-9 Comparison of Peak Displacement at Rock Sites for the 1971 San Fernando Earthquake with Value Predicted by the Proposed Semi-Empirical Model for M=6.6

from the overall comparisons in Figs.8-1 through 8-9 that the present model is applicable to various types of earthquakes. It should be emphasized that the proposed semi-empirical model was based only on earthquake data obtained in Japan. This suggests that earthquakes share a similar attenuation law for strong-motion peaks irrespective of their country of origin.

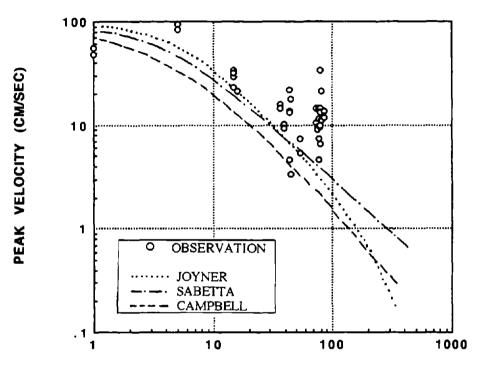
The observed values in Figs.8-1 through 8-9 were chosen regardless of the detailed material characteristics of rock partly because of a lack of information. On the other hand, the predicted values for the proposed model are estimates for the seismic bed rock which was defined based upon the renovation of the amplification factors. In spite of such variation in the definition of rock the predicted and observed values agree reasonably well. Hence the definition of rock can presumably be flexible for peak value prediction, particularly peak velocity prediction as opposed to spectra and time history predictions.

In this section, we have compared the proposed semi-empirical model, which was based on Japanese data, with earthquakes in the U.S. and Mexico. It is also illustrative to compare the existing U.S. empirical attenuation relations, which were based on U.S. data composed primarily of the 1971 San Fernando data, with the more recent 1989 Loma Prieta and 1985 Michoacan data. Fig.8-10 shows a comparison of the predicted values from Trifunac[12] and McGuire[26] with the observed values for the 1989 Loma Prieta event (M=7.0). Both predicted and observed values are plotted in terms of epicentral distance. We can see from a comparison between Fig.8-2 and Fig.8-10 that Trifunac[12] and McGuire[26] do not give better estimates for the observed values of the Loma Prieta event than the proposed model even though the McGuire estimates are fairly consistent. The predicted values from Joyner and Boore[27], Campbell[28] and Sabetta[29], which use closest distance to fault rupture to characterize source-to-site distance, are compared with the observed values from the Loma Prieta event in Fig.8-11. Note in Fig.8-11 that these three empirical relations underestimate the observed values in the Loma Prieta event. Hence although the existing U.S. empirical attenuation relations are based primarily on U.S. data and in some cases use fairly sophisticated measures for site-to-source distance, they do not provide significantly better estimates for observed peak velocity on rock and in some cases (Fig.8-11) provide significantly worse estimates. A similar comparison for the 1985 Michoacan earthquake (M=8.1) is illustrated in Figs.8-12 and 8-13. Fig.8-12 is a comparison between the observed values for peak velocity at rock sites from the 1985 Michoacan event and the empirical estimates by Trifunac[12] and McGuire[26]. A comparison between Fig.8-5 and Fig.8-12 shows that Trifunac[12] and McGuire[26] give worse estimates than the proposed model for the 1985 Michoacan event. Fig.8-13 compares the observed peak velocities with the empirical estimates from Joyner and Boore[27], Campbell[28] and Sabetta[29] in terms of closest distance to fault



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Fig.8-10 Comparison of Observed Peak Velocity at Rock Sites for the 1989 Loma Prieta Earthquake with Empirical Estimates for a Magnitude 7.0 Event by Trifunac and McGuire



CLOSEST DISTANCE TO FAULT RUPTURE (KM)

Fig.8-11 Comparison of Observed Peak Velocity at Rock Sites for the 1989 Loma Prieta Earthquake with Empirical Estimates for a Magnitude 7.0 Event by Joyner and Boore, Campbell and Sabetta

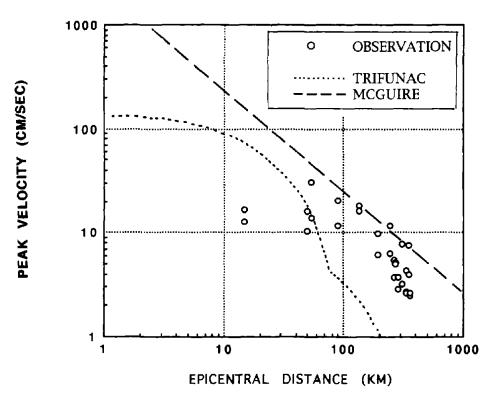


Fig.8-12 Comparison of Observed Peak Velocity at Rock Sites for the 1985 Michoacan Earthquake with Empirical Estimates for a Magnitude 8.1 Event by Trifunac and McGuire

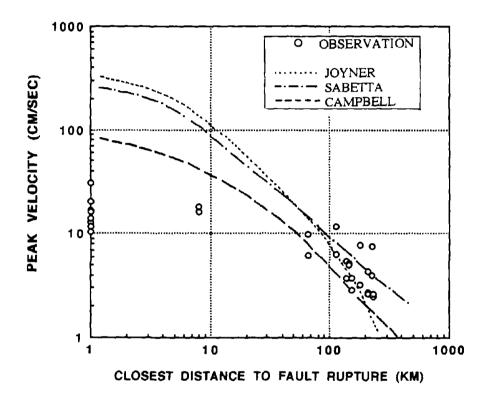


Fig.8-13 Comparison of Observed Peak Velocity at Rock Sites for the1985 Michoacan Earthquake with Empirical Estimates for a Magnitude 8.1 Event by Joyner and Boore, Campbell and Sabetta

rupture. In this figure, the observed values in the fault area are plotted with distance=1 km. Note that the predicted values are good for distance greater than about 80 km but significantly overestimate the observed values at short distances. Hence it is concluded from these comparisons that the existing U.S. empirical relations do not provide more reasonable estimates of peak velocity than the proposed model.

As shown above, the proposed semi-empirical model appears superior to presently existing empirical relations. However there is disparity between the observed and predicted values for the model. The disparity is attributable to several reasons including incompleteness of the model and the peculiarities of each earthquake. Some of the incompleteness result from the simplification of the proposed model being developed for engineering application. In particular, the proposed model does not consider the faulting process at the seismic source which affects peak values of strong motions. Regarding the peculiarities of each earthquake, characteristic scatter of observed peak values is often discussed based on the polarization of the azimuth from seismic focus to observation sites. Such polarization is associated with the rupture directivity of faulting. This suggests that the effects of rupture directivity can explain some of the scatter of observed values about the semi-empirical model. For example, Fig.8-14 shows the observed values of peak velocity at rock sites during the 1989 Loma Prieta earthquake for the sites south and north of the epicenter. Note that the sites situated south of the epicenter generally have smaller peak values than those north, implying that a characteristic rupture directivity of the earthquake influences peak values at each observation site. The effects of rupture directivity are easy to grasp if the rupture is assumed to progress in a uniform manner as illustrated in Fig.8-15. Assuming a unilaterally uniform rupture directivity, Hirasawa and Stauder[36] has shown that amplitude coefficient is given as a function of the azimuth angle ψ by

$$\frac{1}{1 - \frac{\sigma}{\beta}\cos\psi}$$
(8.1)

where v is the rupture propagation velocity and β is the shear wave velocity.

Eq. (8.1) explains the well-known phenomenon that the amplitudes of motions are larger at sites located in the direction of the rupture progress.

Now assuming that the case of $\psi = \frac{\pi}{2}$ in Eq.(8.1) is equivalent to the mean value estimated by the proposed semi-empirical model as well as assuming $\frac{\nu}{\beta} = 0.8$, we obtained expected scatters on the basis of the directivity effect. Such upper and lower bounds for predicted value are drawn

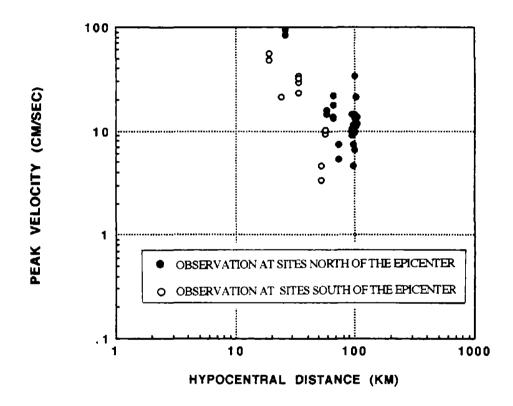
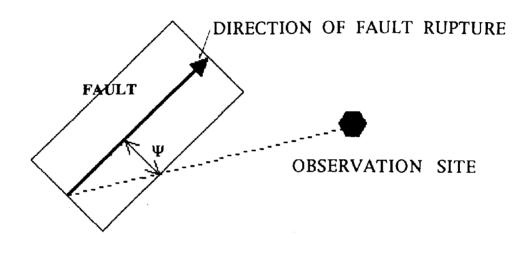


Fig.8-14 Peak Velocity at Rock Sites North and South of the Epicenter, Loma Prieta 1989



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Fig.8-15 Sketch showing Azimuth Angle for an Arbitrary Observation Site with Respect to the Direction of Fault Rupture

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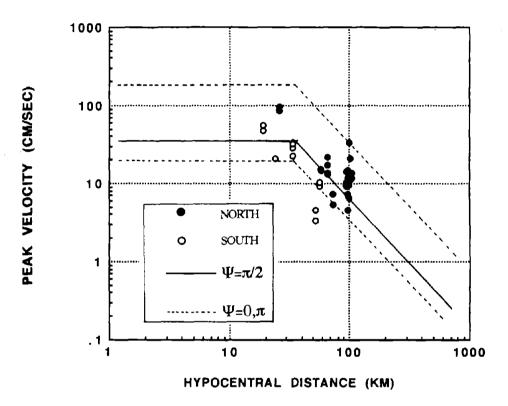


Fig.8-16 Peak Velocity at Rock Sites for the Loma Prieta Event with Scatter Bands Based upon Rupture Directivity in Fig.8-15

in Fig.8-16 together with the mean prediction value. This figure shows that the scatter of observed values about the predicted value from the proposed model, at least for the case of peak rock velocity from the 1989 Loma Prieta event, is explained by fault rupture directivity effects. However fault rupture directivity is not included in the proposed model because it is not known a priori.

As mentioned in Section 2, we derived our semi-empirical model of strong-motion peaks based on the assumption that peak acceleration in a fault zone is independent of earthquake magnitude. The validity of this assumption can be judged by a comparison between the predicted and observed values. However the comparisons shown in Figs.8-1, 8-4 and 8-7 are not enough to judge the validity because observed data within the fault zones are few. We need more strong-motion records observed on rock sites in a fault zone having different size to finally judge our assumption.

SECTION 9 ESTIMATION OF SOIL STRAIN

We have obtained relatively good agreement between the observed peak values of motions and the predicted values from the proposed model. The best agreement was found for peak velocity. This motivates us to apply it to the estimation of soil strain which is associated with peak velocity. In this section, a simplified method for estimating soil strain is presented together with comparisons between predicted and observed values.

9.1 Simplified Method for Estimating Soil Strain

Soil strains induced during earthquakes have been known to play a pivotal role not only in controlling non-linear behavior of ground motions including liquefaction of sandy soils but also in determining the seismic performance of buried pipelines. Despite such importance, there have been relatively few observations of soil strain because of the technical difficulties involved. Hence it is almost impossible at present to derive an empirical expression for soil strain using the technique described previously for strong-motion peaks. However, since strain is theoretically proportional to the corresponding particle velocity, it is possible to indirectly estimate maximum soil strain using our semi-empirical model for peak velocity. According to wave theory for one dimensional propagation, the maximum horizontal soil strain ε_{max} , in the direction of propagation, is given by

$$\varepsilon_{\max} = \frac{\sigma_{\max}}{C}$$
(9.1)

where v_{max} is the peak particle velocity, and C is the apparent propagation velocity of the wave with respect to the ground surface.

The term v_{max} in Eq. (9.1), needless to say, can be calculated for a site if the soil profile is known, using our semi-empirical model. We now consider methods to approximate the apparent propagation velocity C.

The apparent propagation velocity C is a function of the wave type. In the case of body waves, the apparent velocity is a function of angle of incidence and material properties of the surface soils. O'Rourke et al.[37] studied the apparent horizontal propagation velocity of S-wave using theoretical analysis as well as observed values in the U.S. and Japan. They concluded that it falls in the range of 2.0 to 5.0 km/sec with an average of about 3.5 km/sec. Since they studied a

number of different sites, the average velocity of 3.5 km/sec would be acceptable as a firstapproximation. Herein we employ the value of 3.5 km/sec as the apparent propagation velocity of body waves with respect to the ground surface.

For the case of surface waves, Rayleigh wave(R-wave) induces soil strain alternating between tension and compression in the direction of propagation. For R-waves, the propagation velocity is a function of frequency. This relation is quantified by a dispersion curve for the phase or propagation velocity. For typical soil profiles with shear wave velocity increasing with depth, the propagation velocity is an increasing function of period. For example, Fig.9-1 shows an approximate dispersion curve developed by O'Rourke et al.[38] for the fundamental R-wave for a uniform soil layer over a half space. For long period motion $hf/c_{\perp} \le 0.25$, the phase velocity is somewhat less than the shear wave velocity of the half space, while for short period motion $hf/c_{\perp} \ge 0.5$, the phase velocity is equal to the shear wave velocity of the surface layer, C_L . Note however that the R-wave phase velocity corresponding to the natural frequency of the soil layer in shear $f = C_{\perp}/4h$ is $0.875C_{\rm H}$, that is, it is controlled by the shear wave velocity of the half space. For sites subject to both body and surface waves, we assume herein that the peak particle velocity $v_{\rm max}$ occurs during the later arriving R-wave portion of the record. We further assume that the predominant frequency of the R-wave portion matches the natural frequency of soil layer in shear. That is, for sites subject to surface waves

$$\varepsilon_{\text{mex}} = \frac{\upsilon_{\text{mex}}}{0.875 \cdot C_{\text{H}}}$$
(9.2)

where v_{max} is the peak particle velocity from Eq.(5.3) or Eq.(5.4)) and C_H is the shear wave velocity of the seismic bed rock which underlies the site. Based upon the reference site and the seismic bed rock for peak velocity in section 5.1, we choose 2.0 km/sec as a representative value for C_H.

The above considerations gives us a simplified way to estimate the maximum longitudinal or normal strain separately for body waves and surface waves. The next problem is to identify which wave type is likely to be most prominent in a given record. This complicated phenomenon has been studied by several workers. In general a large earthquake with a shallow focal depth is more likely to generate surface waves. Since the detailed consideration about this problem is beyond the scope of this report and our target is to develop a simplified method for estimating the maximum soil strain, the discussion is herein confined to an assumption of surface wave generation suggested by Nakamura[39]. Nakamura[39] investigated the existence of surface waves in

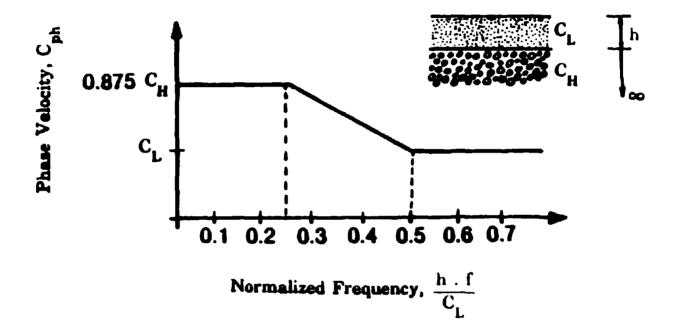


Fig.9-1 Approximate Dispersion Curve for Fundamental R-wave for Uniform Soil Layer over a Half Space(after O'Rourke et al.[38])

records obtained during a total of 29 earthquakes by the use of non-stationary spectra analysis. A table in that work identifies the generation of surface waves as being dependent on earthquake magnitude and an apparent angle defined by focal depth and epicentral distance. From the Nakamura table, we herein establish the following conditions for generation of surface waves:

where M is the earthquake magnitude, Δ is the epicentral distance and D is the focal depth. It should be noted that the above standard for surface wave generation is an approximation. Hence our simplified method for estimating the maximum soil strain can be summarized as follows; For sites subject to surface waves, that is M>6.0 and Δ /D> 1.5, or $6.0 \ge M>5.0$ and

Δ/D > 6.0

$$\varepsilon_{\max} = \frac{\sigma_{\max}}{1.75 \times 10^5}$$
(9.3)

while for all other sites, body waves control and

$$\varepsilon_{\text{mex}} = \frac{\nabla_{\text{mex}}}{3.5 \times 10^5} \tag{9.4}$$

where v_{max} is the peak particle velocity in cm/sec given by Eq.(5.3) or Eq.(5.4).

Eqs.(9.3) and (9.4) make it possible to estimate the maximum strain at a site provided that earthquake magnitude, epicentral distance, focal depth and hypocentral distance are known as well as the surface profile. For example, Fig.9-2 is a plot of the attenuation of estimated maximum strain at a rock site, for which $AMP_i(v)$ is taken as 1.0 in Eq.(5.3) or Eq.(5.4), subject to surface waves.

9.2 Comparison of Estimated Soil Strain with Observed Values

In this section, the estimated strains given by Eq.(9.3) or Eq.(9.4) are compared with strains observed at representative sites to check the validity of the simplified method.

The Kubota Corp. in Japan has been observing soil strains as well as the behavior of pipelines during earthquakes at two separate sites in Aomori Prefecture, namely Kansen and Shimonaga.

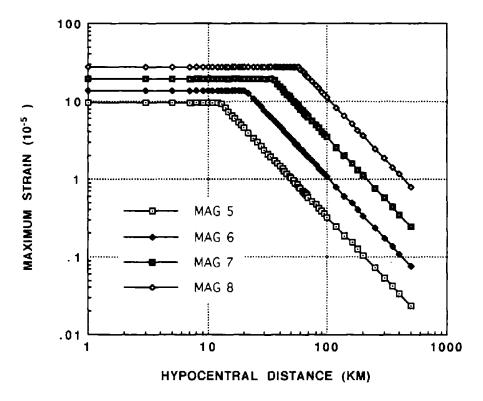


Fig.9-2 Attenuation for Estimated Maximum Soil Strain at Rock Site Subject to Surface Waves

The details of these observation systems including soil profiles at both sites are available in Iwamoto et al.[40]. Figs 9-3 and 9-4 each show the soil logs at the Kansen and Shimonaga sites. Although the observations at both sites have been carried out since 1975 giving useful data relevant to seismic performance of buried pipelines, the maximum soil strains observed until 1983 are compared with estimated normal strains from Eq.(9.3) or Eq.(9.4).

In order to estimate the maximum soil strain based on Eq.(9.3) or Eq.(9.4), one needs the amplification coefficient $AMP_i(v)$ applicable to both the Kansen and Shimonaga sites. We offered two methods: the "qualitative method" and "quantitative method" for the estimate of $AMP_i(v)$ at a site not included in our statistical analysis. According to the qualitative method, the value of $AMP_i(v)$ at the Kansen site is expected to be about 2.70 since the Kansen soil profile in Fig.9-3 is most similar to the Itajima site in Fig. 5-13(1). On the other hand, the estimated $AMP_i(v)$ by the quantitative method which consists of Eq.(5.8) and Eq.(5.9) is 2.18 because the value of C_{amp} is 8.30 by Eq.(5.8). The calculation of C_{amp} for the Kansen site is shown in Appendix B. This example shows that the qualitative method gives fairly accurate amplification factor, although it is simple. Since the quantitative method is expected to yield the more accurate value, we use 2.18 as the amplification factor for the Kansen site. Similarly, the quantitative method resulted in $AMP_i(v) = 5.28$ at the Shimonaga site via $C_{amp} = 35.9$. Having obtained the amplification factors $AMP_i(v)$ at both sites, it is possible to predict the maximum soil strains expected at both sites knowning the earthquake magnitude, epicentral distance, focal depth and hypocentral distance. The predicted maximum soil strains at the Kansen and Shimonaga sites are plotted, respectively, in Figs.9-5 and 9-6 and compared with observed maximum normal or longitudinal soil strains. In both figures, data points with an open circle are estimated values using Eq.(9.3) (surface wave source) while the closed circle indicates values from Eq.(9.4) (only body wave source). Fig.9-5 and 9-6 show that the predicted values coincide relatively well with the observed values. Comparisons similar to Figs.9-5 and 9-6 between the predicted and observed maximum strains are shown in Figs. 9-7 and 9-8 for two other observation sites. These are University of Tokyo, Chiba site[41] and Chubu Electrical Power Corp., Chubu site[42]. The observed strain at the Chiba site was obtained by observing pipe strain[41] and herein we assume that the pipe strain represents soil strain. Again Figs.9-7 and 9-8 show that the comparison between predicted and observed strains is relatively good.

9.3 Discussion of Simplified Method for Soil Strain

As shown in Figs.9-5 through 9-8, on average the simplified method predicts well the observed maximum normal or longitudinal soil strains. However there is some scatter between observed

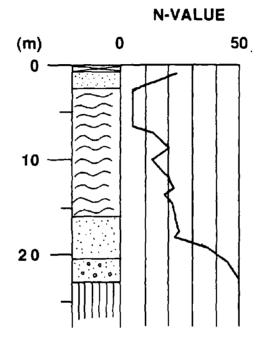


Fig.9-3 Soil Profile for the Kansen Site (Kubota Corp. Soil Strain Installation)

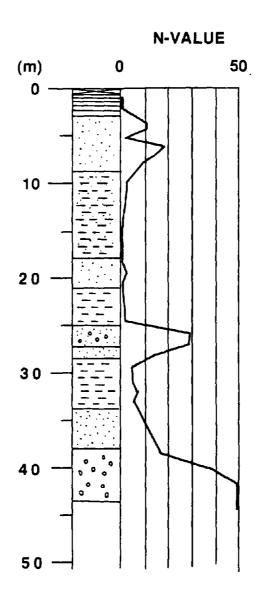


Fig.9-4 Soil Profile for the Shimonaga Site (Kubota Corp. Soil Strain Installation)

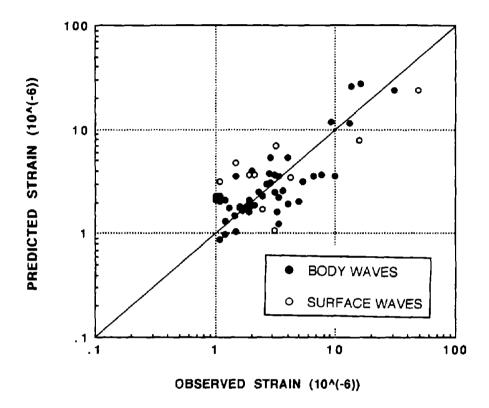
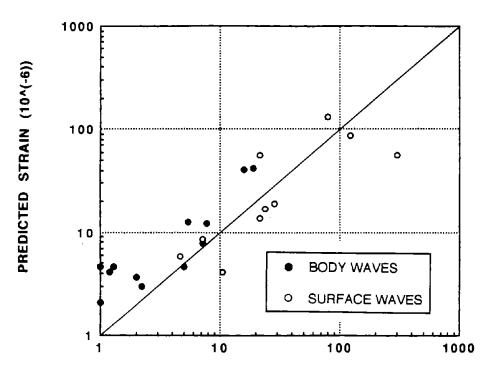


Fig.9-5 Comparison Between Observed Soil Strain at the Kubota Corp. Kansen Site and Predicted Values from Eqs.(9.3) or (9.4)



OBSERVED STRAIN (10^(-6))

Fig.9-6 Comparison Between Observed Soil Strain at the Kubota Corp. Shimonaga Site and Predicted Values from Eqs.(9.3) or (9.4)

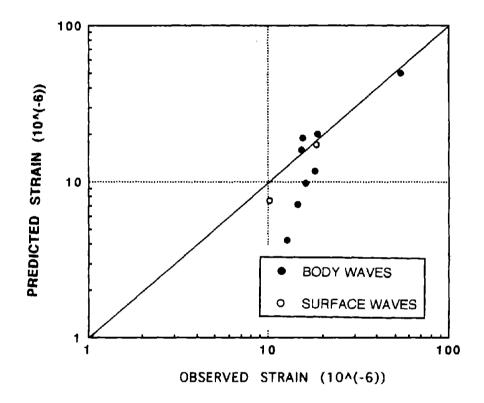
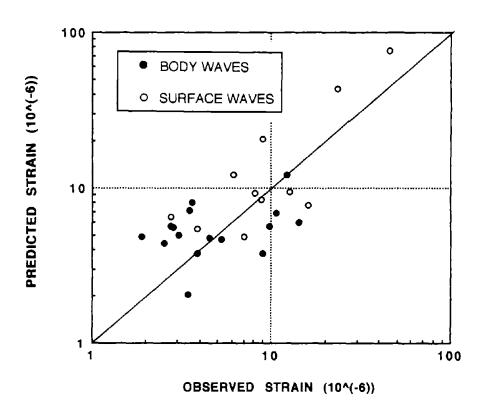


Fig.9-7 Comparison Between Observed Soil Strain at the Univ. of Tokyo Chiba Site and Predicted Values from Eqs.(9.3) or (9.4)



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Fig.9-8 Comparison Between Observed Soil Strain at the Chubu Electric Power Corp.Chubu Site and Predicted Values from Eqs.(9.3) or (9.4)

and predicted values. Some of this scatter is attributed to errors in estimated values for the peak particle velocity, v_{max} , as shown for example in Fig.4-3. Another source for error is inaccuracy in the measured soil strain. For example the measured strain would be less than the maximum soil strain at a site if the measuring device was not parallel to the direction of wave propagation. This is a possible explanation for points above the 1 to 1 match line in Figs.9-5 through 9-8. Finally for sites where surface waves are likely, we assume that the peak velocity, v_{max} , occurs during the later surface wave portion of the record. In addition we assume that predominant period of that peak motion corresponds to the natural frequency of soil layer in shear. It is of course possible that the peak velocity, v_{max} , may occur during the body wave portion of the record. It is also possible that the predominant frequency of surface waves is somewhat higher than $0.25C_L/h$ and R-wave phase velocity in Fig.9-1 would hence be less than $0.875C_H$. However if both these happen together, the soil strain which is a quotient might remain relatively unchanged from that given by Eq.(9.3).

SECTION 10 SUMMARY AND CONCLUSIONS

This report dealt with a semi-empirical model for estimating the peak values of strong motions with emphasis on the peak velocity which is needed for lifeline earthquake engineering studies. In the derivation of the model, theoretical information about seismic sources was combined with a statistical analysis of strong-motion data from Japan. The concept of dummy variables was used to obtain amplification factors due to individual local site conditions in the statistical analysis. An attenuation law for the peak acceleration, peak velocity and peak displacement on a rock was also obtained in terms of earthquake magnitude and hypocentral distance. The resulting amplification factors for peak velocity due to local site conditions were examined in connection with spectral amplification and soil profile, providing a method to predict the amplification factor at a new site. In addition, the resulting attenuation law for peak values on a rock was successfully compared with strong-motion data observed during three representative earthquakes in the U.S. and Mexico. Attenuation laws for strong motions by other researchers were also compared against the proposed model. Finally, a simplified method for estimating soil strain was developed. The main conclusions from this study are summarized as follows:

(1) Purely empirical models for prediction of strong-motion parameters suffer due to the fact that there usually is a correlation between the supposed independent variables in the strong-motion data. It is possible to overcome this difficulty as done herein by employing a standard attenuation coefficient empirically derived from extensive earthquake data collected by JMA.

(2) Amplification factor due to local site effects depends on the individual observation sites in contrast to the rough classification system commonly used by other researches. We developed a method for obtaining amplification factors at each observation site with the help of dummy variables. Results indicated that amplification factors vary remarkably from site to site and also depend on motion characteristics of interest, i.e.: acceleration, velocity and displacement.

(3) From a comparison against the amplification spectra, it was concluded that acceleration amplification is exclusively determined by period components less than about 0.3 sec while velocity's amplification is closely related to period components greater than about 1.0 sec. These amplification factors are also intimately related to the soil profile. In this study, we proposed two methods for predicting amplification factors, the "qualitative method" and "quantitative method." In the former method the amplification factor is estimated by a visual comparison of soil profiles. In the latter method the amplification factor is calculated from the distribution of N-values in the soil profiles.

(4) Besides the amplification factors due to local site effects, we obtained a set of attenuation laws for peak values on the seismic bed rock using the proposed model. The seismic bed rock was defined based on the selection of reference site for the regression analysis and then a reconsideration based upon the resulting amplification factors. For example, the seismic bed rock for peak velocity corresponds to the rock outcrop at OFUNATO whose shear wave velocity is about **2000** m/sec. The attenuation laws for seismic bed rock are expressed in terms of earthquake magnitude and hypocentral distance. The expressions for attenuation including the amplification factors AMP_i are given in Eqs.(5.1) to (5.6).

(5) On the assumption that earthquake strong motions are analogous to simple harmonic motion, we obtained a rough estimate of the predominant periods of acceleration and velocity motions expected at a rock site. The resultant predominant periods, which are summarized in Table 6-I, indicated a tendency of longer periods with increasing earthquake magnitude. Also the resulting predominant periods compared favorably with observations by Seed et al.

(6) The peaks of strong motions at a rock site predicted by the proposed model were compared with the observed values from the 1989 Loma Prieta earthquake, the 1985 Michoacan earthquake and 1971 San Fernando earthquake. It was shown that the proposed model predicts relatively well the observed data. In particular, we found a good agreement between the predicted and observed values in the comparisons of peak velocity which is a primary goal of this study. Since the proposed model was based solely on Japanese strong-motion data, this suggests that strong-motion peaks have a common attenuation law irrespective of country of origin. Empirical models developed by other researchers, though established using the strong-motion data in the U.S., were also compared with the proposed semi-empirical model. The comaprison showed that these existing empirical relarions do not provide better estimates to the observed data than the proposed semi-empirical model.

(7) Based upon the proposed semi-empirical model for peak velocity, a simplified method for estimating maximum normal or longitudinal soil strain was developed herein. A comparison of predicted strains with observed values showed that the simplified method is reasonably accurate.

Finally it is pointed out that the basic logic used in this report could be used to estimate not only peaks of strong motions but also other parameters related to earthquakes.

In this report, some simplified procedures were adopted based on practical considerations. For instance, the derivation of the amplification factors for a soil profile was performed using only typically available N-value data for soil, and deep layers down to real bed rock were not considered. Using more detailed soil and rock information, more accurate amplification factor

could be obtained. Furthermore, non-linear material characteristics of soft soils were not dealt with in this report. These problems are open questions for possible further study.

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APPENDIX A

Table A-I List of Strong-Motion Records Used in This Study

_357 strong motion records obtained at 33 observation sites

Observation site list

NO	SITE NAME
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 24 25 26 27 28 9 30 31 32	KUSHIRO CHIYODA TOKACHI HOROMAN SHIN ISHIKARI TOMAKOMAI MURORAN AOMORI HACHINOHE MAZAKI MIYAKO OFUNATO (Reference site: hard slate) SHIOGAMA TAIRA SHINTONE KASHIMA JIMU KASHIMA PWR TONE ESD OMIGAWA CHIBA YAMASHITA HEN KANNONZAKI OCHIAI KINOKAWA ITAJIMA HOSOSHIMA SOMA SHINAGAWA ONAHAMA JI AKITA CHIBA S HITACHI NAKA
33	KASHIMA ZOKAN

Table A-I	List of	Strong-Motion	Records	Used i	in This	Study	(Cont'd)	
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NO	SITE	М	D	Re	r	Amax	V _{max}	D _{max}	
1	1	7.0	(KM) 60.0	(KM) 209.0	(KM) 217.4	(cm/sec ²) 98.700	(cm/sec) 7.040	(cm) 1.770	
2	1 1	7.0 5.8	60.0 60.0	209.0 61.0	217.4 85.6	79.900 155.100	7.210 5.960	1.790 2.900	
3 4	1	5.8 5.8	60.0	61.0	85.6	87.100	5.890	0.720	
5	1	7.1	26.0	191.0	193.3	77.100	5.140	2.720	
6 7	1 1	7.1 7.4	26.0 40.0	191.0 128.0	193.3 134.1	56.800 224.600	5.620 29.270	1.690 6.300	
8	1	7.4	40.0	128.0	134.1	125.400	15.220	2.860	
9	7	7.9	0.0	285.8	285.8	252.300	22.090	8.580	
10 11	7 7	7.9 7.5	0.0 40.0	285.8 216.0	285.8 219.7	240.000 191.600	19.790 6.950	6.720 1.280	
12	7	7.5	40.0	216.0	219.7	123.700	5.550	3.050	
13	7	6.9	80.0	170.0	174.6	70.400	3.290	0.880	
14 15	7 7	6.9 7.1	80.0 130.0	170.0 103.0	174.6 165.9	47.800 155.400	3.430 15.550	1.820 3.560	
16	7	7.1	130.0	103.0	165.9	237.800	9.670	1.490	
17	8	7.9	0.0	244.0	244.0	319.500	45.980	18.690	
18 19	8 8	7.9 7.5	0.0 40.0	244.0 219.0	244.0 222.6	200.000 82.600	39.710 9.060	13.790 2.620	
20	8	7.5	40.0	219.0	222.6	106.000	9.670	2.520	
21 22	8	6.4	80.0 80.0	103.0 103.0	130.4 130.4	70.600 86.900	3.780 3.310	1.090 0.670	
22	8 8	6.4 7.2	0.0	293.0	293.7	22.000	4.530	1.730	
24	8	7.2	0.0	293.0	293.7	29.400	4.580	1.670	
25 26	8 8	6.9 6.9	80.0 80.0	212.0 212.0	215.7 215.7	32.400 35.700	5.480 5.630	2.170 2.900	
27	9	7.2	0.0	150.0	151.3	46.800	3.460	0.910	
28	9	7.2	0.0	150.0	151.3	41.600	3.020	1.920	
29 30	9 9	6.9 6.9	80.0 80.0	150.0 150.0	155.2 155.2	42.100 30.600	4.080 3.270	1.510 2.000	
31	9	6.6	40.0	75.0	85.0	71.200	5.960	2.000	
32	9	6.6	40.0	75.0	85.0	62.800	4.910	1.590	
33 34	9 9	7.9 7.9	0.0 0.0	185.0 185.0	185.0 185.0	327.300 209.500	27.580 32.280	10.780 12.180	
35	9 9	6.4	80.0	59.0	99.4	93.100	4.420	1.320	
36	9	6.4	80.0	59.0	99.4	88.400	3.100	1.020	
37 38	9 9 9	5.6 5.6	40.0 40.0	49.5 49.5	53.4 53.4	116.300 107.600	3.890 3.300	1.010 0.910	
39	9	7.4	40.0	273.0	275.9	75.300	8.160	1.780	
40	9	7.4	40.0	273.0	275.9	73.200	8.660	2.010	
41 42	11 11	7.9 7.9	0.0 0.0	191.0 191.0	191.0 191.0	179.000 196.100	7.440 5.910	3.120 1.610	
43	11	7.5	40.0	214.0	217.7	161.100	5.350	1.310	
44	11	7.5	40.0	214.0	217.7	138.300	4.500	1.170	
45 И=Мас	11 Initude.	6.3 30.0 94.0 98.7 87.400 2.930 0.620 e, D=Depth, R_e =Epicentral distance, r=Hypocentral distance							

4611 6.3 30.0 94.0 98.7 153.300 2.260 1.330 4711 6.0 30.0 96.0 100.6 118.400 3.710 1.080 4811 6.0 30.0 96.0 100.6 76.800 2.340 1.280 4911 6.7 50.0 99.0 110.9 98.300 4.360 1.500 5011 6.7 50.0 99.0 110.9 98.300 4.360 1.500 5111 7.4 40.0 166.0 170.8 246.900 8.970 1.930 5211 7.4 40.0 166.0 170.8 175.000 7.070 1.180 5313 6.4 50.0 117.0 127.2 58.600 4.430 0.690 5413 6.7 50.0 110.0 120.8 123.600 10.040 1.140 5613 6.7 50.0 110.0 120.8 123.600 19.010 3.410 5713 7.4 40.0 100.0 107.7 335.300 29.800 6.220 5813 7.4 40.0 100.0 107.7 335.300 29.800 6.220 5813 7.4 40.0 100.0 107.7 335.300 29.800 6.220 5813 7.4 40.0 100.0 107.7 355.00 4.200 6012 6.2 40.0 70.2 <	NO	SITE	М	D	Re	r	Amax	V _{max}	D _{max}
	447890123456789012345678901234567777777890123	11 11 11 11 11 11 11 13 13 13 13 12 12 12 12 12 12 12 12 12 12 12 12 12	6666776666776666666557777776666677666666	(KM 30.0 30.0 50.0 50.0 50.0 50.0 50.0 50.0	 (KM) 94.0 96.0 99.0 99.0 166.0 117.0 110.0 100.0 70.2 70.2 54.0 57.0 103.0 288.5 80.0 69.0 48.0 86.0 86.0 46.0 50.5 53.1 53.1 	(KM) 98.7 100.6 100.6 110.9 170.8 170.8 127.2 127.2 127.2 127.2 127.2 127.7 80.8 73.6 70.0 90.3 110.5 296.9 80.0 69.0 84.9 91.1 47.1 47.1 51.5 54.0 54.0	(cm/sec ²) 153.300 118.400 76.800 130.300 98.300 246.900 175.000 58.600 64.000 223.600 163.900 335.300 299.400 51.300 167.900 69.200 138.000 138.000 130.700 62.000 144.200 222.900 273.300 81.400 60.500 63.100 55.200 94.300 76.200 86.000 71.000 325.800 365.000 103.800 139.500 171.300 152.500 72.400 74.800	(cm/sec 2.260 3.710 2.340 3.280 4.360 8.970 7.070 4.430 5.140 10.040 19.010 29.800 50.630 1.500 3.500 1.500 3.500 1.500 3.900 4.100 12.600 12.200 16.800 4.200 5.900 5.500 7.100 6.800 5.500 7.100 6.800 5.500 7.100 6.800 5.500 7.100 6.800 5.500 5.500 7.100 6.800 5.500 5.700 5.500 5.500 5.500 5.500 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.700 5.500 5.500 5.700 5.700 5.000 5.500 5.700 5.500 5.700 5.500 5.700 5.700 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.700 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.000 5.0000 5.0000 5.0000 5.00000000) (cm) 1.330 1.080 1.280 0.770 1.500 1.930 1.180 0.690 0.670 1.140 3.410 6.220 12.250 0.600 4.200 0.800 0.900 1.000 1.000 1.000 1.000 1.300 3.800 1.400 1.300 3.800 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.300 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.500 1.400 1.300 1.500 1.500 1.500 1.500 1.400 1.300 1.500 1.500 1.500 1.400 1.300 1.500 1.500 1.500 1.000
85 26 6.2 120.0 47.5 129.1 88.500 8.100 1.500	82 83 84	26 26 26	6.1 6.1 6.2	10.0 10.0 120.0	53.1 53.1 47.5	54.0 54.0 129.1	72.400 74.800 83.300	2.900 3.000 7.000	1.100 1.300 1.100
89 5 7.5 40.0 224.0 227.5 172.100 19.600 4.300	90 91 92	5 5 5 5 5 2	6.7 6.7 7.9	50.0 50.0 0.0	166.6 166.6 243.0	173.9 173.9 243.0	73.100 82.300 86.000	7.800 8.900 15.800	2.000 2.700 5.600

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Table A-I List of Strong-Motion	Records Used	in This	Study (Co	ont'd)
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NO	SITE	М	D	Re	r	Amax	Vmax	D _{max}
93	2	7.9	(KM 0.0) (KM) 243.0	(KM) 243.0	(cm/sec ²) 110.400	(cm/sec) 17.900	(cm) 7.600
94	2	6.7	50.0	62.7	80.2	139.600	6.500	2.300
95	2	6.7	50.0	62.7	80.2	120.900	6.200	2.300
96	2	7.4	40.0	228.7	232.2	108.700	6.700	2.300
97	2	7.4	40.0	228.7	232.2	93.400	8.300	2.400
98	4	7.9	0.0	156.4	156.4	133.100	7.100	3.200
99 100	4	7.9 7.5	0.0 40.0	156.4 74.7	156.4 84.7	107.900 104.600	6.600 4.200	2.200 2.300
101	4	7.5	40.0	74.7	84.7	97.400	4.800	2.100
102		6.7	50.0	35.4	61.3	246.500	8.200	1.700
103		6.7	50.0	35.4	61.3	191.800	8.200	2.100
104		5.4	50.0	85.1	98.7	60.600	3.100	1.300
105		5.4	50.0	85.1	98.7	57.600	3.700	1.300
106 107		5.1 5.1	50.0 50.0	59.7 59.7	77.9 77.9	65.300 74.800	3.300	0.800 0.900
108		5.5	40.0	60.7	72.7	74.800 58.900	4.000 3.100	0.800
109		5.5	40.0	60.7	72.7	48.300	3.400	2.100
110		5.5	50.0	20.2	53.9	90.000	4.700	1.100
111		5.5	50.0	20.2	53.9	85.200	3.100	0.500
112		7.4	40.0	165.6	170.4	97.700	12.000	2.400
113		7.4	40.0	165.6	170.4	104.300	9.800	2.100
114 115		5.2 5.2	40.0 40.0	9.4 9.4	41.1 41.1	67.600 257.300	4.800 13.800	0.800 1.000
116		5.9	50.0	26.8	56.7	105.400	13.100	2.800
117		5.9	50.0	26.8	56.7	96.200	6.100	1.200
118		5.8	60.0	33.2	68.6	103.300	8.600	1.400
119		5.8	60.0	33.2	68.6	92.900	5.100	0.900
120		6.1	60.0	41.4	72.9	90.600	7.000	2.000
121 122		6.1 6.1	60.0 40.0	41.4 55.4	72.9 68.3	71.700 176.000	5.000 12.600	1.100 1.500
123		6.1	40.0	55.4	68.3	174.200	12.300	1.800
124		5.1	50.0	11.0	51.2	83.400	2.700	1.200
125		5.1	50.0	11.0	51.2	92.900	5.200	3.100
126		6.1	50.0	74.4	89.6	94.900	10.000	2.800
127		6.1	50.0	74.4	89.6	57.600	3.400 3.700	1.700
128 129		5.3 5.3	70.0 70.0	12.9 12.9	71.2 71.2	87.500 71.300	4.400	0.600 1.300
130		5.4	60.0	20.6	63.4	94.100	6.600	1.500
131		6.1	50.0	29.4	58.0	84.100	7.600	1.400
132		6.1	50.0	29.4	58.0	89.700	12.500	3.100
133		5.6	100.0	71.3	122.8	49.600	5.000	1.200
134 135		5.6 5.8	100.0 50.0	71.3 23.6	122.8 55.3	81.300 130.800	5.400 8.400	0.900 1.500
135		5.8 5.8	50.0 50.0	23.6	55.3 55.3	86.600	3.400	0.800
137		5.2	100.0	46.6	110.3	57.600	2.200	0.300
138	22	5.2	100.0	46.6	110.3	60.300	3.600	0.500
139	22	7.1	70.0	266.4	275.4	85.200	4.400	1.100

NO	SITE	м	D (KM	R _e I) (KM)	r (KM)	A _{max} (cm/sec ²)	V _{max} (cm/sec	D _{max} c) (cm)
140	22	7.1	70.0	266.4	275.4	62.600	3.600	0.800
141	22	7.2	50.0	256.7	261.5	67.000	3.000	1.600
142	22	7.2	50.0	256.7	261.5	54.500	3.200	1.400
143 144	22 22	4.9 4.9	60.0 60.0	33.9 33.9	68.9 68.9	259.500 176.500	6.000 3.000	0.500 0.700
145	22	6.9	10.0	113.7	114.1	62.100	4.300	1.400
146	22	6.9	10.0	113.7	114.1	46.200	3.300	0.900
147	22	7.0	0.0	69.8	69.8	140.900	4.400	1.100
148	22	7.0	0.0	69.8	69.8	88.200	3.300	1.100
149	23	4.5	0.0	11.4	11.4	97.900	2.800	0.500
150	23	4.5	0.0	11.4	11.4	102.300	5.200	0.800
151 152	23 23	4.5 4.5	0.0 0.0	10.3 10.3	10.3 10.3	76.400 76.400	3.300	0.900 0.700
152	23	4.5 4.3	10.0	7.7	12.6	115.800	3.400 4.200	0.500
154	23	4.3	10.0	7.7	12.6	197.000	3.300	0.300
155	24	5.0	0.0	5.5	5.5	96.200	6.100	1.100
156	24	5.0	0.0	5.5	5.5	138.300	6.600	2.000
157	24	5.9	60.0	46.3	75.8	63.000	4.300	0.700
158	24	5.9	60.0	46.3	75.8	59.500	4.000	0.900
159	24	5.8	60.0	41.6	73.0	81.300	3.600	0.700
160 161	24 24	5.8 4.1	60.0 0.0	41.6 8.9	73.0 5.4	45.700 90.900	3.300	0.600
162	24 24	4.1	0.0	8.9 8.9	5.4 5.4	73.700	1.100 1.600	0.200 0.700
163	10	5.6	40.0	45.9	60.9	107.300	4.960	3.300
164	10	5.6	40.0	45.9	60.9	92.400	2.960	1.350
165	10	6.7	50.0	115.0	125.4	25.900	2.910	2.020
166	10	7.4	40.0	180.5	184.9	102.100	4.890	5.150
167	19	6.1	60.0	39.8	72.0	108.400	9.460	5.270
168 169	19 19	6.1 6.3	60.0 40.0	39.8 81.2	72.0 90.5	133.900 35.100	13.770	6.440 1.940
170	19	6.3 6.3	40.0	81.2	90.5 90.5	36.700	3.800 3.860	2.250
171	19	5.8	50.0	65.1	82.1	49.100	7.060	2.840
172	19	5.8	50.0	65.1	82.1	29.000	5.220	2.220
173	19	6.1	40.0	57.6	70.1	112.500	11.120	7.160
174	19	6.1	40.0	57.6	70.1	111.600	10.300	6.690
175	19	5.4	60.0	44.9	74.9	134.200	7.210	2.350
176 177	19 18	5.4 5.2	60.0 40.0	44.9 12.8	74.9	85.800	6.030	1.500 4.040
178	18	5.2 5.2	40.0	12.8	42.0 42.0	103.900 109.700	10.800 7.710	4.040 5.540
179	18	6.1	60.0	35.3	69.6	101.800	16.930	6.810
180	18	6.1	60.0	35.3	69.6	85.800	11.110	5.260
181	18	6.3	40.0	80.3	89.7	42.700	3.760	1.890
182	18	6.3	40.0	80.3	89.7	49.100	4.170	1.900
183	18	6.1	40.0	52.9	66.3	120.800	13.150	5.340
1,84 185	18 3	6.1 7.1	40.0	52.9 95.0	66.3 161.0	155.600	16.640	6.270
185	3	7.1	130.0 130.0	95.0 95.0	161.0	92.800 121.500	6.300 6.300	2.500 1.900
			100.0	00.0			0.000	1.000

NO	SITE	м	D	Re	r	A _{max}	V _{max}	D _{max}
187	3	5.5	(KM 70.0) (KM) 17.0	(KM) 72.0	(cm/sec ²) 84.400	(cm/sec) 2.600) (cm) 0.800
188	3	5.5	70.0	17.0	72.0	63.300	2.200	1.100
189	3	7.1	40.0	64.0	75.5	164.000	8.500	3.300
190	3	7.1	40.0	64.0	75.5	259.600	13.400	1.400
191 192	7 7	7.1 7.1	40.0 40.0	137.0 137.0	142.7 142.7	172.600 183.100	11.100	2.100
192	16	7.1 5.9	40.0 40.0	48.0	62.5	49.900	17.400 4.900	2.400 1.300
194	16	5.9	40.0	48.0	62.5	82.800	9.500	2.200
195	16	6.1	60.0	50.0	64.0	48.900	4.900	1.600
196	16	6.1	60.0	50.0	64.0	116.300	11.200	1.800
197	16	6.3	40.0	90.0	98.5	75.500	3.900	0.700
198	16	6.3	40.0	90.0	98.5	54.300	4.000	1.100
199 200	16	6.1 6.1	40.0 40.0	55.0 55.0	234.9 234.9	72.500 92.100	7.200 5.700	1.100 0.900
200	16 6	7.1	40.0 40.0	102.0	109.6	89.800	7.700	3.200
202	6	7.1	40.0	102.0	109.6	93.200	8.700	4.800
203	6	6.5	130.0	22.4	169.7	101.600	3.900	1.000
204	6	6.5	130.0	22.4	169.7	98.500	3.700	1.600
205	15	4.8	50.0	20.2	53.9	67.500	2.600	0.600
206	15	4.8	50.0	20.2	53.9	51.600	2.100	0.400
207 208	15 15	5.4 5.4	80.0 80.0	41.0 41.0	72.7 72.7	64.900 41.900	3.900 3.000	0.600 0.900
209	15	6.1	80.0	83.7	109.1	40.100	6.600	1.300
210	15	6.1	80.0	83.7	109.1	24.200	3.500	0.700
211	14	5.9	70.0	45.1	83.3	54.800	4.100	0.700
212	14	5.9	70.0	45.1	83.3	76.600	3.800	0.600
213	14	5.4	90.0	41.7	99.2	49.600	2.700	0.600
214	14	5.4	90.0	41.7	99.2	83.300	3.300	0.800
215 216	22 22	6.1 6.1	80.0 80.0	49.0 49.0	85.4 85.4	65.500 109.500	3.800 5.300	0.800 0.700
217	24	4.5	0.0	3.4	3.4	127.200	3.100	0.400
218	24	4.5	0.0	3.4	3.4	148.500	5.700	0.500
219	25	7.5	30.0	103.0	107.3	201.300	14.400	3.240
220	25	7.5	30.0	103.0	107.3	213.200	19.560	3.990
221	25	6.6	40.0	18.7	44.2	699.100	33.020	9.300
222 223	25 25、	6.6 5.3	40.0 40.0	18.7 18.3	44.2 44.0	810.600 213.800	24.650 8.250	4.340 1.930
224	25	5.3	40.0	18.3	44.0	298.600	12.930	2.310
225	25	6.7	10.0	135.4	135.8	141.000	2.890	0.310
226	25	6.7	10.0	135.4	135.8	126.800	2.350	0.630
227	25	4.7	10.0	137.5	137.9	125.500	3.790	0.750
228	25	4.7	10.0	137.5	137.9	78.100	2.470	0.500
229	28 28	6.1	70.0	41.0	81.2	140.000	12.900	1.260
230 231	28 28	6.1 4.9	70.0 78.0	41.0 28.0	81.2 82.9	102.000 29.500	10.500 2.470	1. 48 0 0.640
232	28	4.9	78.0	28.0	82.9	33.100	1.330	0.420
233	28	6.1	78.0	46.0	90.6	73.500	4.610	0.840

NO SITE	М	D	R _e) (KM)	Г (КАА)	A _{max}	V _{max}	D _{max}
234 28	6.1	(KM 78.0	46 .0	(KM) 90.6	(cm/sec ²) 68.700	(cm/sec 6.160	0.870
235 28	6.7	58.0	73.0	93.2	122.900	14.940	2.160
236 28 237 28	6.7 6.0	58.0 96.0	73.0 11.0	93.2 96.6	109.200 190.200	10.530 7.480	1.660 0.8 4 0
238 28	6.0	96.0 96.0	11.0	96.6	65.100	3.410	0.650
239 27	6.4	52.0	84.0	98.8	107.800	2.910	0.720
240 27	6.4	52.0	84.0	98.8	78.000	2.430	0.460
241 27	6.7	35.0	127.0	131.7	123.800	3.610	0.590
242 27	6.7	35.0	127.0	131.7	145.300	5.370	1.000
243 27 244 27	6.6 6.6	44.0 44.0	99.0 99.0	108.3 108.3	355.100 220.900	9.120 11.910	2.520 1.390
245 27	6.5	47.0	102.0	112.3	130.700	3.280	0.530
246 27	6.5	47.0	102.0	112.3	117.100	3.720	0.990
247 29	5.4	90.0	29.0	94.6	94.600	3.460	1.020
248 29	5.4	90.0	29.0	94.6	90.000	2.270	0.630
249 29	4.9	60.0 60.0	25.0 25.0	65.0	57.300	1.910	0.500
250 29 251 29	4.9 5.8	54.0	25.0 25.0	65.0 59.5	66.400 152.200	1.360 5.250	0.310 0.950
252 29	5.8	54.0	25.0	59.5	164.600	7.030	1.320
253 29	5.2	49.0	31.0	58.0	84.300	2.080	0.860
254 29	5.2	49.0	31.0	58.0	112.200	2.980	0.510
255 29	5.7	53.0	30.0	60.9	52.000	1.810	0.710
256 29 257 13	5.7 6.7	53.0 35.0	30.0 168.0	60.9 171.6	90.900 66.200	3.250 4.090	0.430 0.970
258 13	6.7	35.0	168.0	171.6	75.300	8.440	0.870
259 13	6.6	44.0	134.0	141.0	76.900	5.010	0.830
260 13	6.6	44.0	134.0	141.0	95. 90 0	9.460	1.110
261 6	7.1	130.0	50.0	139.3	167.000	15.200	3.150
262 6 263 6	7.1	130.0	50.0	139.3	169.000	10.400	2.870
263 6 264 6	7.0 7.0	119.0 119.0	108.0 108.0	160.7 160.7	76.500 66.400	5.130 4.790	1.950 0.910
265 30	7.4	40.0	249.0	252.2	27.900	3.650	2.410
266 30	7.4	40.0	249.0	252.2	26.200	4.030	1.500
267 30	7.7	14.0	107.0	107.9	219.100	27.940	11.550
268 30	7.7	14.0	107.0	107.9	235.300	24.480	10.720
269 30 270 30	6.1 6.1	23.0 23.0	113.0 113.0	115.3 115.3	63.600 49.400	5.200 3.910	1.500 1.150
271 30	6.0	14.0	115.0	115.8	75.600	2.060	0.430
272 30	6.0	14.0	115.0	115.8	43.300	2.530	0.540
273 31	7.4	40.0	345.0	347.3	31.900	4.150	1.280
274 31	7.4	40.0	345.0	347.3	30.000	3.570	1.630
275 31 276 31	6.1 6.1	70.0 70.0	18.0 18.0	72.3 72.3	99.700 161.000	11.800 12.400	1.540 2.210
277 31	6.0	70.0	38.0	72.3 81.4	30.400	4.640	1.120
278 31	6.0	72.0	38.0	81.4	55.900	8.520	1.730
279 31	6.1	78 .0	30.0	83.6	72.900	4.880	0.720
280 31	6.1	78.0	30.0	83.6	75.000	8.010	1.250

NO	SITE	М	D	Re	r	A _{max}	V _{max}	D _{max}
	• •		(KM		(KM)	(cm/sec ²)	(cm/sec)	(cm)
281	31	6.7	58.0	44.0	72.8	300.700	13.250	2.340
282		6.7	58.0	44.0	72.8	262.700	19.400	3.910
283		7.4	40.0	319.0	321.5	22.100	6.120	2.650
284		7.4	40.0	319.0	321.5 156.6	24.600 121.500	5.820 21.810	2.600 7.680
285 286		7.7 7.7	14.0 14.0	156.0 156.0	156.6	168.000		11.680
280		7.1	6.0	160.0	160.1	65.500	7.540	2.790
288		7.1	6.0	160.0	160.1	73.700	9.550	3.390
289		7.7	14.0	204.0	204.5	22.600	5.480	3.590
290		7.7	14.0	204.0	204.5	24.000	5.260	3.970
291	32	5.0	56.0	10.0	56.9	84.700	1.460	0.050
292		5.0	56.0	10.0	56.9	94.500	1.500	0.100
293		5.0	43.0	28.0	51.3	181.100	3.280	0.130
294		5.0	43.0	28.0	51.3	170.500	3.590	0.070
295		5.8	42.0	51.0	66.1	104.100	2.590	0.290
296	32	5.8	42.0	51.0	66.1	113.300	2.980	0.340
297		4.6	61.0	74.0	95.9	31.100	0.780	0.030
298		4.6	61.0	74.0	95.9	53.100	1.000	0.060
299		5.2	48.0	48.0	67.9	67.300	1.240	0.080
300		5.2	48.0	48.0	67.9	59.300	1.060	0.120
301		4.8	66.0	14.0	67.5	75.200	1.460	0.060
302		4.8	66.0	14.0	67.5	82.900	1.760	0.090
303		6.6 6.6	44.0 44.0	151.0 151.0	157.3 157.3	52.600 39.100	1.610 2.3 4 0	0.460 0.600
304 305		0.0 4.9	44.0 61.5	38.0	72.3	61.400	1.100	0.050
306		4.9	61.5	38.0	72.3	36.500	0.570	0.040
307		4.5	49.0	11.0	50.2	132.400	2.740	0.150
308		4.7	49.0	11.0	50.2	107.800	2.670	0.170
309		6.8	116.0	125.0	170.5	75.200	6.940	1.150
310		6.8	116.0	125.0	170.5	61.500	4.830	0.970
311	26	7.1	33.0	47.0	57.4	248.800	19.740	2.470
312		7.1	33.0	47.0	57.4	358.200	29.050	4.850
313		7.4	40.0	281.0	283.8	53.400	4.190	1.830
314		7.4	40.0	281.0	283.8	39.100	4.500	1.370
315		7.0	30.0	118.0	121.8	87.600	5.000	2.000
316		7.0	30.0	118.0	121.8	106.500	4.820	2.080
317		5.6	43.0	76.0	87.3	114.200	4.100	0.720
318		5.6	43.0	76.0	87.3	51.600 117.700	1.710	0.710
319 320		5.0 5.0	43.0 43.0	61.0 61.0	74.6 74.6	47.700	4.090 1.450	0.740 0.420
320		5.0 6.1	44.0	64.0	74.0	125.800	4.870	0.420
321		6.1	44.0 44.0	64.0 64.0	77.7	61.300	3.500	0.430
323		5.8	42.0	68.0	79.9	105.700	3.790	0.530
324		5.8	42.0	68.0	79.9	66.700	3.740	0.700
325		6.7	58.0	65.0	87.1	133.100	8.600	3.180
326		6.7	58.0	65.0	87.1	134.600	7.010	1.960
327		5.6	54.0	71.0	89.2	69.200	3.870	0.370

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M=Magnitude, D=Depth, Re=Epicentral distance, r=Hypocentral distance A_{max} =Peak acceleration, V_{max} =Peak velocity, D_{max} =Peak displacement

NO	SITE	М	D	Re	r	Amax	V _{max}	D _{max}
			(KM)		(KM)	(cm/sec ²)	(cm/sec)	(cm)
32	8 33	5.6	54.0	71.0	89.2	56.500	2.230 ⁽	0.340
329	9 33	4.9	42.0	12.0	43.7	87.600	2.530	0.410
330	0 33	4.9	42.0	12.0	43.7	34.900	1.100	0.280
33	1 11	6.6	72.0	27.0	76.9	231.600	9.140	2.210
333	2 11	6.6	72.0	27.0	76.9	230.500	9.510	1.980
333	3 11	7.1	0.0	95.0	95.0	183.100	7.040	1.760
334		7.1	0.0	95.0	95.0	137.400	5.560	1.710
33	57	7.7	14.0	270.0	270.4	39.900	2.550	1.240
33(7.7	14.0	270.0	270.4	30.000	2.420	1.660
33		7.1	6.0	201.0	201.1	70.900	4.300	0.830
331		7.0	119.0	164.4	202.6	56.200	3.080	0.880
339		7.0	119.0	164.0	202.6	127.800	4.590	0.750
34(7.7	100.0	401.0	413.3	47.300	2.280	1.090
34		7.7	100.0	401.0	413.3	64.200	2.390	1.280
342		6.1	60.0	85.0	104.0	41.800	2.450	0.630
343		6.1	60.0	85.0	104.0	62.500	3.170	0.580
344		5.7	84.0	42.0	93.9	61.500	2.960	1.370
34!		5.7	84.0	42.0	93.9	96.800	3.610	1.930
34(7.0	119.0	42.0	126.2	150.200	8.250	3.120
343		7.0	119.0	42.0	126.2	197.900	5.910	1.680
348		6.4	92.8	48.0	104.5	81.700	2.930	0.660
349		6.4	92.8	48.0	104.5	116.900	3.370	0.870
35(6.0	78.0	106.0	131.6	54.800	2.570	0.770
35		6.0	78.0	106.0	131.6	74.200	3.220	1.000
35		7.4	40.0	374.0	376.1	26.000	3.350	0.640
35:		7.4	40.0	374.0	376.1	18.300	1.930	0.740
354		6.0	22.0	60.0	63.9	110.300	6.720	0.760
35		6.0	22.0	60.0	63.9	68.300	3.920	0.470
35		6.7	58.0	77.0	96.4	115.100	8.000	2.120
35	7 21	6.7	58.0	77.0	96.4	74.900	8.700	2.440

A-9

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APPENDIX B

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i	Xį	N(x _i)	$\frac{\sqrt{N(x_{j+1})}}{\frac{1}{i}\sum_{j=1}^{i}\sqrt{N(x_j)}}$
1	1.5	24	0.456
2	2.5	5	0.627
3	3.7	5	0.784
4	5.0	6	0.830
5	7.0	6	1.402
6	8.0	16	1.469
7	9.0	20	1.192
8	10.0	15	1.344
9	12.0	20	1.357
10	13.0	22	1.186
11	14.0	18	1.347
12	15.5	24	1.362
13	17.5	26	1.246
14	18.5	23	1.574
_15	20.0	38	1.650
16	21.0	45	1.671
17	23.0	50	

Based on Fig.9-3, we obtain the following values.

For example for i=10

$$\frac{\sqrt{N(x_{j+1})}}{\frac{1}{1}\sum_{j=1}^{1}\sqrt{N(x_j)}} = 1.186$$

Since the maximum value of the fourth column is for i=16, that is, M=16,

$$x_{M} = 21.0$$

$$\frac{1}{M} \sum_{j=1}^{M} \sqrt{N(x_{j})} = 4.230$$

$$Ma \times \left[\frac{\sqrt{N(x_{j+1})}}{\frac{1}{i} \sum_{j=1}^{i} \sqrt{N(x_{j})}}\right] = 1.671$$

and finally

$$C_{amp} = Ma \times \left[\frac{\sqrt{N(x_{j+1})}}{\frac{1}{i} \sum_{j=1}^{i} \sqrt{N(x_{j})}}\right] \times \frac{x_{M}}{\frac{1}{M} \sum_{j=1}^{M} \sqrt{N(x_{j})}}$$
$$= 1.671 \times \frac{21.0}{4.230}$$
$$= 8.30$$

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scaling strong-motion peaks in terms of seismic so conditions. Peak acceleration, peak velocity and similar fashion because they are interrelated. How velocity which is a key ground motion parameter f studies. With the help of seismic source theories, using strong motions obtained in Japan. In the da- used in the selection of the model itself and the m magnitude M and hypocentral distance r are selled dummy variables are introduced to identify the am local site conditions. The resulting semi-empirical velocity and displacement are then compared with three earthquakes in the U.S. and Mexico. This semi-empirical model is superior to existing models amplification factors for acceleration, velocity and by the model are found to be period-dependent an addition, two methods for predicting the amplificat Finally, a simplified method for estimating maximur of the proposed semi-empirical expression for the 17. Document Analysis a. Descriptors	beak displacement vever emphasis or lifeline earth the semi-empir rivation, statist odel parameters ted as independ plification factor expressions for strong-motion d comparison sugge for strong groud displacement per d related to loc ion factor at a n soil strain is	nt are analyzed in a is placed on the peak quake engineering ical model is derived ical considerations are . Earthquake ent variables and the r due to individual r the peak acceleration, ata observed during gests that the proposed und motion peaks. The taks obtained empirically al soil conditions. In new site are proposed.
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